



## Fixed Point Results for Weakly $\alpha$ -Admissible Pairs

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**Abstract.** In this paper, we introduce the concepts of weakly and partially weakly  $\alpha$ -admissible pair of mappings and obtain certain coincidence and fixed point theorems for classes of weakly  $\alpha$ -admissible contractive mappings in a b-metric space. As an application, we derive some new coincidence and common fixed point results in a b-metric space endowed with a binary relation or a graph. Moreover, an example is provided here to illustrate the usability of the obtained results.

### 1. Introduction and Preliminaries

The concept of a weakly contractive mapping ( $d(fx, fy) \leq d(x, y) - \varphi(d(x, y))$  for all  $x, y \in X$ , where  $\varphi$  is an altering distance function) was introduced by Alber and Guerre-Delabre [5] in the setup of Hilbert spaces. Rhoades [34] proved that every weakly contractive mapping defined on a complete metric space has a unique fixed point.

Self mappings  $f$  and  $g$  on a metric space  $X$  are called generalized weakly contractions, if there exists a lower semicontinuous function  $\varphi : [0, \infty) \rightarrow [0, \infty)$  with  $\varphi(0) = 0$  and  $\varphi(t) > 0$  for all  $t > 0$  such that

$$d(fx, gy) \leq N(x, y) - \varphi(N(x, y)),$$

where,

$$N(x, y) = \max\{d(x, y), d(x, fx), d(y, gy), \frac{1}{2}[d(x, gy) + d(y, fx)]\},$$

for all  $x, y \in X$  ([33]).

**Theorem 1.1.** [33] Let  $(X, d)$  be a complete metric space. If  $f, g : X \rightarrow X$  are generalized weakly contractions, then there exists a unique point  $u \in X$  such that  $u = fu = gu$ .

For more results in this direction we refer the reader to [8, 15].

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Many researchers have obtained fixed point results in complete metric spaces endowed with a partial order (See, e.g., [1, 3, 9, 11, 23–27, 30]).

In 2012, Samet et al. [32] introduced the concepts of  $\alpha$ - $\psi$ -contractive and  $\alpha$ -admissible mappings and established various fixed point theorems for such mappings defined on complete metric spaces. Afterwards, Salimi et al. [31] and Hussain et al. [16–18] modified the notion of  $\alpha$ -admissible mapping and established certain (common) fixed point theorems.

**Definition 1.2.** [32] Let  $T$  be a self-mapping on  $X$  and let  $\alpha : X \times X \rightarrow [0, +\infty)$  be a function. We say that  $T$  is an  $\alpha$ -admissible mapping if

$$x, y \in X, \quad \alpha(x, y) \geq 1 \quad \implies \quad \alpha(Tx, Ty) \geq 1.$$

**Definition 1.3.** Let  $f$  and  $g$  be two self-maps on a set  $X$  and let  $\alpha : X \times X \rightarrow [0, \infty)$  be a function. A pair  $(f, g)$  is said to be,

- (i) weakly  $\alpha$ -admissible if  $\alpha(fx, gfx) \geq 1$  and  $\alpha(gx, fgx) \geq 1$  for all  $x \in X$ ,
- (ii) partially weakly  $\alpha$ -admissible if  $\alpha(fx, gfx) \geq 1$  for all  $x \in X$ .

Let  $X$  be a non-empty set and  $f : X \rightarrow X$  be a given mapping. For every  $x \in X$ , let  $f^{-1}(x) = \{u \in X : fu = x\}$ .

**Definition 1.4.** Let  $X$  be a set,  $f, g, h : X \rightarrow X$  are mappings such that  $fX \cup gX \subseteq hX$  and let  $\alpha : X \times X \rightarrow [0, \infty)$  be a function. The ordered pair  $(f, g)$  is said to be:

- (a) weakly  $\alpha$ -admissible with respect to  $h$  if and only if for all  $x \in X$ ,  $\alpha(fx, gy) \geq 1$  for all  $y \in h^{-1}(fx)$  and  $\alpha(gx, fy) \geq 1$  for all  $y \in h^{-1}(gx)$ ,
- (b) partially weakly  $\alpha$ -admissible with respect to  $h$  if  $\alpha(fx, gy) \geq 1$  for all  $y \in h^{-1}(fx)$ .

**Remark 1.5.** In the above definition: (i) if  $g = f$ , we say that  $f$  is weakly  $\alpha$ -admissible (partially weakly  $\alpha$ -admissible) with respect to  $h$ , (ii) if  $h = I_X$  (the identity mapping on  $X$ ), then the above definition reduces to the concepts of weakly  $\alpha$ -admissible (partially weakly  $\alpha$ -admissible) mapping.

**Definition 1.6.** Let  $f$  and  $g$  be two self-maps on a set  $X$  and let  $\alpha : X \times X \rightarrow [0, \infty)$  be a function. The weakly  $\alpha$ -admissible (partially weakly  $\alpha$ -admissible) pair  $(f, g)$  is said to be triangular weakly  $\alpha$ -admissible (triangular partially weakly  $\alpha$ -admissible) if  $\alpha(x, z) \geq 1$  and  $\alpha(z, y) \geq 1$  implies  $\alpha(x, y) \geq 1$  for all  $x, y, z \in X$ .

**Definition 1.7.** Let  $X$  be a set,  $f, g, h : X \rightarrow X$  are mappings such that  $fX \cup gX \subseteq hX$  and let  $\alpha : X \times X \rightarrow [0, \infty)$  be a function. The ordered pair  $(f, g)$  is said to be triangular weakly  $\alpha$ -admissible (triangular partially weakly  $\alpha$ -admissible) with respect to  $h$  if it is weakly  $\alpha$ -admissible (partially weakly  $\alpha$ -admissible) with respect to  $h$  and if  $\alpha(x, z) \geq 1$  and  $\alpha(z, y) \geq 1$  imply  $\alpha(x, y) \geq 1$  for all  $x, y, z \in X$ .

**Example 1.8.** Let  $X = [0, \infty)$ ,

$$f(x) = \begin{cases} x, & 0 \leq x \leq 1, \\ 1, & 1 \leq x \leq \infty, \end{cases} \quad g(x) = \begin{cases} \sqrt{x}, & 0 \leq x \leq 1, \\ 1, & 1 \leq x \leq \infty, \end{cases}$$

$$R(x) = \begin{cases} x^3, & 0 \leq x \leq 1, \\ 1, & 1 \leq x \leq \infty, \end{cases} \quad S(x) = \begin{cases} x^2, & 0 \leq x \leq 1, \\ 1, & 1 \leq x \leq \infty, \end{cases}$$

and let  $\alpha(x, y) = e^{y-x}$  for all  $x, y \in [0, \infty)$ . Then  $(f, g)$  is triangular weakly  $\alpha$ -admissible with respect to  $R$ , and,  $(g, f)$  is a triangular weakly  $\alpha$ -admissible pair with respect to  $S$ . Indeed, if  $\begin{cases} \alpha(x, z) \geq 1 \\ \alpha(z, y) \geq 1 \end{cases}$ , then  $\begin{cases} x - z \leq 0, \\ z - y \leq 0, \end{cases}$  that is,  $x - y \leq 0$  and so,  $\alpha(x, y) = e^{y-x} \geq 1$ .

To prove that  $(f, g)$  is partially weakly  $\alpha$ -admissible with respect to  $R$ , let  $x, y \in X$  be such that  $y \in R^{-1}fx$ , that is,  $Ry = fx$ . So, we have  $x = y^3$  and hence,  $y = \sqrt[3]{x}$ . As  $gy = g(\sqrt[3]{x}) = \sqrt{\sqrt[3]{x}} = \sqrt[3]{x} \geq x = fx$ , for all  $x \in [0, 1]$ , therefore,  $\alpha(fx, gy) = e^{gy-fx} = e^{\sqrt[3]{x}-x} \geq 1$ . Hence,  $(f, g)$  is partially weakly  $\alpha$ -admissible with respect to  $R$ .

Also,  $(g, f)$  is partially weakly  $\alpha$ -admissible with respect to  $S$ . Indeed, let  $x, y \in X$  be such that  $y \in S^{-1}gx$ , that is,  $Sy = gx$ . Hence, we have  $y^2 = \sqrt{x}$ . As  $fy = f(\sqrt{x}) = \sqrt[3]{x} \geq \sqrt{x} = gx$ , for all  $x \in [0, 1]$ , therefore,  $\alpha(gx, fy) = e^{fy-gx} = e^{\sqrt[3]{x}-\sqrt{x}} \geq 1$ . Hence,  $(g, f)$  is partially weakly  $\alpha$ -admissible with respect to  $S$ .

Recently, Hussain et al. [16] introduced the concept of  $\alpha$ -completeness for a metric space which is weaker than the concept of completeness.

