



Fixed Point Results for Multivalued Hardy–Rogers Contractions in b -Metric Spaces

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Abstract. The purpose of this paper is to present some fixed point results in b -metric spaces using a contractive condition of Hardy-Rogers type with respect to the functional H . The data dependence of the fixed point set, the well-posedness of the fixed point problem, as well as, the Ulam-Hyres stability are also studied.

1. Preliminaries

In 1973, Hardy and Rogers ([5]) gave a generalization of Reich fixed point theorem. Since then, many authors have been used different Hardy-Rogers contractive type conditions in order to obtain fixed point results. In what follows we shall recall, pure randomly, some of them.

In 2009, Kadelburg, Radenovic and Rasic ([6]), gave some common fixed point results in cone metric spaces. Radojevic, Paunovic and Radenovic ([7]) have obtained some coincidence point theorems in complete metric spaces. Sgroi and Vetro ([9]) have presented some results for \mathcal{F} -contractions in complete and ordered metric spaces. Finally, Roshan, Shobkolaei, Sedghi and Abbas ([8]) gave some common fixed point results in b -metric spaces.

In this paper we shall give some fixed point results for multivalued operators in b -metric spaces using a contractive condition of Hardy-Rogers type with respect to the functional H . The data dependence of the fixed point set, the well-posedness of the fixed point problem, as well as, the Ulam-Hyres stability are also studied.

Because we shall work in b -metric spaces, we'll start by presenting some notions about this kind of metric spaces.

Definition 1.1. Let X be a nonempty set and let $s \geq 1$ be a given real number. A function $d : X \times X \rightarrow \mathbb{R}_+$ is said to be a b -metric if and only if for all $x, y, z \in X$, the following conditions are satisfied:

1. $d(x, y) = 0 \iff x = y$;
2. $d(x, y) = d(y, x)$;
3. $d(x, y) \leq s[d(x, z) + d(z, y)]$.

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In this case, the pair (X, d) is called b – metric space with constant s .

Remark 1.2. The class of b -metric spaces is larger than the class of metric spaces since a b -metric space is a metric space when $s=1$.

Example 1.3. Let $X=\{0, 1, 2\}$ and $d : X \times X \rightarrow \mathbb{R}_+$ such that $d(0, 1) = d(1, 0) = d(0, 2) = d(2, 0) = 1, d(1, 2) = d(2, 1) = \alpha \geq 2, d(0, 0) = d(1, 1) = d(2, 2) = 0$. We have

$$d(x, y) \leq \frac{\alpha}{2} [d(x, z) + d(z, y)], \text{ for } x, y, z \in X.$$

Then (X, d) is a b -metric space. If $\alpha > 2$ the ordinary triangle inequality does not hold and (X, d) is not a metric space.

Example 1.4. The set $l^p(\mathbb{R}) = \left\{ (x_n) \subset \mathbb{R} \mid \lim_{n \rightarrow \infty} |x_n|^p < \infty \right\}, 0 < p < 1$, together with the functional $d : l^p(\mathbb{R}) \times l^p(\mathbb{R}) \rightarrow \mathbb{R}_+, d(x, y) = \left(\lim_{n \rightarrow \infty} |x - y|^p \right)^{1/p}$, is a b -metric space with constant $s = 2^{1/p}$.

Example 1.5. Let $X = \mathbb{R}$ and $d : X \times X \rightarrow \mathbb{R}_+, d(x, y) = |x - y|^3$. The (X, d) is a b -metric space with constant $s = 3$.

Definition 1.6. Let (X, d) be a b – metric space with constant s . Then the sequence $(x_n)_{n \in \mathbb{N}} \subset X$ is called:

1. convergent if and only if there exists $x \in X$ such that $d(x_n, x) \rightarrow 0$, as $n \rightarrow \infty$;
2. Cauchy if and only if $d(x_n, x_m) \rightarrow 0$, as $n, m \rightarrow \infty$.

Definition 1.7. Let (X, d) be a b – metric space with constant s . If Y is a nonempty subset of X , then the closure \bar{Y} of Y is the set of limits of all convergent sequences of points in Y , i.e.,

$$\bar{Y} := \{x \in X : \exists (x_n)_{n \in \mathbb{N}}, x_n \rightarrow x, \text{ as } n \rightarrow \infty\}.$$

Definition 1.8. Let (X, d) be a b – metric space with constant s . Then a subset $Y \subset X$ is called:

1. closed if and only if for each sequence $(x_n)_{n \in \mathbb{N}} \subset Y$ which converges to x , we have $x \in Y$;
2. compact if and only if for every sequence of elements of Y there exists a subsequence that converges to an element of Y ;
3. bounded if and only if $\delta(Y) := \{d(a, b) : a, b \in Y\} < \infty$.

