

Published by Faculty of Sciences and Mathematics, University of Niš, Serbia Available at: http://www.pmf.ni.ac.rs/filomat

A Viscosity Iterative Algorithm for the Optimization Problem System

H. R. Sahebia, S. Ebrahimia

^aDepartment of Mathematics, Ashtian Branch, Islamic Azad University, Ashtian, Iran.

Abstract. In this paper, we suggest and analysis a viscosity iterative algorithm for finding a common element of the set of solution of a mixed equilibrium problem and the set the of solutions of a variational inequality and all common fixed points of a nonexpansive semigroup. This algorithm strongly converges to an element which solves an optimization problem system. Finally, some examples and numerical results are also given.

1. Introduction

Throughout this paper, we always assume that H is a Hilbert space and C is a nonempty, closed convex subset of H. Let $T: C \to C$ be a mapping. The fixed points set of T is denoted by F(T), that is

$$F(T) = \{x \in C : x = Tx\}.$$

The mapping T is called nonexpansive if $||Tx - Ty|| \le ||x - y||$, for all $x, y \in C$. Also, a map $f : C \to C$ is a λ -contraction on C if there exist a constant $\lambda \in [0,1)$ and $x,y \in C$ such that $||f(x) - f(y)|| \le \lambda ||x - y||$. The strong(weak) convergence of $\{x_n\}$ to x is written by $x_n \to x$ ($x_n \to x$) as $n \to \infty$. For any $x \in H$, there exists a unique nearest point of x in C, denoted by $P_C x$ such that

$$||x - P_C x|| \le ||x - y||$$
, for all $y \in C$.

 P_C is called the metric projection of H onto C.

A family $S = \{T(s) : s \in [0, +\infty)\}$ of mappings of C into itself is called a nonexpansive semigroup on C, if it satisfies the following conditions:

- (i) T(0)x = x for all $x \in C$;
- (ii) $T(s+t) = T(s) \circ T(t)$ for all $s, t \ge 0$;
- (iii) $||T(s)x T(s)y|| \le ||x y||$ for all $x, y \in C$ and $s \ge 0$;
- (iv) for all $x \in C$, $s \mapsto T(s)x$ is continuous.

Received: 04 February 2015; Accepted: 09 July 2015

Communicated by Dragan S. Djordjević

Email addresses: sahebi@email.aiau.ac.ir (H. R. Sahebi), ebrahimi@mail.aiau.ac.ir (S. Ebrahimi)

²⁰¹⁰ Mathematics Subject Classification. Primary: 47H09, 47H10; Secondary: 47J20.

Keywords. Viscosity approximatin, Nonexpansive semigroup, general equilibrium problems, strongly positive linear bounded operator, α —inverse strongly monotone mapping, fixed point, Hilbert space.

The set of all common fixed points of S is denoted by F(S), that is,

$$F(S) = \{ x \in C : T(s)x = x, s \in [0, +\infty) \}.$$

Let $F: C \times C \to R$ be a bi-function and $\psi: C \to R \cup \{\infty\}$ be a proper extended real-valued function. The classical mixed equilibrium problem [1] is to find $x \in C$ such that

$$F(x,y) + \psi(y) \ge \psi(x), \text{ for all } y \in C. \tag{1}$$

The solutions set of (1) is denoted by $MEP(F, \psi)$. One can see if x is a solution of problem, then $x \in dom\psi = \{x \in C : \psi(x) < \infty\}$.

If $\psi \equiv 0$, then the mixed equilibrium problem (1) is reduces to the followings equilibrium problem [1]: finding $x \in C$ such that

$$F(x, y) \ge 0$$
, for all $y \in C$. (2)

The solutions set of (2) is denoted by EP(F).

Let $\phi : C \to H$ be a mapping. A variational inequality problem (denoted by $VI(C, \phi)$) is to find $x \in C$ such that

$$\langle \phi x, y - x \rangle \ge 0$$
, for all $y \in C$. (3)

The map $G: C \to H$ is ρ -inverse strongly monotone, if there exists a positive real number $\rho > 0$ such that

$$\langle Gx - Gy, x - y \rangle \ge \rho ||Gx - Gy||^2$$
, for all $x, y \in C$.