**Definition 1.9.** [16] Let  $(X, d)$  be a metric space and let  $\alpha : X \times X \rightarrow [0, \infty)$  be a mapping. The metric space  $X$  is said to be  $\alpha$ -complete if and only if every Cauchy sequence  $\{x_n\}$  in  $X$  with  $\alpha(x_n, x_{n+1}) \geq 1$  for all  $n \in \mathbb{N}$ , converges in  $X$ .

**Remark 1.10.** If  $X$  is a complete metric space, then  $X$  is also an  $\alpha$ -complete metric space. But, the converse is not true (see, Example 1.17 of [37]).

**Definition 1.11.** [16] Let  $(X, d)$  be a metric space and let  $\alpha : X \times X \rightarrow [0, \infty)$  and  $T : X \rightarrow X$  be mappings. We say that  $T$  is an  $\alpha$ -continuous mapping on  $(X, d)$ , if, for given  $x \in X$  and sequence  $\{x_n\}$ ,

$$x_n \rightarrow x \text{ as } n \rightarrow \infty \text{ and } \alpha(x_n, x_{n+1}) \geq 1 \text{ for all } n \in \mathbb{N} \implies Tx_n \rightarrow Tx.$$

**Example 1.12.** [16] Let  $X = [0, \infty)$  and  $d(x, y) = |x - y|$  be a metric on  $X$ . Assume that  $T : X \rightarrow X$  and  $\alpha : X \times X \rightarrow [0, +\infty)$  be defined by

$$Tx = \begin{cases} x^5, & \text{if } x \in [0, 1], \\ \sin \pi x + 2, & \text{if } (1, \infty), \end{cases} \quad \text{and} \quad \alpha(x, y) = \begin{cases} x^2 + y^2 + 1, & \text{if } x, y \in [0, 1], \\ 0, & \text{otherwise.} \end{cases}$$

Clearly,  $T$  is not continuous, but  $T$  is  $\alpha$ -continuous on  $(X, d)$ .

Motivated by [19] we introduce the following concept.

**Definition 1.13.** [19] Let  $(X, d)$  be a metric space and  $f, g : X \rightarrow X$ . The pair  $(f, g)$  is said to be  $\alpha$ -compatible if  $\lim_{n \rightarrow \infty} d(fgx_n, gfx_n) = 0$ , whenever  $\{x_n\}$  is a sequence in  $X$  such that  $\alpha(x_n, x_{n+1}) \geq 1$  for all  $n \in \mathbb{N}$  and  $\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n = t$  for some  $t \in X$ .

**Remark 1.14.** If  $(f, g)$  is a compatible pair, then  $(f, g)$  is also an  $\alpha$ -compatible pair. But, the converse is not true. The following example which is adapted from example 1.2 of [7] illustrates this fact.

**Example 1.15.** Let  $X = [1, \infty)$  and  $d(x, y) = |x - y|$ . Assume that  $f, g : X \rightarrow X$  and  $\alpha : X \times X \rightarrow [0, +\infty)$  be defined by

$$fx = \begin{cases} 2, & \text{if } x \in [1, 2], \\ 6, & \text{if } (2, \infty), \end{cases} \quad gx = \begin{cases} 6 - 2x, & \text{if } x \in [1, 2], \\ 7, & \text{if } (2, \infty), \end{cases} \quad \text{and} \quad \alpha(x, y) = \begin{cases} 1, & \text{if } x = y = 2, \\ 0, & \text{otherwise.} \end{cases}$$

Clearly,  $(f, g)$  is not compatible, but it is an  $\alpha$ -compatible pair. Indeed, let  $\{x_n\}$  be a sequence such that  $\alpha(x_n, x_{n+1}) \geq 1$  for all  $n \in \mathbb{N}$  and  $\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n$ . Then,  $x_n = 2$  for all  $n \in \mathbb{N}$ . Then  $\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n = 2$  and  $\lim_{n \rightarrow \infty} gfx_n = \lim_{n \rightarrow \infty} fgx_n = 2$ . Again, if we consider the sequence  $y_n = 2 - \frac{1}{n}$ , then  $\lim_{n \rightarrow \infty} fy_n = \lim_{n \rightarrow \infty} gy_n = 2$ ,  $\lim_{n \rightarrow \infty} gfy_n = 2$  and  $\lim_{n \rightarrow \infty} fgy_n = 6$ . Thus,  $f$  and  $g$  are  $\alpha$ -compatible but not compatible.

**Definition 1.16.** [20] Let  $f, g : X \rightarrow X$  be given self-mappings on  $X$ . The pair  $(f, g)$  is said to be weakly compatible if  $f$  and  $g$  commute at their coincidence points (i.e.,  $fgx = gfx$ , whenever  $fx = gx$ ).

**Definition 1.17.** Let  $(X, d)$  be a metric space and let  $\alpha : X \times X \rightarrow [0, \infty)$  be a function. We say that  $(X, d)$  is  $\alpha$ -regular if the following conditions hold:

$$\text{if } x_n \rightarrow x, \text{ where } \alpha(x_n, x_{n+1}) \geq 1 \text{ for all } n \in \mathbb{N}, \text{ then } \alpha(x_n, x) \geq 1 \text{ for all } n \in \mathbb{N}.$$

The concept of  $b$ -metric space was introduced by Czerwik in [10]. Since then, several papers have been published on the fixed point theory of various classes of operators in  $b$ -metric spaces (see, also, [4, 6, 12–14, 21, 28, 29]).

**Definition 1.18.** [10] Let  $X$  be a (nonempty) set and  $s \geq 1$  be a given real number. A function  $d : X \times X \rightarrow \mathbb{R}^+$  is a  $b$ -metric iff, for all  $x, y, z \in X$ , the following conditions are satisfied:

- $b_1.$   $d(x, y) = 0$  iff  $x = y$ ,
- $b_2.$   $d(x, y) = d(y, x)$ ,
- $b_3.$   $d(x, z) \leq s[d(x, y) + d(y, z)]$ .

The pair  $(X, d)$  is called a  $b$ -metric space.

**Definition 1.19.** Let  $X$  be a nonempty set. Then  $(X, d, \leq)$  is called a partially ordered  $b$ -metric space if and only if  $d$  is a  $b$ -metric on a partially ordered set  $(X, \leq)$ .

Recently, Hussain et al. have presented an example of a  $b$ -metric which is not continuous (see, example 3 in [12]).

Since in general a  $b$ -metric is not continuous, we need the following simple lemma about the  $b$ -convergent sequences in the proof of our main result.

**Lemma 1.20.** [2] Let  $(X, d)$  be a  $b$ -metric space with  $s \geq 1$  and suppose that  $\{x_n\}$  and  $\{y_n\}$  are  $b$ -convergent to  $x$  and  $y$ , respectively. Then we have,

$$\frac{1}{s^2}d(x, y) \leq \liminf_{n \rightarrow \infty} d(x_n, y_n) \leq \limsup_{n \rightarrow \infty} d(x_n, y_n) \leq s^2d(x, y).$$

In particular, if  $x = y$ , then we have  $\lim_{n \rightarrow \infty} d(x_n, y_n) = 0$ . Moreover, for each  $z \in X$ , we have,

$$\frac{1}{s}d(x, z) \leq \liminf_{n \rightarrow \infty} d(x_n, z) \leq \limsup_{n \rightarrow \infty} d(x_n, z) \leq sd(x, z).$$

Motivated by the works in [11, 17, 18, 23, 24], we prove some coincidence point results for weakly  $\alpha$ -admissible  $(\psi, \varphi)$ -contractive mappings in  $b$ -metric and partially ordered  $b$ -metric spaces. Our results extend and generalize certain recent results in the literature and provide main results in [23, 24] as corollaries.

## 2. Main Results

Let  $(X, d)$  be a  $b$ -metric space and let  $f, g, R, S : X \rightarrow X$  be four self mappings. Throughout this paper, unless otherwise stated, for all  $x, y \in X$ , let

$$M(x, y) \in \left\{ d(Sx, Ry), \frac{d(Sx, fx) + d(Ry, gy)}{2s}, \frac{d(Sx, gy) + d(Ry, fx)}{2s} \right\}$$

and

$$N(x, y) = \min\{d(Sx, fx), d(Sx, gy), d(Ry, fx), d(Ry, gy)\}.$$

Throughout this paper,  $\psi, \varphi : [0, \infty) \rightarrow [0, \infty)$  are altering distance functions and  $\phi : [0, \infty) \rightarrow [0, \infty)$  is a bounded function. Recall that a function  $\varphi : [0, \infty) \rightarrow [0, \infty)$  is called an altering distance function, if  $\varphi$  is continuous and nondecreasing and  $\varphi(t) = 0$  if and only if  $t = 0$  [22].