Definition 1.9. The b – metric space (X, d) is complete if every Cauchy sequence in X converges.

Let us consider the following families of subsets of a b -metric space (X, d) :

$$\mathcal{P}(X) = \{Y \mid Y \subset X\}, P(X) := \{Y \in \mathcal{P}(X) \mid Y \neq \emptyset\}; P_b(X) := \{Y \in \mathcal{P}(X) \mid Y \text{ is bounded}\},$$

$$P_{cl}(X) := \{Y \in \mathcal{P}(X) \mid Y \text{ is closed}\}; P_{cp}(X) := \{Y \in \mathcal{P}(X) \mid Y \text{ is compact}\}$$

Throughout the paper the following functionals are used:

- **the gap functional:** $D : P(X) \times P(X) \rightarrow \mathbb{R}_+$

$$D(A, B) = \inf\{d(a, b) \mid a \in A, b \in B\}.$$

In particular, if $x_0 \in X$, then $D(x_0, B) := D(\{x_0\}, B)$.

- **the Pompeiu-Hausdorff generalized functional:** $H : P(X) \times P(X) \rightarrow \mathbb{R}_+ \cup \{+\infty\}$,

$$H(A, B) = \max\{\rho(A, B), \rho(B, A)\},$$

where $\rho : P(X) \times P(X) \rightarrow \mathbb{R}_+ \cup \{+\infty\}$ defined as

$$\rho(A, B) = \sup\{D(a, B) \mid a \in A\},$$

is called **the excess generalized functional**.

Let $T : X \rightarrow P(X)$ be a multivalued operator. A point $x \in X$ is called fixed point for T if and only if $x \in T(x)$.

The set $\text{Fix}(T) := \{x \in X \mid x \in T(x)\}$ is called the fixed point set of T , while $S\text{Fix}(T) = \{x \in X \mid \{x\} = T(x)\}$ is called the strict fixed point set of T . Notice that $S\text{Fix}(T) \subseteq \text{Fix}(T)$.

The following properties of some of the functionals defined above will be used throughout the paper (see [1], [4] for details and proofs):

Lemma 1.10. *Let (X, d) be a b -metric space with constant $s > 1$, $A, B \in P_{cl}(X)$. Then*

1. $D(x, B) \leq d(x, b)$, for any $b \in B$;
2. $D(x, B) \leq H(A, B)$, for any $x \in A$;
3. $D(x, A) \leq s[d(x, y) + D(y, A)]$, for all $x, y \in X, A \subset X$;
4. $D(x, A) = 0$ if and only if $x \in \overline{A}$;
5. For any $q > 1$, $a \in A$, there exists $b \in B$ such that $d(a, b) \leq qH(A, B)$;
6. $d(x_n, x_{n+p}) \leq sd(x_n, x_{n+1}) + s^2d(x_{n+1}, x_{n+2}) + \dots + s^{p-1}d(x_{n+p-2}, x_{n+p-1}) + s^{p-1}d(x_{n+p-1}, x_{n+p})$, for any $n \in \mathbb{N}$ and $p \in \mathbb{N}^*$.

2. Fixed Point Results

In this section we shall present our main fixed point theorem for multivalued Hardy-Rogers operators.

Theorem 2.1. *Let (X, d) be a complete b -metric space with constant $s > 1$ and $T : X \rightarrow P(X)$ a multivalued operator such that:*

- (i) *there exist $a, b, c \in \mathbb{R}_+, a + b + 2cs < \frac{s-1}{s^2}$ and $b + cs < \frac{1}{s}$ such that*

$$H(T(x), T(y)) \leq ad(x, y) + b[D(x, T(x)) + D(y, T(y))] + c[D(x, T(y)) + D(y, T(x))],$$

for all $x, y \in X$;

- (ii) *T is closed;*

In these conditions $\text{Fix}(T) \neq \emptyset$.