Recall that *A* is a strongly positive bounded linear operator on *H* , if there exists a constant $\eta > 0$ such that

$$\langle Ax, x \rangle \ge \eta ||x||^2$$
, for all $x \in H$. (4)

In 2009, Li et al. [13], motivated and inspired by Marino and Xu [15], introduced the following two iterative algorithms for the approximation of common fixed points of one parameter nonexpansive semigroup $\{T(s): s \in [0, +\infty)\}$ on a nonempty closed convex subset C in a Hilbert space:

$$x_n = \alpha_n \gamma f(x_n) + (I - \alpha_n A) \frac{1}{s_n} \int_0^{s_n} T(s) x_n ds, \tag{5}$$

$$y_{n+1} = \alpha_n \gamma f(x_n) + (I - \alpha_n A) \frac{1}{s_n} \int_0^{s_n} T(s) y_n ds, \tag{6}$$

where $A: C \to H$ is a linear bounded strongly positive operator and $f: H \to H$ is α -cotraction, $\{\alpha_n\}$ and $\{s_n\}$ are sequences in [0,1) and $[0,+\infty)$, respectively .

In 2010, Cianciaruso et al. [4] introduced the following iterative method (by improving Plutieng and Punpaeng [18]), that include equilibrium and fixed points problems for nonexpansive semigroups $S = \{T(s)\}_{s\geq 0}$ on a Hilbert space H

$$\begin{cases} x_1 \in H \text{ chosen arbitrary,} \\ G(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - y_n \rangle \ge 0, \text{ for all } y \in H, \\ x_{n+1} = \alpha_n \gamma f(x_n) + (I - \alpha_n A) \frac{1}{s_n} \int_0^{s_n} T(s) u_n ds, \text{ for all } n \ge 0 \end{cases}$$

$$(7)$$

where $A: C \to H$ is a linear bounded strongly positive operator and $f: H \to H$ is α -contraction . They proved, the iterative algorithm $\{x_n\}$ which is defined by (7) strongly converges to a common element of $z \in F(S) \cap EP(F)$ and solved the variational inequality

$$\langle (\gamma f - A)z, p - z \rangle \le 0$$
, for all $p \in F(S) \cap EP(F)$.

Kang et al. [8] considerd an iterative algorithm $\{x_n\}$ in a Hilbert space as follows:

$$x_{n+1} = \alpha_n \gamma f(x_n) + \beta_n x_n + ((1 - \beta_n)I - \alpha_n A) \frac{1}{t_n} \int_0^{t_n} T(s) x_n ds.$$

Under the certain condition, the sequence $\{x_n\}$ strongly converges to a unique solution of the variational inequality

$$\langle (\gamma f - A)x^*, x - x^* \rangle \leq 0, \forall x \in F(T).$$

By intuition from [2], we suggest and analysis an iterative algorithm for finding a common element of the set of solution of a mixed equilibrium problem and the set of solutions of a variational inequality and all common fixed points of a nonexpansive semigroup in the framework of a Hilbert space.

2. Preliminaris

Let *G* be a monotone mapping of *C* into *H*. We have :

$$x \in VI(C, G) \iff x = P_C(x - \lambda Gx), \ \lambda > 0.$$

A set valued mapping $Q: H \to 2^H$ is called monotone, if for all $x, y \in H$, $f \in Qx$ and $g \in Qy$ imply $\langle x - y, f - g \rangle \ge 0$. A monotone mapping $Q: H \to 2^H$ is maximal if the graph of Q (denoted by Graph(Q)) is not properly contained in the graph of any other monotone mapping. It is known that a monotone mapping Q is maximal if and only if for $(x, f) \in H \times H$, $\langle x - y, f - g \rangle \ge 0$ for every $(y, g) \in Graph(Q)$ implies that $f \in Qx$. Let $N_C v$ be the normal cone to C at $v \in C$, that is, $N_C v = \{w \in H : \langle x - v, w \rangle \le 0, \forall x \in C\}$ and define

$$Qx = \begin{cases} Gv + N_C v & \text{if } v \in C \\ \emptyset & \text{if } v \notin C \end{cases}$$
 (8)

then Q is the maximal monotone and $0 \in Qv$ if and only if $v \in VI(C, G)$ [19].