**Theorem 2.1.** Let  $(X, d)$  be an  $\alpha$ -complete  $b$ -metric space and let  $f, g, R, S : X \rightarrow X$  be four mappings such that  $f(X) \subseteq R(X)$ ,  $g(X) \subseteq S(X)$  and  $\alpha : X \times X \rightarrow [0, \infty)$  be a function. Suppose that for every  $x, y \in X$  with  $\alpha(Sx, Ry) \geq 1$ ,

$$\psi(sd(fx, gy)) \leq \psi(M(x, y)) - \varphi(M(x, y)) + \phi(N(x, y))N(x, y). \quad (1)$$

Assume that  $f, g, R$  and  $S$  are  $\alpha$ -continuous, the pairs  $(f, S)$  and  $(g, R)$  are  $\alpha$ -compatible and the pairs  $(f, g)$  and  $(g, f)$  are triangular partially weakly  $\alpha$ -admissible with respect to  $R$  and  $S$ , respectively. Then, the pairs  $(f, S)$  and  $(g, R)$  have a coincidence point  $z$  in  $X$ . Moreover, if  $\alpha(Sz, Rz) \geq 1$ , then  $z$  is a coincidence point of  $f, g, R$  and  $S$ .

*Proof.* Let  $x_0$  be an arbitrary point of  $X$ . Choose  $x_1 \in X$  such that  $fx_0 = Rx_1$  and  $x_2 \in X$  such that  $gx_1 = Sx_2$ . Continuing this way, construct a sequence  $\{z_n\}$  defined by:

$$z_{2n+1} = Rx_{2n+1} = fx_{2n}$$

and

$$z_{2n+2} = Sx_{2n+2} = gx_{2n+1}$$

for all  $n \geq 0$ .

As  $x_1 \in R^{-1}(fx_0)$  and  $x_2 \in S^{-1}(gx_1)$  and the pairs  $(f, g)$  and  $(g, f)$  are partially weakly  $\alpha$ -admissible with respect to  $R$  and  $S$ , respectively, we have,

$$\alpha(Rx_1 = fx_0, gx_1 = Sx_2) \geq 1$$

and

$$\alpha(gx_1 = Sx_2, fx_2 = Rx_3) \geq 1.$$

Repeating this process, we obtain  $\alpha(Rx_{2n+1}, Sx_{2n+2}) = \alpha(z_{2n+1}, z_{2n+2}) \geq 1$  for all  $n \geq 0$ .

We will complete the proof in three steps.

Step I. We will prove that  $\lim_{k \rightarrow \infty} d(z_k, z_{k+1}) = 0$ .

Define  $d_k = d(z_k, z_{k+1})$ . Suppose that  $d_{k_0} = 0$  for some  $k_0$ . Then,  $z_{k_0} = z_{k_0+1}$ . If  $k_0 = 2n$ , then  $z_{2n} = z_{2n+1}$  gives  $z_{2n+1} = z_{2n+2}$ . Indeed,

$$\begin{aligned} \psi(sd(z_{2n+1}, z_{2n+2})) &= \psi(sd(fx_{2n}, gx_{2n+1})) \\ &\leq \psi(M(x_{2n}, x_{2n+1})) - \varphi(M(x_{2n}, x_{2n+1})) + \phi(N(x_{2n}, x_{2n+1}))N(x_{2n}, x_{2n+1}), \end{aligned} \quad (2)$$

where,

$$\begin{aligned} &M(x_{2n}, x_{2n+1}) \\ &\in \left\{ d(Sx_{2n}, Rx_{2n+1}), \frac{d(Sx_{2n}, fx_{2n}) + d(Rx_{2n+1}, gx_{2n+1})}{2s}, \frac{d(Sx_{2n}, gx_{2n+1}) + d(Rx_{2n+1}, fx_{2n})}{2s} \right\} \\ &= \left\{ d(z_{2n}, z_{2n+1}), \frac{d(z_{2n}, z_{2n+1}) + d(z_{2n+1}, z_{2n+2})}{2s}, \frac{d(z_{2n}, z_{2n+2}) + d(z_{2n+1}, z_{2n+1})}{2s} \right\} \\ &= \left\{ 0, \frac{d(z_{2n+1}, z_{2n+2})}{2s}, \frac{d(z_{2n}, z_{2n+2})}{2s} \right\} \end{aligned}$$

and

$$\begin{aligned} &N(x_{2n}, x_{2n+1}) \\ &= \min\{d(Sx_{2n}, fx_{2n}), d(Sx_{2n}, gx_{2n+1}), d(Rx_{2n+1}, fx_{2n}), d(Rx_{2n+1}, gx_{2n+1})\} \\ &= \min\{d(z_{2n}, z_{2n+1}), d(z_{2n}, z_{2n+2}), d(z_{2n+1}, z_{2n+1}), d(z_{2n+1}, z_{2n+2})\} = 0. \end{aligned}$$

If  $M(x_{2n}, x_{2n+1}) = \frac{d(z_{2n+1}, z_{2n+2})}{2s}$ , then (2) will be,

$$\begin{aligned} \psi(sd(z_{2n+1}, z_{2n+2})) &\leq \psi\left(\frac{d(z_{2n+1}, z_{2n+2})}{2s}\right) - \varphi\left(\frac{d(z_{2n+1}, z_{2n+2})}{2s}\right) + \phi(0) \times 0 \\ &\leq \psi\left(\frac{d(z_{2n+1}, z_{2n+2})}{2s}\right) - \varphi\left(\frac{d(z_{2n+1}, z_{2n+2})}{2s}\right), \end{aligned} \quad (3)$$

which implies that  $\varphi\left(\frac{d(z_{2n+1}, z_{2n+2})}{2s}\right) = 0$ , that is,  $z_{2n} = z_{2n+1} = z_{2n+2}$ . Similarly, if  $k_0 = 2n + 1$ , then  $z_{2n+1} = z_{2n+2}$  gives  $z_{2n+2} = z_{2n+3}$ . Continuing this process, we find that  $z_k$  is a constant sequence for  $k \geq k_0$ . Hence,  $\lim_{k \rightarrow \infty} d(z_k, z_{k+1}) = 0$  holds true.

Now, suppose that

$$d_k = d(z_k, z_{k+1}) > 0 \quad (4)$$

for each  $k$ . We claim that

$$d(z_{k+1}, z_{k+2}) \leq d(z_k, z_{k+1}) \quad (5)$$

for each  $k = 1, 2, 3, \dots$ .

Let  $k = 2n$  and for an  $n \geq 0$ ,  $d(z_{2n+1}, z_{2n+2}) \geq d(z_{2n}, z_{2n+1}) > 0$ . Then, as  $\alpha(Sx_{2n}, Rx_{2n+1}) \geq 1$ , using (1) we obtain that

$$\begin{aligned} \psi(sd(z_{2n+1}, z_{2n+2})) &= \psi(sd(fx_{2n}, gx_{2n+1})) \\ &\leq \psi(M(x_{2n}, x_{2n+1})) - \varphi(M(x_{2n}, x_{2n+1})) + \phi(N(x_{2n}, x_{2n+1}))N(x_{2n}, x_{2n+1}), \end{aligned} \quad (6)$$

where,

$$\begin{aligned} M(x_{2n}, x_{2n+1}) & \\ \in \{ &d(Sx_{2n}, Rx_{2n+1}), \frac{d(Sx_{2n}, fx_{2n}) + d(Rx_{2n+1}, gx_{2n+1})}{2s}, \frac{d(Sx_{2n}, gx_{2n+1}) + d(Rx_{2n+1}, fx_{2n})}{2s} \} \\ = \{ &d(z_{2n}, z_{2n+1}), \frac{d(z_{2n}, z_{2n+1}) + d(z_{2n+1}, z_{2n+2})}{2s}, \frac{d(z_{2n}, z_{2n+2}) + d(z_{2n+1}, z_{2n+1})}{2s} \} \end{aligned}$$

and

$$\begin{aligned} N(x_{2n}, x_{2n+1}) & \\ = \min \{ &d(Sx_{2n}, fx_{2n}), d(Sx_{2n}, gx_{2n+1}), d(Rx_{2n+1}, fx_{2n}), d(Rx_{2n+1}, gx_{2n+1}) \} \\ = \min \{ &d(z_{2n}, z_{2n+1}), d(z_{2n}, z_{2n+2}), d(z_{2n+1}, z_{2n+1}), d(z_{2n+1}, z_{2n+2}) \} = 0. \end{aligned}$$

If

$$M(x_{2n}, x_{2n+1}) = \frac{d(z_{2n}, z_{2n+1}) + d(z_{2n+1}, z_{2n+2})}{2s} \leq \frac{d(z_{2n+1}, z_{2n+2})}{s},$$

as  $d(z_{2n+1}, z_{2n+2}) \geq d(z_{2n}, z_{2n+1})$ , then from (6), we have,

$$\begin{aligned} &\psi(sd(z_{2n+1}, z_{2n+2})) \\ &\leq \psi\left(\frac{d(z_{2n}, z_{2n+1}) + d(z_{2n+1}, z_{2n+2})}{2s}\right) - \varphi\left(\frac{d(z_{2n}, z_{2n+1}) + d(z_{2n+1}, z_{2n+2})}{2s}\right) \\ &\leq \psi(sd(z_{2n+1}, z_{2n+2})) - \varphi\left(\frac{d(z_{2n}, z_{2n+1}) + d(z_{2n+1}, z_{2n+2})}{2s}\right), \end{aligned} \quad (7)$$

which implies that,  $\varphi\left(\frac{d(z_{2n}, z_{2n+1}) + d(z_{2n+1}, z_{2n+2})}{2s}\right) \leq 0$ , this is possible only if

$$\frac{d(z_{2n}, z_{2n+1}) + d(z_{2n+1}, z_{2n+2})}{2s} = 0,$$

that is,  $d(z_{2n}, z_{2n+1}) = 0$ , a contradiction to (4). Hence,  $d(z_{2n+1}, z_{2n+2}) \leq d(z_{2n}, z_{2n+1})$  for all  $n \geq 0$ .