Proof. (i) It's easy to see that because $a + b + 2cs < \frac{s-1}{s^2}, a + b + cs < a + b + 2cs < \frac{s-1}{s^2}$ and hence,

$$s(a + b + cs) < \frac{s-1}{s}.$$

On the other hand, since $b + cs < \frac{1}{s}$, we obtain

$$\frac{1 - b - cs}{s(a + b + cs)} > 1.$$

Let $x_0 \in X$ and $1 < q < \frac{1 - b - cs}{s(a + b + cs)}$.

There exists $x_1 \in T(x_0)$ such that

$$H(T(x_0), T(x_1)) \leq ad(x_0, x_1) + b[D(x_0, T(x_0)) + D(x_1, T(x_1))] + c[D(x_0, T(x_1)) + D(x_1, T(x_0))].$$

By Lemma 1.1. we have:

$$D(x_0, T(x_0)) \leq d(x_0, x_1);$$

$$D(x_1, T(x_1)) \leq H(T(x_0), T(x_1));$$

$$D(x_1, T(x_0)) = 0;$$

$$D(x_0, T(x_1)) \leq s[d(x_0, x_1) + D(x_1, T(x_1))] \leq s[d(x_0, x_1) + H(T(x_0), T(x_1))].$$

Hence

$$H(T(x_0), T(x_1)) \leq ad(x_0, x_1) + bd(x_0, x_1) + bH(T(x_0), T(x_1)) + csd(x_0, x_1) + csH(T(x_0), T(x_1))$$

$$(1 - b - cs)H(T(x_0), T(x_1)) \leq (a + b + cs)d(x_0, x_1)$$

Since $b + cs < \frac{1}{s} < 1$ we have

$$H(T(x_0), T(x_1)) \leq \frac{a + b + cs}{1 - b - cs}d(x_0, x_1).$$

Using again Lemma 1.1., there exists $x_2 \in T(x_1)$ such that

$$d(x_1, x_2) \leq qH(T(x_0), T(x_1))$$

$$d(x_1, x_2) \leq q \frac{a + b + cs}{1 - b - cs}d(x_0, x_1).$$

Let $q \frac{a+b+cs}{1-b-cs} := \alpha < \frac{1}{s} < 1$

Hence

$$d(x_1, x_2) \leq \alpha d(x_0, x_1).$$

Continuing this process we shall obtain that there exists a sequence $(x_n)_{n \in \mathbb{N}}$, with $x_n \in T(x_{n-1})$, such that $d(x_n, x_{n+1}) \leq \alpha^n d(x_0, x_1)$ for each $n \in \mathbb{N}$.

This inequality implies that $(x_n)_{n \in \mathbb{N}}$ is a Cauchy sequence, see [3]. Hence there exists $x \in X$ such that $x_n \rightarrow x$, as $n \rightarrow \infty$.

Now, we shall prove that $x \in T(x)$.

We have:

$$\begin{aligned} D(x, T(x)) &\leq sd(x, x_{n+1}) + sD(x_{n+1}, T(x)) \\ &\leq sd(x, x_{n+1}) + sH(T(x_n), T(x)). \end{aligned}$$

$$\begin{aligned} H(T(x_n), T(x)) &\leq ad(x_n, x) + b[D(x_n, T(x_n)) + D(x, T(x))] + c[D(x, T(x_n)) + D(x_n, T(x))] \\ &\leq ad(x_n, x) + bd(x_n, x_{n+1}) + bD(x, T(x)) + cd(x_{n+1}, x) + csd(x_n, x) + csD(x, T(x)). \end{aligned}$$

Hence

$$\begin{aligned} D(x, T(x)) &\leq sd(x, x_{n+1}) + asd(x_n, x) + bsd(x_n, x_{n+1}) + bsD(x, T(x)) + \\ &\quad csd(x_{n+1}, x) + cs^2d(x_n, x) + cs^2D(x, T(x)). \end{aligned}$$

If $n \rightarrow \infty$ then we obtain $(1 - bs - cs^2)D(x, T(x)) \leq 0$.