Suppose $\psi: C \to \mathbb{R} \bigcup \{+\infty\}$ is a real-valued function. To solve the mixed equilibrium problem for a bi-function $F: C \times C \to \mathbb{R}$, let us assume the followings:

- (A_1) F(x,x) = 0 for all $x \in C$;
- (A₂) F is monotone, i.e., $F(x, y) + F(y, x) \le 0$ for all $x, y \in C$;
- (A₃) For each $x, y, z \in C$, $\lim_{t \to 0^+} F(tz + (1 t)x, y) \le F(x, y)$;
- (A_4) For each fixed $x \in C$, $y \mapsto F(x, y)$ is convex and lower semicontinuous;
- (A_5) For each fixed $y \in C$, $x \mapsto F(x, y)$ is weakly upper semicontinuous;
- (B_1) For each $x \in C$ and r > 0, there exist a bounded subset $D_x \subseteq C$ and $y_x \in C$ such that for each $z \in C \setminus D_x$, $F(z, y_x) + \psi(y_x) \psi(z) + \frac{1}{r} \langle y_x z, z x \rangle < 0$,
- (B_2) C is a bounded set.

Lemma 2.1. ([16]) Let C be a nonempty closed convex subset of a Hilbert space H and $\{T(s)\}_{s\geq 0}$ be a nonexpansive semigroup on H . Then, for every $h\geq 0$

$$\lim_{t\to\infty} \sup_{x\in C} \left\| \frac{1}{t} \int_0^t T(s)xds - T(h) \frac{1}{t} \int_0^t T(s)xds \right\| = 0.$$

Lemma 2.2. ([22]) Let $\{x_n\}$ and $\{y_n\}$ be bounded sequences in a Banach space X such that

$$x_{n+1} = \lambda_n x_n + (1 - \lambda_n) y_n, \quad n \ge 0,$$

where $\{\lambda_n\}$ is a sequence in [0, 1] such that

$$0 < \liminf_{t \to \infty} \lambda_n \le \limsup_{t \to \infty} \lambda_n < 1.$$

Assume

$$\limsup_{t\to\infty}(\|y_{n+1}-y_n\|-\|x_{n+1}-x_n\|)\leq 0,$$

then $\lim_{t\to\infty} ||y_n - x_n|| = 0$.

Lemma 2.3. ([26]) Let $\{s_n\}$ be a sequence of nonnegative real numbers satisfying

$$s_{n+1} \leq (1 - \gamma_n)s_n + \delta_n$$
, for all $n \geq 0$,

where $\{\gamma_n\}$ is a sequence in (0,1) and $\{\delta_n\}$ is a sequences of real numbers such that

(i)
$$\lim_{t\to\infty} \gamma_n = 0$$
 and $\sum_{n=1}^{\infty} \gamma_n = \infty$;

(ii)
$$\limsup_{t\to\infty} \frac{\delta_n}{\gamma_n} \le 0$$
 or $\sum |\delta_n| < \infty$;

then $\lim_{t\to\infty} s_n = 0$.

Lemma 2.4. ([17]) Let C be a nonempty closed convex subset of H.

Let $F: C \times \to \mathbb{R}$ be a bi-function satisfies (A1) - (A5) and $\psi: C \to \mathbb{R} \cup \{+\infty\}$ be a proper lower semicontinuous and convex function. Assume either (B1) or (B2) holds. For r > 0 and $x \in H$, define a mapping $T_r: H \to C$ as follows:

$$T_r(x) = \{z \in C : F(z,y) + \psi(y) + \frac{1}{r} \langle y - z, z - x \rangle \ge \psi(z), \forall y \in C\},$$

for all $x \in H$. Then the following hold:

- (1) $T_r(x) \neq \emptyset$, $\forall x \in H$.
- (2) T_r is singel-valued.
- (3) T_r is firmly nonexpansive, that is, for any $x, y \in H$

$$||T_r x - T_r y||^2 \le \langle T_r x - T_r y, x - y \rangle.$$

- (4) $F(T_r) = MEP(F, \psi)$.
- (5) $MEP(F, \psi)$ is closed and convex.

3. Viscosity Iterative Algorithm

The viscosity method has been successfully applied to various problems coming from calculus of variations, minimal surface problems, plasticity theory and phase transition. It plays a central role in the study of degenerated elliptic and parabolic second order equations [10], [12], [14]. First abstract formulation of the properties of the viscosity approximation have been given by Tykhonov [23] in 1963 when studying illposed problems (see [5] for details). The concept of viscosity solution for Hamilton-Jacobi equations, which plays a crucial role in control theory, game theory and partial differential equations has been introduced by Crandall and Lions [3]. Recently, the viscosity iterative algorithm have received rapid development, see, for example, [6], [9], [11], [20], [24] and [25]. In this section, we introduce a viscosity iterative algorithma for finding a common element of the set of solution for an equilibrium problem (involving a bi-function defined on a closed convex subset) and the set of fixed points of a nonexpansive semigroup.