Therefore, (5) is proved for  $k = 2n$ .

Similarly, it can be shown that,

$$d(z_{2n+2}, z_{2n+3}) \leq d(z_{2n+1}, z_{2n+2}) \quad (8)$$

for all  $n \geq 0$ .

Analogously, for other values of  $M(x_{2n}, x_{2n+1})$ , we can see that  $\{d(z_k, z_{k+1})\}$  is a nondecreasing sequence of nonnegative real numbers. Therefore, there is an  $r \geq 0$  such that

$$\lim_{k \rightarrow \infty} d(z_k, z_{k+1}) = r. \quad (9)$$

We know that,

$$M(x_{2n}, x_{2n+1}) \in \left\{ d(z_{2n}, z_{2n+1}), \frac{d(z_{2n}, z_{2n+1}) + d(z_{2n+1}, z_{2n+2})}{2s}, \frac{d(z_{2n}, z_{2n+2}) + d(z_{2n+1}, z_{2n+1})}{2s} \right\}.$$

Substituting the values of  $M(x_{2n}, x_{2n+1})$  in (6) and then taking the limit as  $n \rightarrow \infty$  in (6), we obtain that  $r = 0$ . For instance, let

$$M(x_{2n}, x_{2n+1}) = \frac{d(z_{2n}, z_{2n+2}) + d(z_{2n+1}, z_{2n+1})}{2s}.$$

So, from (6) we have

$$\begin{aligned} & \psi\left(s d(z_{2n+1}, z_{2n+2})\right) \\ & \leq \psi\left(\frac{d(z_{2n}, z_{2n+2}) + d(z_{2n+1}, z_{2n+1})}{2s}\right) - \varphi\left(\frac{d(z_{2n}, z_{2n+2}) + d(z_{2n+1}, z_{2n+1})}{2s}\right) \\ & = \psi\left(\frac{d(z_{2n}, z_{2n+2})}{2s}\right) - \varphi\left(\frac{d(z_{2n}, z_{2n+2})}{2s}\right) \\ & \leq \psi\left(\frac{d(z_{2n}, z_{2n+1}) + d(z_{2n+1}, z_{2n+2})}{2}\right) - \varphi\left(\frac{d(z_{2n}, z_{2n+2})}{2s}\right). \end{aligned} \quad (10)$$

Letting  $n \rightarrow \infty$  in (10), using (9) and the continuity of  $\psi$  and  $\varphi$ , we have,

$$\varphi\left(\lim_{n \rightarrow \infty} \frac{d(z_{2n}, z_{2n+2})}{2s}\right) = 0.$$

Hence,  $\lim_{n \rightarrow \infty} \frac{d(z_{2n}, z_{2n+2})}{2s} = 0$ , from our assumptions about  $\varphi$ .

Now, taking into account (10) and letting  $n \rightarrow \infty$ , we find that  $\psi(sr) \leq \psi(0) - \varphi(0)$ . Hence,  $r = 0$ . In general, for the other values of  $M(x_{2n}, x_{2n+1})$  we can show that,

$$r = \lim_{k \rightarrow \infty} d(z_k, z_{k+1}) = \lim_{n \rightarrow \infty} d(z_{2n}, z_{2n+1}) = 0. \quad (11)$$

*Step II.* We will show that  $\{z_n\}$  is a  $b$ -Cauchy sequence in  $X$ . Assume on contrary that, there exists  $\varepsilon > 0$  for which we can find subsequences  $\{z_{2m(k)}\}$  and  $\{z_{2n(k)}\}$  of  $\{z_{2n}\}$  such that  $n(k) > m(k) \geq k$  and

$$d(z_{2m(k)}, z_{2n(k)}) \geq \varepsilon \quad (12)$$

and  $n(k)$  is the smallest number such that the above condition holds; i.e.,

$$d(z_{2m(k)}, z_{2n(k)-1}) < \varepsilon. \quad (13)$$

From triangle inequality and (12) and (13), we have,

$$\varepsilon \leq d(z_{2m(k)}, z_{2n(k)}) \leq s[d(z_{2m(k)}, z_{2n(k)-1}) + d(z_{2n(k)-1}, z_{2n(k)})]. \quad (14)$$

Taking the limit as  $k \rightarrow \infty$  in (14), from (11) we obtain that,

$$\varepsilon \leq \limsup_{k \rightarrow \infty} d(z_{2m(k)}, z_{2n(k)}) \leq s\varepsilon. \quad (15)$$

Using triangle inequality again we have,

$$d(z_{2m(k)}, z_{2n(k)}) \leq s[d(z_{2m(k)}, z_{2m(k)+1}) + d(z_{2m(k)+1}, z_{2n(k)})].$$

Making  $k \rightarrow \infty$  in the above inequality, we have,

$$\frac{\varepsilon}{s} \leq \limsup_{k \rightarrow \infty} d(z_{2m(k)+1}, z_{2n(k)}). \quad (16)$$

Finally,

$$d(z_{2m(k)+1}, z_{2n(k)-1}) \leq s[d(z_{2m(k)+1}, z_{2m(k)}) + d(z_{2m(k)}, z_{2n(k)-1})].$$

Letting  $k \rightarrow \infty$ , and using (15), we have,

$$\limsup_{k \rightarrow \infty} d(z_{2m(k)+1}, z_{2n(k)-1}) \leq s\varepsilon. \quad (17)$$

We know that  $2n(k) - 1 \geq 2m(k)$  and  $\alpha(Sx_{2n+2}, Rx_{2n+1}) = \alpha(gx_{2n+1}, fx_{2n}) \geq 1$  for all  $n \in \mathbb{N}$ . On the other hand, the pairs  $(f, g)$  and  $(g, f)$  are triangular partially weakly  $\alpha$ -admissible with respect to  $R$  and  $S$ , respectively. So,  $\alpha(Rx_{2n(k)-1}, Sx_{2n(k)-2}) \geq 1$  and  $\alpha(Sx_{2n(k)-2}, Rx_{2n(k)-3}) \geq 1$  implies  $\alpha(Rx_{2n(k)-1}, Rx_{2n(k)-3}) \geq 1$ . Also,  $\alpha(Rx_{2n(k)-1}, Rx_{2n(k)-3}) \geq 1$  and  $\alpha(Rx_{2n(k)-3}, Sx_{2n(k)-4}) \geq 1$  implies that  $\alpha(Rx_{2n(k)-1}, Sx_{2n(k)-4}) \geq 1$ . Continuing this manner, we obtain that  $\alpha(Rx_{2n(k)-1}, Sx_{2m(k)}) \geq 1$ . Now we can apply (1), to obtain that

$$\begin{aligned} \psi(sd(z_{2m(k)+1}, z_{2n(k)})) &= \psi(sd(fx_{2m(k)}, gx_{2n(k)-1})) \\ &\leq \psi(M(x_{2m(k)}, x_{2n(k)-1})) - \varphi(M(x_{2m(k)}, x_{2n(k)-1})) \\ &\quad + \phi(N(x_{2m(k)}, x_{2n(k)-1}))N(x_{2m(k)}, x_{2n(k)-1}), \end{aligned} \quad (18)$$

where,

$$\begin{aligned} M(x_{2m(k)}, x_{2n(k)-1}) &\in \{d(Sx_{2m(k)}, Rx_{2n(k)-1}), \frac{d(Sx_{2m(k)}, fx_{2m(k)}) + d(Rx_{2n(k)-1}, gx_{2n(k)-1})}{2s}, \\ &\frac{d(Sx_{2m(k)}, gx_{2n(k)-1}) + d(Rx_{2n(k)-1}, fx_{2m(k)})}{2s}\} \\ &= \{d(z_{2m(k)}, z_{2n(k)-1}), \frac{d(z_{2m(k)}, z_{2m(k)+1}) + d(z_{2n(k)-1}, z_{2n(k)})}{2s}, \\ &\frac{d(z_{2m(k)}, z_{2n(k)}) + d(z_{2n(k)-1}, z_{2m(k)+1})}{2s}\} \end{aligned}$$

and

$$\begin{aligned} N(x_{2m(k)}, x_{2n(k)-1}) &= \min\{d(Sx_{2m(k)}, fx_{2m(k)}), d(Sx_{2m(k)}, gx_{2n(k)-1}), d(Rx_{2n(k)-1}, fx_{2m(k)}), d(Rx_{2n(k)-1}, gx_{2n(k)-1})\} \\ &= \min\{d(z_{2m(k)}, z_{2m(k)+1}), d(z_{2m(k)}, z_{2n(k)}), d(z_{2n(k)-1}, z_{2m(k)+1}), d(z_{2n(k)-1}, z_{2n(k)})\}. \end{aligned}$$

From (11), clearly  $N(x_{2m(k)}, x_{2n(k)-1}) \rightarrow 0$ .