Since $b + cs < \frac{1}{s}$ we have that $bs + cs^2 < 1$ and hence, $D(x, T(x)) = 0$. This implies that $x \in T(x)$ and hence $\text{Fix}(T) \neq \emptyset$. \square

An existence and uniqueness fixed point result for multivalued Hardy-Rogers operators is the following:

Theorem 2.2. Let (X, d) be a complete b -metric space with constant $s > 1$ and $T : X \rightarrow P(X)$ a multivalued operator such that:

(i) there exist $a, b, c \in \mathbb{R}_+$, $a + b + 2cs < \frac{s-1}{s^2}$ and $b + cs < \frac{1}{s}$ such that

$$H(T(x), T(y)) \leq ad(x, y) + b [D(x, T(x)) + D(y, T(y))] + c [D(x, T(y)) + D(y, T(x))],$$

for all $x, y \in X$;

(ii) T is closed;

If $SFix(T) \neq \emptyset$ then $SFix(T) = Fix(T) = \{x\}$.

Proof. Let $x \in SFix(T)$ and suppose that there exist $y \in Fix(T)$, $y \neq x$.

$$\begin{aligned} d(x, y) &= D(T(x), y) \leq H(T(x), T(y)) \\ &\leq ad(x, y) + b [D(x, T(x)) + D(y, T(y))] + c [D(x, T(y)) + D(y, T(x))] \\ &\leq ad(x, y) + 2cd(x, y). \end{aligned}$$

Hence $(1 - a - 2c)d(x, y) \leq 0$.

Since $a + 2c < a + b + 2cs < \frac{s-1}{s^2} < 1$, we shall obtain that $d(x, y) = 0$ which implies that $x = y$ and this is a contradiction.

In conclusion $SFix(T) = Fix(T) = \{x\}$. \square

An example illustrating our theorem is given in what follows.

Example 2.3. Let us consider the following two sets (see [2]):

$$\begin{aligned} M_1 &= \left\{ \frac{m}{n} \mid m = 0, 1, 3, 9, \dots; n = 3k + 1, k \in \mathbb{N} \right\}; \\ M_2 &= \left\{ \frac{m}{n} \mid m = 1, 3, 9, 27, \dots; n = 3k + 2, k \in \mathbb{N} \right\}. \end{aligned}$$

Let $X = M_1 \cup M_2$. Define $T : X \rightarrow \mathbb{R}_+$,

$$T(x) = \begin{cases} \{\alpha x, \beta x\}, & x \in M_1 \\ \{\beta x\}, & x \in M_2 \end{cases},$$

where $0 < \beta \leq \alpha < 1$.

Notice that T is not a Hardy-Rogers operator with respect to the metric $\hat{d}(x, y) := |x - y|$ (see [2]), but it becomes a Hardy-Rogers operator with respect to the b -metric (with constant $s = 3$) defined by $d(x, y) = |x - y|^3$.

Proof. We shall prove that there exist $a, b, c \in \mathbb{R}_+$ such that T is a Hardy-Rogers with respect to d . We shall have four cases:

(1) $x, y \in M_1$

In this case $\rho(T(x), T(y)) = |\alpha x - \alpha y|^3 = \alpha^3 d(x, y)$ and $\rho(T(y), T(x)) = |\alpha y - \alpha x|^3 = \alpha^3 d(x, y)$ and hence $H(T(x), T(y)) = \alpha^3 d(x, y)$.

(2) $x, y \in M_2$

In this case $\rho(T(x), T(y)) = |\beta x - \beta y|^3 = \beta^3 d(x, y)$ and $\rho(T(y), T(x)) = |\beta y - \beta x|^3 = \beta^3 d(x, y)$ and hence $H(T(x), T(y)) = \beta^3 d(x, y) \leq \alpha^3 d(x, y)$.

(3) $x \in M_1, y \in M_2$

In this case $\rho(T(x), T(y)) = |\alpha x - \beta y|^3$ and $\rho(T(y), T(x)) = |\beta y - \alpha x|^3$ and hence $H(T(x), T(y)) = |\alpha x - \beta y|^3$.

We have to consider the following cases:

3.1. If $x > y$, then $|x - \frac{\beta}{\alpha}y| < |x - \beta y|$, and hence $H(T(x), T(y)) = |\alpha x - \beta y|^3 = \alpha^3 |x - \frac{\beta}{\alpha}y|^3 \leq \alpha^3 |x - \beta y|^3 = \alpha^3 D(x, T(y))$.

3.2. If $x < y$, then:

If $x < \beta y$, then $|\frac{\alpha}{\beta}x - y| < |\alpha x - y|$, and hence $H(T(x), T(y)) = |\alpha x - \beta y|^3 = \beta^3 |\frac{\alpha}{\beta}x - y|^3 \leq \beta^3 |\alpha x - y|^3 = \beta^3 D(y, T(x)) \leq \alpha^3 D(y, T(x))$.