Theorem 3.1. Let

- H be a real Hilbert space, C be a nonempty closed convex subset of H,
- F_1, F_2, \ldots, F_k be bi-functions from $C \times C$ to \mathbb{R} satisfying (A1) (A5),
- $\psi_1, \psi_2, \dots, \psi_k$ be proper lower semicontinuous and convex functions form C to $\mathbb{R} \cup \{\infty\}$,
- $f: C \to C$ be a λ -contraction,
- $F(S) = \{T(s) : s \in [0, +\infty)\}$ is a nonexpansive semigroup on C,
- $G: C \to H$ be a ρ -inverse strongly monotone map,
- A be a strongly positive linear bounded operator on H with coefficient $\eta > 0$ and $0 < \gamma < \frac{\eta}{\lambda}$,
- the conditions (B1) or (B2) holds.
- $F(S) \cap_{i=1}^k MEP(F_i, \psi_i) \cap VI(C, G) \neq \emptyset$,
- $\{x_n\}$ be a sequence generated by $x_1 \in C$, $u_n^{(i)} \in C$ for all $i \in \{1, 2, \dots, k\}$ in the following manner:

$$\begin{cases} x_1 \in C, \\ F_1(u_n^{(1)}, y) + \psi_1(y) - \psi_1(u_n^{(1)}) + \frac{1}{r_n} \langle y - u_n^{(1)}, u_n^{(1)} - x_n \rangle \ge 0, \text{ for all } y \in C, \\ F_2(u_n^{(2)}, y) + \psi_2(y) - \psi_2(u_n^{(2)}) + \frac{1}{r_n} \langle y - u_n^{(2)}, u_n^{(2)} - x_n \rangle \ge 0, \text{ for all } y \in C, \\ \vdots \\ F_k(u_n^{(k)}, y) + \psi_k(y) - \psi_k(u_n^{(k)}) + \frac{1}{r_n} \langle y - u_n^{(k)}, u_n^{(k)} - x_n \rangle \ge 0, \text{ for all } y \in C, \\ \omega_n = \frac{u_n^{(1)} + u_n^{(2)} \cdots u_n^{(k)}}{k}, \\ z_n = P_C(\omega_n - t_n G \omega_n), \\ y_n = \lambda_n \omega_n + (1 - \lambda_n) z_n, \\ x_{n+1} = \alpha_n \gamma f(x_n) + \beta_n x_n + ((1 - \beta_n)I - \alpha_n A) \frac{1}{s_n} \int_0^{s_n} T(s) y_n ds, \end{cases}$$

where $\{\alpha_n\}$, $\{\beta_n\}$ and $\{\lambda_n\}$ are the sequences in (0,1) and $\{r_n\} \subset (0,\infty)$, $\{t_n\} \subset (0,2\rho)$ are a real sequence.

Suppose

(C1)
$$\lim_{n\to\infty}\alpha_n=0, \ \sum_{n=1}^{\infty}\alpha_n=\infty,$$

(C2)
$$\lim_{n\to\infty} \lambda_n = 0$$
,

(C3)
$$0 < \liminf_{n \to \infty} \beta_n \le \limsup_{n \to \infty} \beta_n < 1$$
,

(C4)
$$\liminf_{n\to\infty} r_n > 0$$
, and $\lim_{n\to\infty} |r_{n+1} - r_n| = 0$,

(C5)
$$\{t_n\} \subset [a,b], for a,b \in (0,2\rho) \ and \lim_{n\to\infty} |t_{n+1}-t_n|=0,$$

(C6)
$$\lim_{n\to\infty} s_n = \infty$$
, and $\limsup_{n\to\infty} ||s_{n+1} - s_n||$ is finite.

Then

- (i) the sequence $\{x_n\}$ is bounded,
- (ii) $\lim_{n\to\infty} ||x_{n+1} x_n|| = 0$,

(iii)
$$\lim_{n\to\infty}||\omega_n-x_n||=0,$$

(iv)
$$\lim_{n\to\infty} ||G\omega_n - Gp|| = 0$$
, $p \in MEP(F_i, \psi_i) \cap VI(C, G)$

(v)
$$\lim_{n\to\infty} ||x_n - \frac{1}{s_n} \int_0^{s_n} T(S)y_n ds|| = 0$$
 and $\lim_{n\to\infty} ||y_n - \frac{1}{s_n} \int_0^{s_n} T(S)y_n ds|| = 0$.