If

$$M(x_{2m(k)}, x_{2n(k)-1}) = \frac{d(z_{2m(k)}, z_{2m(k)+1}) + d(z_{2n(k)-1}, z_{2n(k)})}{2s},$$

then from (11), we get that  $\lim_{k \rightarrow \infty} M(x_{2m(k)}, x_{2n(k)-1}) = 0$ . Hence, according to (18) we have,  $\lim_{k \rightarrow \infty} d(z_{2m(k)+1}, z_{2n(k)}) = 0$ , which contradicts (16). If

$$M(x_{2m(k)}, x_{2n(k)-1}) = \frac{d(z_{2m(k)}, z_{2n(k)}) + d(z_{2n(k)-1}, z_{2m(k)+1})}{2s},$$

then from (15) and (17), we get that,

$$\limsup_{k \rightarrow \infty} M(x_{2m(k)}, x_{2n(k)-1}) \leq \frac{s\varepsilon + s\varepsilon}{2s} = \varepsilon.$$

Taking the limit as  $k \rightarrow \infty$  in (18), we have,

$$\begin{aligned} \psi(\varepsilon) &= \psi\left(s \cdot \frac{\varepsilon}{s}\right) \\ &\leq \psi\left(s \limsup_{k \rightarrow \infty} d(z_{m(k)+1}, z_{n(k)})\right) \\ &\leq \psi\left(\limsup_{k \rightarrow \infty} M(x_{2m(k)}, x_{2n(k)-1})\right) - \varphi\left(\liminf_{k \rightarrow \infty} M(x_{2m(k)}, x_{2n(k)-1})\right) \\ &\quad + \limsup_{k \rightarrow \infty} \phi(N(x_{2m(k)}, x_{2n(k)-1}))N(x_{2m(k)}, x_{2n(k)-1}) \\ &\leq \psi(\varepsilon) - \varphi\left(\liminf_{k \rightarrow \infty} M(x_{2m(k)}, x_{2n(k)-1})\right) + 0, \end{aligned} \quad (19)$$

which implies that  $\varphi(\liminf_{k \rightarrow \infty} M(x_{2m(k)}, x_{2n(k)-1})) \leq 0$ . Hence,  $\liminf_{k \rightarrow \infty} d(x_{2m(k)}, x_{2n(k)}) = 0$ , a contradiction to (15).

If

$$M(x_{2m(k)}, x_{2n(k)-1}) = d(x_{2m(k)}, x_{2n(k)-1}),$$

then from (13), by taking the limit as  $k \rightarrow \infty$  in (18), we have,

$$\begin{aligned} \psi(\varepsilon) &= \psi\left(s \cdot \frac{\varepsilon}{s}\right) \\ &\leq \psi\left(s \limsup_{k \rightarrow \infty} d(z_{m(k)+1}, z_{n(k)})\right) \\ &\leq \psi\left(\limsup_{k \rightarrow \infty} d(z_{2m(k)}, z_{2n(k)-1})\right) - \varphi\left(\liminf_{k \rightarrow \infty} d(z_{2m(k)}, z_{2n(k)-1})\right) \\ &\leq \psi(\varepsilon) - \varphi\left(\liminf_{k \rightarrow \infty} d(z_{2m(k)}, z_{2n(k)-1})\right), \end{aligned} \quad (20)$$

which implies that  $\varphi(\liminf_{k \rightarrow \infty} d(z_{2m(k)}, z_{2n(k)-1})) \leq 0$ . Hence,  $\liminf_{k \rightarrow \infty} d(z_{2m(k)}, z_{2n(k)-1}) = 0$ . Therefore, from triangular inequality we can conclude that  $\liminf_{k \rightarrow \infty} d(z_{2m(k)}, z_{2n(k)}) = 0$  which contradicts (15).

Hence  $\{z_n\}$  is a  $b$ -Cauchy sequence.

*Step III.* We will show that  $f, g, R$  and  $S$  have a coincidence point.

Since  $\{z_n\}$  is a  $b$ -Cauchy sequence in the  $\alpha$ -complete  $b$ -metric space  $X$  and  $\alpha(z_k, z_{k+1}) \geq 1$ , then there exists  $z \in X$  such that,

$$\lim_{n \rightarrow \infty} d(z_{2n+1}, z) = \lim_{n \rightarrow \infty} d(Rx_{2n+1}, z) = \lim_{n \rightarrow \infty} d(fx_{2n}, z) = 0 \quad (21)$$

and

$$\lim_{n \rightarrow \infty} d(z_{2n}, z) = \lim_{n \rightarrow \infty} d(Sx_{2n}, z) = \lim_{n \rightarrow \infty} d(gx_{2n-1}, z) = 0. \quad (22)$$

Hence,

$$Sx_{2n} \rightarrow z \text{ and } fx_{2n} \rightarrow z, \text{ as } n \rightarrow \infty. \quad (23)$$

As  $(f, S)$  is  $\alpha$ -compatible and  $\alpha(z_{2n}, z_{2n+2}) \geq 1$ , so,

$$\lim_{n \rightarrow \infty} d(Sfx_{2n}, fSx_{2n}) = 0. \quad (24)$$

Moreover, from  $\lim_{n \rightarrow \infty} d(fx_{2n}, z) = 0$ ,  $\lim_{n \rightarrow \infty} d(Sx_{2n}, z) = 0$  and the  $\alpha$ -continuity of  $S$  and  $f$ , we obtain that

$$\lim_{n \rightarrow \infty} d(Sfx_{2n}, Sz) = 0 = \lim_{n \rightarrow \infty} d(fSx_{2n}, fz). \quad (25)$$

By the triangle inequality, we have,

$$\begin{aligned} d(Sz, fz) &\leq s[d(Sz, Sfx_{2n}) + d(Sfx_{2n}, fz)] \\ &\leq sd(Sz, Sfx_{2n}) + s^2[d(Sfx_{2n}, fSx_{2n}) + d(fSx_{2n}, fz)]. \end{aligned} \quad (26)$$

Taking the limit as  $n \rightarrow \infty$  in (26), we obtain that

$$d(Sz, fz) \leq 0,$$

which yields that  $fz = Sz$ , that is,  $z$  is a coincidence point of  $f$  and  $S$ .

Similarly, it can be proved that  $gz = Rz$ . Now, let  $\alpha(Rz, Sz) \geq 1$ . From (1) we have,

$$\psi(sd(fz, gz)) \leq \psi(M(z, z)) - \varphi(M(z, z)) + \phi(N(z, z))N(z, z), \quad (27)$$

where,

$$\begin{aligned} M(z, z) &\in \left\{ d(Sz, Rz), \frac{d(Sz, fz) + d(Rz, gz)}{2s}, \frac{d(Sz, gz) + d(Rz, fz)}{2s} \right\} \\ &= \left\{ d(fz, gz), 0, \frac{d(fz, gz)}{s} \right\} \end{aligned}$$

and

$$N(z, z) = \min\{d(Sz, fz), d(Sz, gz), d(Rz, fz), d(Rz, gz)\} = 0.$$

In all three cases, (27) yields that  $fz = gz = Sz = Rz$ .  $\square$

In the following theorem, we omit the assumption of  $\alpha$ -continuity of  $f$ ,  $g$ ,  $R$  and  $S$  and replace the  $\alpha$ -compatibility of the pairs  $(f, S)$  and  $(g, R)$  by weak compatibility of the pairs.