If $x > \beta y$, then we have another two cases:

If $\alpha x < \beta y$, then $|\frac{\alpha}{\beta}x - y| < |\alpha x - y|$, and hence $H(T(x), T(y)) = |\alpha x - \beta y|^3 = \beta^3 |\frac{\alpha}{\beta}x - y|^3 \leq \beta^3 |\alpha x - y|^3 = \beta^3 D(y, T(x)) \leq \alpha^3 D(y, T(x))$.

If $\alpha x > \beta y$, then $|x - \frac{\beta}{\alpha}y| < |x - \beta y|$, and hence $H(T(x), T(y)) = |\alpha x - \beta y|^3 = \alpha^3 |x - \frac{\beta}{\alpha}y|^3 \leq \alpha^3 |x - \beta y|^3 = \alpha^3 D(x, T(y))$.

(4) $x \in M_2, y \in M_1$

In this case $\rho(T(x), T(y)) = |\beta x - \alpha y|^3$ and $\rho(T(y), T(x)) = |\alpha y - \beta x|^3$ and hence $H(T(x), T(y)) = |\alpha y - \beta x|^3$.

Just like in the previous case, we have to consider the following cases:

4.1. $x > y$

If $y < \beta x$, $|\frac{\alpha}{\beta}y - x| < |\alpha y - x|$, and hence $H(T(x), T(y)) = |\alpha y - \beta x|^3 = \beta^3 |\frac{\alpha}{\beta}y - x|^3 \leq \beta^3 |\alpha y - x|^3 = \beta^3 D(x, T(y)) \leq \alpha^3 D(x, T(y))$.

If $y > \beta x$, then we have another two cases:

If $\alpha y < \beta x$, then $|\frac{\alpha}{\beta}y - x| < |\alpha y - x|$, and hence $H(T(x), T(y)) = |\alpha y - \beta x|^3 = \beta^3 |\frac{\alpha}{\beta}y - x|^3 \leq \beta^3 |\alpha y - x|^3 = \beta^3 D(x, T(y)) \leq \alpha^3 D(x, T(y))$.

If $\alpha y > \beta x$, then $|y - \frac{\beta}{\alpha}x| < |y - \beta x|$, and hence $H(T(x), T(y)) = |\alpha y - \beta x|^3 = \alpha^3 |y - \frac{\beta}{\alpha}x|^3 \leq \alpha^3 |y - \beta x|^3 = \alpha^3 D(y, T(x))$.

4.2 $x < y$

In this case we have $|y - \frac{\beta}{\alpha}x| < |y - \beta x|$, and hence $H(T(x), T(y)) = |\alpha y - \beta x|^3 = \alpha^3 |y - \frac{\beta}{\alpha}x|^3 \leq \alpha^3 |y - \beta x|^3 = \alpha^3 D(y, T(x))$.

Hence, we can conclude that $H(T(x), T(y)) \leq \alpha^3 d(x, y) + \alpha^3 D(x, T(y)) + \alpha^3 D(y, T(x))$, for all $x, y \in X$.

If, for example $\alpha = \beta = \frac{1}{5}$, then $T : X \rightarrow P(X)$. If we consider $a = c = \alpha^3$ and $b = 0$, then, for $s = 3$, all the assumptions on a, b, c in Theorem 2.1 are fulfilled and the operator T defined above satisfies the conditions of the theorem. \square

In what follows we shall present a data dependence theorem for multivalued Hardy-Rogers operators in a complete b -metric space.

Theorem 2.4. Let (X, d) be a complete b -metric space with constant $s > 1$, $T_1, T_2 : X \rightarrow P(X)$ be two multivalued closed operators which satisfy the following conditions:

- (a) there exists $\eta > 0$ such that $H(T_1(x), T_2(x)) \leq \eta$, for all $x \in X$;
- (b) there exist $a_i, b_i, c_i \in \mathbb{R}_+, a_i + b_i + 2c_i s < \frac{s-1}{s^2}$ and $b_i + c_i s < \frac{1}{s}$ such that

$$H(T_i(x), T_i(y)) \leq a_i d(x, y) + b_i [D(x, T_i(x)) + D(y, T_i(y))] + c_i [D(x, T_i(y)) + D(y, T_i(x))],$$

for all $x, y \in X, i \in \{1, 2\}$.