Proof. By the same argument in [7],

$$||(1-\beta_n)I-\alpha_nA|| \le 1-\beta_n-\alpha_n\eta.$$

For any $x, y \in C$, it follows that

$$||(I - t_n G)(x) - (I - t_n G)(y)||^2 = ||(x - y) - t_n (Gx - Gy)||^2$$

$$\leq ||x - y||^2 - 2t_n \rho - 2t_n \rho ||Gx - Gy||^2 + t_n^2 ||Gx - Gy||^2 + t_n^2 ||Gx - Gy||^2$$

$$= ||x - y||^2 + t_n (t_n - 2\rho) ||Gx - Gy||^2.$$
(9)

Therefore, $I - t_n G$ is nonexpansive . Since $t_n \in (0, 2\rho)$, G is a ρ -inverse strongly monotone map, we see that $||(I - t_n)Gx - (I - t_n)Gy|^2 \le ||x - y||^2$.

Let $p \in F(S) \cap_{i=1}^k MEP(F_i, \psi_i) \cap VI(C, G)$. Notice that, for all $n \ge 1$, $1 \le i \le k$, $u_n^{(i)}$ can be re-written as $u_n^{(i)} = T_{r^{(i)}} x_n$, then

$$||u_n^{(i)} - p|| = ||T_{r^{(i)}} x_n - T_{r^{(i)}} p|| \le ||x_n - p||, \tag{10}$$

hence

$$\|\omega_n - p\| = \|\frac{1}{k} \sum_{i=1}^k u_n^{(i)} - p\| \le \|x_n - p\|.$$
(11)

From the fact that P_C and $I - t_n G$ are nonexpansive and $p = P_C(p - t_n Gp)$, we obtain

$$||z_{n} - p|| = ||P_{C}(\omega_{n} - t_{n}G\omega_{n}) - P_{C}(p - t_{n}Gp)||$$

$$\leq ||(I - t_{n}G)\omega_{n} - (I - t_{n}G)p||$$

$$< ||\omega_{n} - p||.$$
(12)

By (11) and (12), one has

$$||y_{n} - p|| = ||\lambda_{n}\omega_{n} + (1 - \lambda_{n})z_{n} - p||$$

$$\leq \lambda_{n}||\omega_{n} - p|| + (1 - \lambda_{n})||z_{n} - p||$$

$$\leq ||\omega_{n} - p||$$

$$\leq ||x_{n} - p||.$$
(13)

(i): We have

$$\begin{aligned} \|x_{n+1} - p\| &= \|\alpha_n \gamma f(x_n) + \beta_n x_n + ((1 - \beta_n)I - \alpha_n A) \frac{1}{s_n} \int_0^{s_n} T(s) y_n ds - p\| \\ &\leq \alpha_n \|\gamma f(x_n) - Ap\| + \beta_n \|x_n - p\| + \|((1 - \beta_n)I - \alpha_n A)\| \frac{1}{s_n} \int_0^{s_n} T(s) y_n ds - p\| \\ &\leq \alpha_n \{\|\gamma f(x_n) - \gamma f(p)\| + \|\gamma f(p) - Ap\| \} + \beta_n \|x_n - p\| + (1 - \beta_n - \alpha_n \eta) \frac{1}{s_n} \int_0^{s_n} \|T(s) y_n ds - p\| \\ &\leq \alpha_n \lambda \gamma \|x_n - p\| + \alpha_n \|\gamma f(p) - \gamma Ap\| + \beta_n \|x_n - p\| + (1 - \beta_n - \alpha_n \eta) \|y_n - p\| \\ &\leq \alpha_n \lambda \gamma \|x_n - p\| + \alpha_n \|\gamma f(p) - \gamma Ap\| + \beta_n \|x_n - p\| + (1 - \beta_n - \alpha_n \eta) \|x_n - p\| \\ &= \{1 - (\alpha_n (\eta - \gamma \lambda))\} \|x_n - p\| + \alpha_n \|\gamma f(p) - \gamma Ap\| \\ &\leq \max\{\|x_n - p\|, \frac{\|\gamma f(p) - Ap\|}{n - \gamma \lambda}\}. \end{aligned}$$

By a simple inductive process,

$$||x_n - p|| \le \max\{||x_1 - p||, \frac{||\gamma f(p) - Ap||}{\eta - \gamma \lambda}\}.$$
 (14)

This implies that the sequence $\{x_n\}$ is bounded. Also , $\{f(x_n)\}$, $\{y_n\}$ and $\{\frac{1}{s_n}\int_0^{s_n}T(s)y_nds\}$ are bounded.