**Theorem 2.2.** Let  $(X, d)$  be an  $\alpha$ -regular  $\alpha$ -complete  $b$ -metric space,  $f, g, R, S : X \rightarrow X$  be four mappings such that  $f(X) \subseteq R(X)$  and  $g(X) \subseteq S(X)$  and  $RX$  and  $SX$  are  $b$ -closed subsets of  $X$ . Suppose that

$$\psi(sd(fx, gy)) \leq \psi(M(x, y)) - \varphi(M(x, y)) + \phi(N(x, y))N(x, y), \quad (28)$$

for all  $x$  and  $y$  with  $\alpha(Sx, Ry) \geq 1$ . Then, the pairs  $(f, S)$  and  $(g, R)$  have a coincidence point  $z$  in  $X$  provided that the pairs  $(f, S)$  and  $(g, R)$  are weakly compatible and the pairs  $(f, g)$  and  $(g, f)$  are triangular partially weakly  $\alpha$ -admissible with respect to  $R$  and  $S$ , respectively. Moreover, if  $\alpha(Sz, Rz) \geq 1$ , then  $z \in X$  is a coincidence point of  $f$ ,  $g$ ,  $R$  and  $S$ .

*Proof.* Following the proof of Theorem 2.1, there exists  $z \in X$  such that:

$$\lim_{k \rightarrow \infty} d(z_k, z) = 0. \quad (29)$$

Since  $R(X)$  is  $b$ -closed and  $\{z_{2n+1}\} \subseteq R(X)$ , therefore  $z \in R(X)$ . Hence, there exists  $u \in X$  such that  $z = Ru$  and

$$\lim_{n \rightarrow \infty} d(z_{2n+1}, Ru) = \lim_{n \rightarrow \infty} d(Rx_{2n+1}, Ru) = 0. \quad (30)$$

Similarly, there exists  $v \in X$  such that  $z = Ru = Sv$  and

$$\lim_{n \rightarrow \infty} d(z_{2n}, Sv) = \lim_{n \rightarrow \infty} d(Sx_{2n}, Sv) = 0. \quad (31)$$

Now, we prove that  $v$  is a coincidence point of  $f$  and  $S$ .

Since  $Rx_{2n+1} \rightarrow z = Sv$ , as  $n \rightarrow \infty$ , from  $\alpha$ -regularity of  $X$ ,  $\alpha(Rx_{2n+1}, Sv) \geq 1$ . Therefore, from (28), we have

$$\psi(sd(fv, gx_{2n+1})) \leq \psi(M(v, x_{2n+1})) - \varphi(M(v, x_{2n+1})) + \phi(N(v, x_{2n+1}))N(v, x_{2n+1}), \quad (32)$$

where,

$$\begin{aligned} M(v, x_{2n+1}) &\in \{d(Sv, Rx_{2n+1}), \frac{d(Sv, fv) + d(Rx_{2n+1}, gx_{2n+1})}{2s}, \frac{d(Sv, gx_{2n+1}) + d(Rx_{2n+1}, fv)}{2s}\} \\ &= \{d(z, z_{2n+1}), \frac{d(z, fv) + d(z_{2n+1}, z_{2n})}{2s}, \frac{d(z, z_{2n}) + d(z_{2n+1}, fv)}{2s}\} \end{aligned}$$

and

$$\begin{aligned} N(v, x_{2n+1}) &= \min\{d(Sv, fv), d(Sv, gx_{2n+1}), d(Rx_{2n+1}, fv), d(Rx_{2n+1}, gx_{2n+1})\} \\ &= \min\{d(z, fv), d(z, z_{2n}), d(z_{2n+1}, fv), d(z_{2n+1}, z_{2n})\} \rightarrow 0. \end{aligned}$$

From Lemma 1.20,

$$\frac{d(z, fv)}{2s^2} \leq \liminf_n M(v, x_{2n+1}) \leq \limsup_n M(v, x_{2n+1}) \leq \frac{d(z, fv)}{2}.$$

Taking the limit as  $n \rightarrow \infty$  in (32), using Lemma 1.20 and the continuity of  $\psi$  and  $\phi$ , we can obtain that  $fv = z = Sv$ .

As  $f$  and  $S$  are weakly compatible, we have  $fz = fSv = Sfv = Sz$ . Thus,  $z$  is a coincidence point of  $f$  and  $S$ .

Similarly, it can be shown that  $z$  is a coincidence point of the pair  $(g, R)$ . The rest of the proof follows from similar arguments as in Theorem 2.1.  $\square$

Taking  $S = R$  in Theorem 2.1, we obtain the following result.

**Corollary 2.3.** *Let  $(X, d)$  be an  $\alpha$ -complete  $b$ -metric space and let  $f, g, R : X \rightarrow X$  be three mappings such that  $f(X) \cup g(X) \subseteq R(X)$  and  $R$  is  $\alpha$ -continuous. Suppose that for every  $x, y \in X$  with  $\alpha(Rx, Ry) \geq 1$ , we have,*

$$\psi(sd(fx, gy)) \leq \psi(M(x, y)) - \phi(M(x, y)) + \phi(N(x, y))N(x, y), \quad (33)$$

where,

$$M(x, y) \in \{d(Rx, Ry), \frac{d(Rx, fx) + d(Ry, gy)}{2s}, \frac{d(Rx, gy) + d(Ry, fx)}{2s}\}$$

and

$$N(x, y) = \min\{d(Rx, fx), d(Rx, gy), d(Ry, fx), d(Ry, gy)\}.$$

Then,  $f, g$  and  $R$  have a coincidence point in  $X$  provided that the pair  $(f, g)$  is triangular weakly  $\alpha$ -admissible with respect to  $R$  and either,

- the pair  $(f, R)$  is  $\alpha$ -compatible and  $f$  is  $\alpha$ -continuous, or
- the pair  $(g, R)$  is  $\alpha$ -compatible and  $g$  is  $\alpha$ -continuous.

Taking  $R = S$  and  $f = g$  in Theorem 2.1, we obtain the following coincidence point result:

**Corollary 2.4.** *Let  $(X, d)$  be an  $\alpha$ -complete  $b$ -metric space and let  $f, R : X \rightarrow X$  be two mappings such that  $f(X) \subseteq R(X)$ . Suppose that for every  $x, y \in X$  with  $\alpha(Rx, Ry) \geq 1$ , we have,*

$$\psi(sd(fx, fy)) \leq \psi(M(x, y)) - \phi(M(x, y)) + \phi(N(x, y))N(x, y), \quad (34)$$

where,

$$M(x, y) \in \{d(Rx, Ry), \frac{d(Rx, fx) + d(Ry, fy)}{2s}, \frac{d(Rx, fy) + d(Ry, fx)}{2s}\}$$

and

$$N(x, y) = \min\{d(Rx, fx), d(Rx, fy), d(Ry, fx), d(Ry, fy)\}.$$

Then, the pair  $(f, R)$  has a coincidence point in  $X$  provided that  $f$  and  $R$  are  $\alpha$ -continuous, the pair  $(f, R)$  is  $\alpha$ -compatible and  $f$  is triangular weakly  $\alpha$ -admissible with respect to  $R$ .

**Example 2.5.** Let  $X = [0, \infty)$ , the metric  $d$  on  $X$  be given by  $d(x, y) = |x - y|^2$ , for all  $x, y \in X$  and  $\alpha : X \times X \rightarrow [0, \infty)$  be given by  $\alpha(x, y) = e^{x-y}$ . Define self-maps  $f, g, S$  and  $R$  on  $X$  by

$$\begin{aligned} fx &= \ln(1 + x), & Rx &= e^x - 1, \\ gx &= \ln(1 + \frac{x}{2}), & Sx &= e^{2x} - 1. \end{aligned}$$

To prove that  $(f, g)$  is partially weakly  $\alpha$ -admissible with respect to  $R$ , let  $x, y \in X$  be such that  $y \in R^{-1}fx$ , that is,  $Ry = fx$ . By the definition of  $f$  and  $R$ , we have  $e^y - 1 = \ln(1 + x)$  and so,  $y = \ln(1 + \ln(1 + x))$ . Therefore,

$$fx = \ln(1 + x) \geq \ln(1 + \frac{\ln(1 + \ln(1 + x))}{2}) = \ln(1 + \frac{y}{2}) = gy.$$

Therefore,  $\alpha(fx, gy) \geq 1$ . Hence  $(f, g)$  is partially weakly  $\alpha$ -admissible with respect to  $R$ .

To prove that  $(g, f)$  is partially weakly  $\alpha$ -admissible with respect to  $S$ , let  $x, y \in X$  be such that  $y \in S^{-1}gx$ , that is,  $Sy = gx$ . Hence, we have  $e^{2y} - 1 = \ln(1 + \frac{x}{2})$  and so,  $y = \frac{\ln(1 + \ln(1 + \frac{x}{2}))}{2}$ . Therefore,

$$gx = \ln(1 + \frac{x}{2}) \geq \ln(1 + \frac{\ln(1 + \ln(1 + \frac{x}{2}))}{2}) = \ln(1 + y) = fy.$$

Therefore,  $\alpha(gx, fy) \geq 1$ .

Furthermore,  $fX = gX = SX = RX = [0, \infty)$ .

Define  $\psi, \varphi : [0, \infty) \rightarrow [0, \infty)$  as  $\psi(t) = bt$  and  $\varphi(t) = (b - 1)t$  for all  $t \in [0, \infty)$ , where  $1 < b \leq 22$ .