In these conditions we have:

$$H(\text{Fix}(T_1), \text{Fix}(T_2)) \leq \frac{\eta^s}{1 - s \max \{A_1, A_2\}},$$

where $A_i = \frac{a_i + b_i + c_i s}{1 - b_i - c_i s}, i \in \{1, 2\}$

Proof. We'll show that for every $x_1^* \in \text{Fix}(T_1)$, there exists $x_2^* \in \text{Fix}(T_2)$ such that

$$d(x_1^*, x_2^*) \leq \frac{s\eta}{1 - sA_2}.$$

Let $x_1^* \in \text{Fix}(T_1)$ arbitrary and let $1 < q < \frac{1 - b_2 - c_2 s}{a_2 + b_2 + c_2 s} \frac{1}{s}$. As in the proof of Theorem 2.1. we construct a sequence $(x_n)_{n \in \mathbb{N}} \subset X$ of successive approximations of T_2 , with $x_0 := x_1^*$ and $x_1 \in T_2(x_1^*)$ having the property:

$$d(x_n, x_{n+1}) \leq \alpha_2^n d(x_0, x_1)$$

for each $n \in \mathbb{N}$, where $\alpha_2 = q \frac{a_2 + b_2 + c_2 s}{1 - b_2 - c_2 s} < \frac{1}{s}$.

If we consider that the sequence $(x_n)_{n \in \mathbb{N}}$ converges to x_2^* , we have that $x_2^* \in \text{Fix}(T_2)$. Moreover, for each $n \geq 0$, we have:

$$d(x_n, x_{n+p}) \leq s\alpha_2^n \frac{1 - (s\alpha_2)^p}{1 - s\alpha_2} d(x_0, x_1), p \in \mathbb{N}^*.$$

Since $s\alpha_2 < 1$, letting $p \rightarrow \infty$ we get that

$$d(x_n, x_2^*) \leq \frac{s\alpha_2^n}{1 - s\alpha_2} d(x_0, x_1), \forall n \in \mathbb{N}.$$

Choosing $n = 0$ in the above relation, we obtain

$$d(x_1^*, x_2^*) \leq \frac{s}{1 - s\alpha_2} d(x_1^*, x_1) \leq \frac{sq}{1 - s\alpha_2} H(T_1(x_1^*), T_2(x_1^*)) \leq \frac{s\eta q}{1 - s\alpha_2}.$$

Interchanging the roles of T_1 and T_2 we obtain that for every $u \in \text{Fix}(T_2)$, there exists $v \in \text{Fix}(T_1)$ such that

$$d(u, v) \leq \frac{s\eta q}{1 - s\alpha_1},$$

where $\alpha_1 = q \frac{a_1 + b_1 + c_1 s}{1 - b_1 - c_1 s} < \frac{1}{s}$.

Thus, letting $q \searrow 1$, we obtain the conclusion. \square

3. Well-Posedness of the Fixed Point Problem

In what follows we shall prove a well-posedness results with respect to the functional D .

Definition 3.1. Let (X, d) be a b -metric space with constant $s \geq 1$ and $T : X \rightarrow P(X)$ be a multivalued operator. By definition, the fixed point problem is well-posed for T with respect to D if:

- (i) $\text{Fix}(T) = \{x^*\}$;

(ii) If $(x_n)_{n \in \mathbb{N}}$ is a sequence in X such that $D(x_n, T(x_n)) \rightarrow 0$, as $n \rightarrow \infty$, then $x_n \xrightarrow{d} x^*$, as $n \rightarrow \infty$.

Theorem 3.2. Let (X, d) be a complete b -metric space with constant $s > 1$ and $T : X \rightarrow P(X)$ a multivalued operator for which there exist $a, b, c \in \mathbb{R}_+$, $a + b + 2cs < \frac{s-1}{s^2}$ and $b + cs < \frac{1}{s}$ such that

$$H(T(x), T(y)) \leq ad(x, y) + b [D(x, T(x)) + D(y, T(y))] + c [D(x, T(y)) + D(y, T(x))],$$

for all $x, y \in X$.

If $S\text{Fix}(T) \neq \emptyset$, then the fixed point problem is well-posed for T with respect to D .

Proof. Let $x \in S\text{Fix}(T)$ and let $(x_n)_{n \in \mathbb{N}}$ such that $D(x_n, T(x_n)) \rightarrow 0$, as $n \rightarrow \infty$.