(ii) : For
$$i \in \{1,2,\cdots,k\}$$
 , $u_n^{(i)}=T_{r_{n,i}}x_n \in dom\psi_i$ and $u_{n+1}^{(i)}=T_{r_{n+1,i}}x_{n+1} \in dom\psi_i$. Also , for all $y \in C$

$$F_i(u_n^{(i)}, y) + \psi_i(y) - \psi_i(u_n^{(i)}) + \frac{1}{r_n} \langle y - u_n^{(i)}, u_n^{(i)} - x_n \rangle \ge 0, \tag{15}$$

$$F_i(u_{n+1}^{(i)}, y) + \psi_i(y) - \psi_i(u_{n+1}^{(i)}) + \frac{1}{r_{n+1}} \langle y - u_{n+1}^{(i)}, u_{n+1}^{(i)} - x_{n+1} \rangle \ge 0.$$
 (16)

In view of (A2) and take $y = u_{n+1}^{(i)}$ in (15) and $y = u_n^{(i)}$ in (16), we obtain

$$\langle u_{n+1}^{(i)} - u_n^{(i)}, \frac{u_n^{(i)} - x_n}{r_n} - \frac{u_{n+1}^{(i)} - x_{n+1}}{r_{n+1}} \rangle \ge 0.$$

$$(17)$$

It follows that

$$\langle u_{n+1}^{(i)} - u_n^{(i)}, u_n^{(i)} - u_{n+1}^{(i)} + x_{n+1} - x_n + (1 - \frac{r_n}{r_{n+1}})(u_{n+1}^{(i)} - x_{n+1}) \rangle \ge 0.$$
 (18)

Since $\liminf r_n > 0$, without loss of generality, there exists $\alpha > 0$ such that $r_n > \alpha$ for all $n \ge 1$. Hence

$$||u_{n+1}^{(i)} - u_n^{(i)}||^2 \le ||u_{n+1}^{(i)} - u_n^{(i)}||\{||x_{n+1} - x_n|| + |1 - \frac{r_n}{r_{n+1}}|||u_{n+1}^{(i)} - x_{n+1}||\},\tag{19}$$

so

$$||u_{n+1}^{(i)} - u_n^{(i)}|| \le ||x_{n+1} - x_n|| + \frac{1}{r_{n+1}}|r_{n+1} - r_n|M_i,$$
(20)

where $M_i = max\{||u_n^{(i)} - x_n||, n \in \mathbb{N}\}.$

Therefore, we obtain

$$\|\omega_{n+1} - \omega_n\| \le \frac{1}{k} \sum_{i=1}^k \|u_{n+1}^{(i)} - u_n^{(i)}\| \le \|x_{n+1} - x_n\| + M|r_{n+1} - r_n|, \tag{21}$$

where $M = \frac{1}{k} \sum_{i=1}^{k} \frac{1}{\alpha} M_i$. From which it follows that

$$\begin{aligned} \|z_{n+1} - z_n\| &= \|P_C(\omega_{n+1} - t_{n+1}G\omega_{n+1}) - P_C(\omega_n - t_nG\omega_n)\| \\ &\leq \|(\omega_{n+1} - t_{n+1}G\omega_{n+1}) - (\omega_n - t_{n+1}G\omega_n) + (\omega_n - t_{n+1}G\omega_n) - (\omega_n - t_nG\omega_n)\| \\ &\leq \|\omega_{n+1} - \omega_n\| + |t_{n+1} - t_n\||G\omega_n\|. \end{aligned}$$

In view of (21), we obtain that

$$||z_{n+1} - z_n|| \le ||x_{n+1} - x_n|| + M|r_{n+1} - r_n| + |t_{n+1} - t_n|||G\omega_n||.$$
(22)

It follows

$$\begin{aligned} \|y_{n+1} - y_n\| &= \|\lambda_{n+1}\omega_{n+1} + (1 - \lambda_{n+1})z_{n+1} - \lambda_n\omega_n - (1 - \lambda_n)z_n\| \\ &= \|\lambda_{n+1}(\omega_{n+1} - \omega_n) + (\lambda_{n+1} - \lambda_n)\omega_n + (1 - \lambda_{n+1})z_{n+1} - (1 - \lambda_{n+1})z_n + (1 - \lambda_{n+1})z_n - (1 - \lambda_n)z_n\| \\ &= \|\lambda_{n+1}(\omega_{n+1} - \omega_n) + (\lambda_{n+1} - \lambda_n)\omega_n + (1 - \lambda_{n+1})(z_{n+1} - z_n) + (\lambda_n - \lambda_{n+1})z_n\| \\ &\leq \lambda_{n+1}\|\omega_{n+1} - \omega_n\| + |\lambda_{n+1} - \lambda_n|(\|\omega_n\| + \|z_n\|) + (1 - \lambda_{n+1})\|z_{n+1} - z_n\| \\ &\leq \lambda_{n+1}\|\omega_{n+1} - \omega_n\| + |\lambda_{n+1} - \lambda_n|(\|\omega_n\| + \|z_n\|) + (1 - \lambda_{n+1})\{\|x_{n+1} - x_n\| + M|r_{n+1} - r_n| + |t_{n+1} - t_n\|\|G\omega_n\|\}, \end{aligned}$$