Using the mean value theorem, for all  $x$  and  $y$  with  $\alpha(Sx, Ry) \geq 1$  we have,

$$\begin{aligned} \psi(2d(fx, gy)) &= 2b |fx - gy|^2 \\ &= 2b \left| \ln(1 + x) - \ln(1 + \frac{y}{2}) \right|^2 \\ &\leq 2b \left| x - \frac{y}{2} \right|^2 \\ &\leq 2b \frac{|2x - y|^2}{4} \\ &\leq \frac{2b}{4} |e^{2x} - 1 - (e^y - 1)|^2 \\ &\leq |Sx - Ry|^2 \\ &= d(Sx, Ry) \\ &= \psi(d(Sx, Ry)) - \varphi(d(Sx, Ry)) + \phi(N(x, y))N(x, y). \end{aligned}$$

Thus, (1) is true for all  $x, y \in X$  and  $M(x, y) = d(Sx, Ry)$ . Therefore, all the conditions of Theorem 2.1 are satisfied. Moreover, 0 is a coincidence point of  $f, g, R$  and  $S$ .  $\square$

**Corollary 2.6.** Let  $(X, d)$  be an  $\alpha$ -regular  $b$ -metric space,  $f, g, R : X \rightarrow X$  be three mappings such that  $f(X) \subseteq R(X)$  and  $g(X) \subseteq R(X)$  and  $RX$  is a  $b$ -closed subset of  $X$ . Suppose that for all elements  $x$  and  $y$  with  $\alpha(Rx, Ry) \geq 1$ , we have,

$$\psi(sd(fx, gy)) \leq \psi(M(x, y)) - \varphi(M(x, y)) + \phi(N(x, y))N(x, y), \quad (35)$$

where

$$M(x, y) \in \{d(Rx, Ry), \frac{d(Rx, fx) + d(Ry, gy)}{2s}, \frac{d(Rx, gy) + d(Ry, fx)}{2s}\}$$

and

$$N(x, y) = \min\{d(Rx, fx), d(Rx, gy), d(Ry, fx), d(Ry, gy)\}.$$

Then, the pairs  $(f, R)$  and  $(g, R)$  have a coincidence point  $z$  in  $X$  provided that the pairs  $(f, R)$  and  $(g, R)$  are weakly compatible and the pair  $(f, g)$  is triangular weakly  $\alpha$ -admissible with respect to  $R$ . Moreover, if  $\alpha(Rz, Rz) \geq 1$ , then  $z \in X$  is a coincidence point of  $f, g$  and  $R$ .

**Corollary 2.7.** Let  $(X, d)$  be an  $\alpha$ -regular  $b$ -metric space,  $f, R : X \rightarrow X$  be two mappings such that  $f(X) \subseteq R(X)$  and  $RX$  is a  $b$ -closed subset of  $X$ . Suppose that for all elements  $x$  and  $y$  with  $\alpha(Rx, Ry) \geq 1$ , we have,

$$\psi(sd(fx, fy)) \leq \psi(M(x, y)) - \varphi(M(x, y)) + \phi(N(x, y))N(x, y), \quad (36)$$

where

$$M(x, y) \in \{d(Rx, Ry), \frac{d(Rx, fx) + d(Ry, fy)}{2s}, \frac{d(Rx, fy) + d(Ry, fx)}{2s}\}$$

and

$$N(x, y) = \min\{d(Rx, fx), d(Rx, fy), d(Ry, fx), d(Ry, fy)\}.$$

Then, the pair  $(f, R)$  have a coincidence point  $z$  in  $X$  provided that the pair  $(f, R)$  is weakly compatible and  $f$  is triangular weakly  $\alpha$ -admissible with respect to  $R$ .

Taking  $R = S = I_X$  (the identity mapping on  $X$ ) in Theorems 2.1 and 2.2, we obtain the following common fixed point result.

**Corollary 2.8.** Let  $(X, d)$  be an  $\alpha$ -complete  $b$ -metric space and let  $f, g : X \rightarrow X$  be two mappings. Suppose that for every elements  $x, y \in X$  with  $\alpha(x, y) \geq 1$ ,

$$\psi(sd(fx, gy)) \leq \psi(M(x, y)) - \varphi(M(x, y)) + \phi(N(x, y))N(x, y), \quad (37)$$

where,

$$M(x, y) \in \{d(x, y), d(x, fx), d(y, gy), \frac{d(x, gy) + d(y, fx)}{2s}\},$$

and

$$N(x, y) = \min\{d(x, fx), d(x, gy), d(y, fx), d(y, gy)\}.$$

Then, the pair  $(f, g)$  have a common fixed point  $z$  in  $X$  provided that the pair  $(f, g)$  is triangular weakly  $\alpha$ -admissible and either,

- a.  $f$  or  $g$  is  $\alpha$ -continuous, or,
- b.  $X$  is  $\alpha$ -regular.

**Remark 2.9.** 1. In all obtained results in this paper, we can replace  $M(x, y)$  by  $O(x, y)$ , where,

$$O(x, y) = \max\{d(Sx, Ry), d(Sx, fx), d(Ry, gy), \frac{d(Sx, gy) + d(Ry, fx)}{2s}\}.$$

2. In all obtained results in this paper, we can replace  $N(x, y)$  by  $P(x, y)$ , where,

$$P(x, y) = d(Rx, fx) \times d(Rx, gy) \times d(Ry, fx) \times d(Ry, gy).$$

### 3. Consequences in Partially Ordered b-Metric Spaces

In this section, we give some common fixed point results on metric spaces endowed with an arbitrary binary relation, specially a partial order relation which can be regarded as consequences of the results presented in the previous section.

In the sequel, let  $(X, d)$  be a metric space and let  $\mathcal{R}$  be a transitive binary relation over  $X$ .

**Definition 3.1.** Let  $f$  and  $g$  be two selfmaps on  $X$  and  $\mathcal{R}$  be a binary relation over  $X$ . A pair  $(f, g)$  is said to be,  
 (i) weakly  $\mathcal{R}$ -increasing if  $fx\mathcal{R}gfx$  and  $gx\mathcal{R}fgx$  for all  $x \in X$ ,  
 (ii) partially weakly  $\mathcal{R}$ -increasing if  $fx\mathcal{R}gfx$  for all  $x \in X$ .

**Definition 3.2.** Let  $\mathcal{R}$  be a binary relation over  $X$  and let  $f, g, h : X \rightarrow X$  are mappings such that  $fX \cup gX \subseteq hX$ . The ordered pair  $(f, g)$  is said to be:

(a) weakly  $\mathcal{R}$ -increasing with respect to  $h$  if and only if for all  $x \in X$ ,  $fx\mathcal{R}gy$  for all  $y \in h^{-1}(fx)$  and  $gx\mathcal{R}fy$  for all  $y \in h^{-1}(gx)$ ,  
 (b) partially weakly  $\mathcal{R}$ -increasing with respect to  $h$  if  $fx\mathcal{R}gy$  for all  $y \in h^{-1}(fx)$ .

Let  $\mathcal{R}$  be a binary relation over  $X$  and let

$$\alpha(x, y) = \begin{cases} 1, & x\mathcal{R}y, \\ 0, & \text{otherwise.} \end{cases}$$

By this assumption, we see that the above definitions are special cases from the definition of weak  $\alpha$ -admissibility and partially weak  $\alpha$ -admissibility.

**Definition 3.3.** [37] Let  $(X, d)$  be a metric space. The metric space  $X$  is said to be  $\mathcal{R}$ -complete if and only if every Cauchy sequence  $\{x_n\}$  in  $X$  with  $x_n\mathcal{R}x_{n+1}$  for all  $n \in \mathbb{N}$ , converges in  $X$ .

**Definition 3.4.** [37] Let  $(X, d)$  be a metric space and let  $T : X \rightarrow X$  be a mapping. We say that  $T$  is an  $\mathcal{R}$ -continuous mapping on  $(X, d)$ , if, for given  $x \in X$  and sequence  $\{x_n\}$  with  $x_n\mathcal{R}x_{n+1}$  for all  $n \in \mathbb{N}$ ,

$$x_n \rightarrow x \text{ as } n \rightarrow \infty \text{ for all } n \in \mathbb{N} \implies Tx_n \rightarrow Tx.$$

**Definition 3.5.** Let  $(X, d)$  be a metric space and let  $f, g : X \rightarrow X$ . The pair  $(f, g)$  is said to be  $\mathcal{R}$ -compatible if  $\lim_{n \rightarrow \infty} d(fgx_n, gfx_n) = 0$ , whenever  $\{x_n\}$  is a sequence in  $X$  such that  $x_n\mathcal{R}x_{n+1}$  for all  $n \in \mathbb{N}$  and  $\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n = t$  for some  $t \in X$ .