We have:

$$d(x_n, x) \leq s [D(x_n, T(x_n)) + H(T(x_n), T(x))] \leq sD(x_n, T(x_n)) + asd(x_n, x) + bsD(x_n, T(x_n)) \\ + bsD(x, T(x)) + csD(x_n, T(x)) + csD(x, T(x_n))$$

$$d(x_n, x) \leq sD(x_n, T(x_n)) + asd(x_n, x) + bsD(x_n, T(x_n)) + \\ + cs^2d(x_n, x) + cs^2D(x, T(x)) + cs^2d(x_n, x) + cs^2D(x_n, T(x_n))$$

$$(1 - as - 2cs^2)d(x_n, x) \leq s(1 + b + cs)D(x_n, T(x_n)).$$

$a + 2cs < a + b + 2cs < \frac{s-1}{s^2} < \frac{1}{s}$ and hence $1 - as - 2cs^2 > 0$.

Thus, we have

$$d(x_n, x) \leq s \frac{1 + b + cs}{1 - as - 2cs^2} D(x_n, T(x_n)).$$

Letting $n \rightarrow \infty$, we shall obtain that $x_n \xrightarrow{d} x$. \square

4. Ulam-Hyers Stability

Definition 4.1. Let (X, d) be a b -metric space and $T : X \rightarrow P_{cl}(X)$ be a multivalued operator. The fixed point inclusion

$$x \in T(x), \quad x \in X \tag{1}$$

is called generalized Ulam-Hyers stable if and only if there exists $\psi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ increasing, continuous in 0 and with $\psi(0) = 0$, such that for each $\varepsilon > 0$ and for each solution $y^* \in X$ of the inequation

$$D(y, T(y)) \leq \varepsilon \tag{2}$$

there exists a solution x^* of the fixed point inclusion (4.1) such that

$$d(y^*, x^*) \leq \psi(\varepsilon).$$

If there exists $C > 0$ such that $\psi(t) := C \cdot t$, for each $t \in \mathbb{R}_+$, then the fixed point inclusion (4.1) is said to be Ulam-Hyers stable.

Theorem 4.2. Let (X, d) be a complete b -metric space with constant $s > 1$ and $T : X \rightarrow P(X)$ a multivalued operator such that:

(i) there exist $a, b, c \in \mathbb{R}_+$, $a + b + 2cs < \frac{s-1}{s^2}$ and $b + cs < \frac{1}{s}$ such that

$$H(T(x), T(y)) \leq ad(x, y) + b [D(x, T(x)) + D(y, T(y))] + c [D(x, T(y)) + D(y, T(x))],$$

for all $x, y \in X$;

(ii) T is closed;

If $S\text{Fix}(T) \neq \emptyset$, then the fixed point inclusion (4.1) is generalized Ulam-Hyers stable.

Proof. We are in the conditions of Theorem 2.1. and Theorem 2.2, hence $\text{Fix}(T) = S\text{Fix}(T) = \{x^*\}$. Let $\varepsilon > 0$ and y^* be a solution of (4.2).

We have

$$\begin{aligned} d(x^*, y^*) &= D(T(x^*), y^*) \leq sH(T(x^*), T(y^*)) + sD(y^*, T(y^*)) \\ &\leq sad(x^*, y^*) + sbD(x^*, T(x^*)) + sbD(y^*, T(y^*)) + \\ &\quad + scD(x^*, T(y^*)) + scD(y^*, T(x^*)) + sD(y^*, T(y^*)) \\ &\leq sad(x^*, y^*) + sbD(y^*, T(y^*)) + s^2cd(x^*, y^*) + \\ &\quad + s^2cD(y^*, T(y^*)) + scd(x^*, y^*) + sD(y^*, T(y^*)). \end{aligned}$$

Thus

$$(1 - as - cs - cs^2)d(x^*, y^*) \leq s(1 + b + cs)D(y^*, T(y^*)).$$

We have that $a + (s + 1)c < a + 2cs < a + b + 2cs < \frac{s-1}{s^2} < \frac{1}{s}$, and hence $as + cs + cs^2 < 1$ and now we conclude

$$d(x^*, y^*) \leq \frac{s(1 + b + cs)}{1 - as - cs - cs^2} \varepsilon.$$

Hence, the fixed point problem (4.1) is generalized Ulam-Hyers stable. \square

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