from which it follows that

$$||y_{n+1} - y_n|| \le ||x_{n+1} - x_n|| + |\lambda_{n+1} - \lambda_n|(||\omega_n|| + ||z_n||) + M|r_{n+1} - r_n| + |t_{n+1} - t_n|||G\omega_n||.$$
(23)

On the other hand

$$\begin{split} &\|\frac{1}{s_{n+1}}\int_{0}^{s_{n+1}}T(s)y_{n+1}ds-\frac{1}{s_{n}}\int_{0}^{s_{n}}T(s)y_{n}ds\|\\ &=\|\frac{1}{s_{n+1}}\int_{0}^{s_{n+1}}[T(s)y_{n+1}-T(s)y_{n}]ds+(\frac{1}{s_{n+1}}-\frac{1}{s_{n}})\int_{0}^{s_{n}}[T(s)y_{n}-T(s)p]ds+\frac{1}{s_{n+1}}\int_{s_{n}}^{s_{n+1}}[T(s)y_{n}-T(s)p]ds\|\\ &\leq\|y_{n+1}-y_{n}\|+\frac{2|s_{n+1}-s_{n}|}{s_{n+1}}\|y_{n}-p\|. \end{split}$$

Thus, we obtian from (23)

$$\begin{split} &\|\frac{1}{s_{n+1}}\int_{0}^{s_{n+1}}T(s)y_{n+1}ds - \frac{1}{s_{n}}\int_{0}^{s_{n}}T(s)y_{n}ds\|\\ &\leq \|x_{n+1} - x_{n}\| + |\lambda_{n+1} - \lambda_{n}|(\|\omega_{n}\| + \|z_{n}\|) + M|r_{n+1} - r_{n}| + |t_{n+1} - t_{n}|\|G\omega_{n}\| + \frac{2|s_{n+1} - s_{n}|}{s_{n+1}}\|y_{n} - p\|. \end{split} \tag{24}$$

Now, suppose $\Sigma_n = \frac{\alpha_n \gamma f(x_n) + ((1-\beta_n)I - \alpha_n A)\Lambda_n}{1-\beta_n}$, where $\Lambda_n = \frac{1}{s_n} \int_0^{s_n} T(s) y_n ds$. It follows from (24)

$$\begin{split} \|\Sigma_{n+1} - \Sigma_{n}\| &= \|\frac{\alpha_{n+1}\gamma f(x_{n+1}) + ((1-\beta_{n+1})I - \alpha_{n+1}A)\Lambda_{n+1}}{1-\beta_{n+1}} - \frac{\alpha_{n}\gamma f(x_{n}) + ((1-\beta_{n})I - \alpha_{n}A)\Lambda_{n}}{1-\beta_{n}}\| \\ &= \|\frac{\alpha_{n+1}\gamma f(x_{n+1})}{1-\beta_{n+1}} + \frac{(1-\beta_{n+1})\Lambda_{n+1}}{1-\beta_{n+1}} - \frac{\alpha_{n+1}A\Lambda_{n+1}}{1-\beta_{n+1}} - \frac{\alpha_{n}\gamma f(x_{n})}{1-\beta_{n}} - \frac{(1-\beta_{n})\Lambda_{n}}{1-\beta_{n}} + \frac{\alpha_{n}A\Lambda_{n}}{1-\beta_{n}}\| \\ &= \|\frac{\alpha_{n+1}}{1-\beta_{n+1}} (\gamma f(x_{n+1}) - A\Lambda_{n+1}) + \frac{\alpha_{n}}{1-\beta_{n}} (A\Lambda_{n} - \gamma f(x_{n})) + (\Lambda_{n+1} - \Lambda_{n})\| \\ &\leq \frac{\alpha_{n+1}}{1-\beta_{n+1}} \|\gamma f(x_{n+1}) - A\Lambda_{n+1}\| + \frac{\alpha_{n}}{1-\beta_{n}} \|A\Lambda_{n} - \gamma f(x_{n})\| + \|\Lambda_{n+1} - \Lambda_{n}\| \\ &\leq \frac{\alpha_{n+1}}{1-\beta_{n+1}} \|\gamma f(x_{n+1}) - A\Lambda_{n+1}\| + \frac{\alpha_{n}}{1-\beta_{n}} \|A\Lambda_{n} - \gamma f(x_{n})\| \\ &+ \|x_{n+1} - x_{n}\| + M|r_{n+1} - r_{n}| + \frac{2|s_{n+1} - s_{n}|}{s_{n+1}} \|y_{n} - p\| + |t_{n+1} - t_{n}| \|G\omega_{n}\| + |\lambda_{n+1} - \lambda_{n}| (\|\omega_{n}\| + \|z_{n}\|). \end{split}$$