**Definition 3.6.** Let  $\mathcal{R}$  be a binary relation over  $X$  and let  $d$  be a metric on  $X$ . We say that  $(X, d, \mathcal{R})$  is  $\mathcal{R}$ -regular if the following condition hold:

if a sequence  $x_n \rightarrow x$  where  $x_n\mathcal{R}x_{n+1}$  for all  $n \in \mathbb{N}$ , then  $x_n\mathcal{R}x$  for all  $n \in \mathbb{N}$ .

Taking  $\mathcal{R} = \leq$  where  $\leq$  is a partial order on the non-empty set  $X$ , we have

**Corollary 3.7.** a) Theorem 2.1 of [24] is a special case of Corollary 2.3.  
 b) Theorem 2.2 of [24] is a special case of Corollary 2.6.  
 c) Corollary 2.1 of [24] is a special case of Corollary 2.8.  
 d) Corollary 2.2 of [24] is a special case of Corollary 2.8.  
 e) Theorem 2.4 of [23] is a special case of Corollary 2.4.  
 f) Theorem 2.6 of [23] is a special case of Corollary 2.7.  
 g) Corollary 2.7 of [23] is a special case of Corollary 2.3 with  $\mathcal{R} = I_X$ .

#### 4. Contractive Mappings on b-Metric Spaces Endowed with a Graph

Consistent with Jachymski [35], let  $(X, d)$  be a b-metric space and  $\Delta$  denotes the diagonal of the Cartesian product  $X \times X$ . Consider a directed graph  $G$  such that the set  $V(G)$  of its vertices coincides with  $X$ , and the set  $E(G)$  of its edges contains all loops, that is,  $E(G) \supseteq \Delta$ . We assume that  $G$  has no parallel edges, so we can identify  $G$  with the pair  $(V(G), E(G))$ . Moreover, we may treat  $G$  as a weighted graph (see [36], p. 309) by assigning to each edge the distance between its vertices. If  $x$  and  $y$  are vertices in a graph  $G$ , then a path in  $G$  from  $x$  to  $y$  of length  $N$  ( $N \in \mathbb{N}$ ) is a sequence  $\{x_i\}_{i=0}^N$  of  $N + 1$  vertices such that  $x_0 = x$ ,  $x_N = y$  and  $(x_{i-1}, x_i) \in E(G)$  for  $i = 1, \dots, N$ .

Recently, some results have appeared in the setting of metric spaces which are endowed with a graph. The first result in this direction was given by Jachymski [35].

**Definition 4.1.** Let  $f$  and  $g$  be two selfmaps on graphic b-metric space  $(X, d)$ . The pair  $(f, g)$  is said to be,

- (i) weakly  $G$ -increasing if  $(fx, gfx) \in E(G)$  and  $(gx, fgx) \in E(G)$  for all  $x \in X$ ,
- (ii) partially weakly  $G$ -increasing if  $(fx, gfx) \in E(G)$  for all  $x \in X$ .

**Definition 4.2.** Let  $(X, d)$  be a graphic b-metric space and let  $f, g, h : X \rightarrow X$  are mappings such that  $fX \cup gX \subseteq hX$ . The ordered pair  $(f, g)$  is said to be:

- (a) weakly  $G$ -increasing with respect to  $h$  if and only if for all  $x \in X$ ,  $(fx, gy) \in E(G)$  for all  $y \in h^{-1}(fx)$  and  $(gx, fy) \in E(G)$  for all  $y \in h^{-1}(gx)$ ,
- (b) partially weakly  $G$ -increasing with respect to  $h$  if  $(fx, gy) \in E(G)$  for all  $y \in h^{-1}(fx)$ .

Let  $(X, d)$  be a graphic b-metric space and let

$$\alpha(x, y) = \begin{cases} 1, & (x, y) \in E(G), \\ 0, & \text{otherwise.} \end{cases}$$

By this assumption, we see that the above definitions are special cases from the definition of weak  $\alpha$ -admissibility and partially weak  $\alpha$ -admissibility.

**Definition 4.3.** [37] Let  $(X, d)$  be a graphic metric space.  $(X, d)$  is said to be  $G$ -complete if and only if every Cauchy sequence  $\{x_n\}$  in  $X$  with  $(x_n, x_{n+1}) \in E(G)$  for all  $n \in \mathbb{N}$ , converges in  $X$ .

**Definition 4.4.** [37] Let  $(X, d)$  be a graphic metric space and let  $T : X \rightarrow X$  be a mapping. We say that  $T$  is an  $G$ -continuous mapping on  $(X, d)$ , if, for given  $x \in X$  and sequence  $\{x_n\}$  with  $(x_n, x_{n+1}) \in E(G)$  for all  $n \in \mathbb{N}$ ,

$$x_n \rightarrow x \text{ as } n \rightarrow \infty \text{ for all } n \in \mathbb{N} \implies Tx_n \rightarrow Tx.$$

**Definition 4.5.** Let  $(X, d)$  be a graphic metric space and let  $f, g : X \rightarrow X$ . The pair  $(f, g)$  is said to be  $G$ -compatible if  $\lim_{n \rightarrow \infty} d(fgx_n, gfx_n) = 0$ , whenever  $\{x_n\}$  is a sequence in  $X$  such that  $(x_n, x_{n+1}) \in E(G)$  for all  $n \in \mathbb{N}$  and  $\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n = t$  for some  $t \in X$ .

**Definition 4.6.** Let  $\mathcal{R}$  be a binary relation over  $X$  and let  $d$  be a metric on  $X$ . We say that  $(X, d, \mathcal{R})$  is  $\mathcal{R}$ -regular if the following condition hold:

if a sequence  $x_n \rightarrow x$  where  $x_n \mathcal{R} x_{n+1}$  for all  $n \in \mathbb{N}$ , then  $x_n \mathcal{R} x$  for all  $n \in \mathbb{N}$ .

**Definition 4.7.** Let  $(X, d)$  be a graphic b-metric space. We say that  $(X, d)$  is  $G$ -regular if the following condition holds:

if a sequence  $x_n \rightarrow x$  with  $(x_n, x_{n+1}) \in E(G)$ , then  $(x_n, x) \in E(G)$  for all  $n \in \mathbb{N}$ .

In the following theorems, we assume that:

for all  $(x, y) \in E(G)$  and  $(y, z) \in E(G)$ , we have  $(x, z) \in E(G)$ .

**Theorem 4.8.** Let  $(X, G, d)$  be a  $G$ -complete graphic  $b$ -metric space. Let  $f, g, R, S : X \rightarrow X$  be four mappings such that  $f(X) \subseteq R(X)$  and  $g(X) \subseteq S(X)$ . Suppose that for every  $x, y \in X$  such that  $(Sx, Ry) \in E(G)$ , we have,

$$\psi(sd(fx, gy)) \leq \psi(M(x, y)) - \varphi(M(x, y)) + \phi(N(x, y))N(x, y).$$

Let  $f, g, R$  and  $S$  are  $G$ -continuous, the pairs  $(f, S)$  and  $(g, R)$  are  $G$ -compatible and the pairs  $(f, g)$  and  $(g, f)$  are partially weakly  $G$ -increasing with respect to  $R$  and  $S$ , respectively. Then, the pairs  $(f, S)$  and  $(g, R)$  have a coincidence point  $z$  in  $X$ . Moreover, if  $(Sz, Rz) \in E(G)$ , then  $z$  is a coincidence point of  $f, g, R$  and  $S$ .

**Theorem 4.9.** Let  $(X, G, d)$  be a  $G$ -regular  $G$ -complete graphic  $b$ -metric space,  $f, g, R, S : X \rightarrow X$  be four mappings such that  $f(X) \subseteq R(X)$  and  $g(X) \subseteq S(X)$  and  $RX$  and  $SX$  are  $b$ -closed subsets of  $X$ . Suppose that

$$\psi(sd(fx, gy)) \leq \psi(M(x, y)) - \varphi(M(x, y)) + \phi(N(x, y))N(x, y),$$

for all  $x$  and  $y$  for which  $(Sx, Ry) \in E(G)$ . Then, the pairs  $(f, S)$  and  $(g, R)$  have a coincidence point  $z$  in  $X$  provided that the pairs  $(f, S)$  and  $(g, R)$  are weakly compatible and the pairs  $(f, g)$  and  $(g, f)$  are partially weakly  $G$ -increasing with respect to  $R$  and  $S$ , respectively. Moreover, if  $(Sz, Rz) \in E(G)$ , then  $z \in X$  is a coincidence point of  $f, g, R$  and  $S$ .

## 5. Conclusion

As we know, the concepts of  $\alpha$ -complete metric space,  $\alpha$ -continuity of a mapping and  $\alpha$ -compatibility of a pair of mappings are weaker than the concepts of complete metric space, continuity of a mapping and compatibility of a pair of mappings, respectively. Therefore, Theorems 2.1 and 2.2 are more general than the corresponding results in [38].

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