Thanks to the conditions (C1)- (C2) and (C4) – (C6), we conclude that

$$\lim_{n \to \infty} \sup (\|\Sigma_{n+1} - \Sigma_n\| - \|x_{n+1} - x_n\|) \le 0.$$

By lemma 2.2, we arrive at

$$\lim_{n \to \infty} ||\Sigma_n - x_n|| = 0. \tag{25}$$

It follows that

$$\lim_{n \to \infty} ||x_{n+1} - x_n|| = \lim_{n \to \infty} (1 - \beta_n) ||\Sigma_n - x_n|| = 0.$$
(26)

(iii): For any $i = 1, 2, \dots, k$, we have

$$\begin{split} \|u_{n}^{(i)} - p\|^{2} &= \|T_{r_{n}^{(i)}} x_{n} - T_{r_{n}^{(i)}} p\|^{2} \\ &\leq \langle T_{r_{n}^{(i)}} x_{n} - T_{r_{n}^{(i)}} p, x_{n} - p \rangle \\ &= \frac{1}{2} (\|u_{n}^{(i)} - p\|^{2} + \|x_{n} - p\|^{2} - \|u_{n}^{(i)} - p - x_{n} + p\|^{2}) \\ &= \frac{1}{2} (\|u_{n}^{(i)} - p\|^{2} + \|x_{n} - p\|^{2} - \|u_{n}^{(i)} - x_{n}\|^{2}), \\ &\leq \|x_{n} - p\|^{2} - \|u_{n}^{(i)} - x_{n}\|^{2}. \end{split}$$

Hence

$$\|\omega_{n} - p\| = \|\sum_{i=1}^{k} \frac{1}{k} (\|u_{n}^{(i)} - p)\|^{2}$$

$$\leq \frac{1}{k} \sum_{i=1}^{k} \|u_{n}^{(i)} - p\|^{2}$$

$$\leq \|x_{n} - p\|^{2} - \frac{1}{k} \sum_{i=1}^{k} \|u_{n}^{(i)} - x_{n}\|^{2}.$$
(27)

In viwe of (27) and (13), we obtain that

$$\begin{aligned} \|x_{n+1} - p\|^2 &= \|\alpha_n \gamma f(x_n) + \beta_n x_n + ((1 - \beta_n)I - \alpha_n A)\Lambda_n - p\|^2 \\ &= \|\alpha_n (\gamma f(x_n) - Ap) + \beta_n (x_n - p) + ((1 - \beta_n)I - \alpha_n A)(\Lambda_n - p)\|^2 \\ &\leq \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta) \|\Lambda_n - p\|^2 \\ &\leq \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta) \|y_n - p\|^2 \\ &\leq \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta) \|\omega_n - p\|^2 \\ &\leq \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta) (\|x_n - p\|^2 - \frac{1}{k} \sum_{i=1}^k \|u_n^{(i)} - x_n\|^2) \\ &\leq \alpha_n \|\gamma f(x_n) - Ap\|^2 + \|x_n - p\|^2 - (1 - \beta_n - \alpha_n \eta) \frac{1}{k} \sum_{i=1}^k \|u_n^{(i)} - x_n\|^2. \end{aligned}$$

It follows that

$$(1 - \beta_n - \alpha_n \eta) \frac{1}{k} \sum_{i=1}^k ||u_n^{(i)} - x_n||^2 \le ||x_n - p||^2 + \alpha_n ||\gamma f(x_n) - Ap||^2 - ||x_{n+1} - p||^2$$

$$= ||x_{n+1} - x_n||(||x_n - p|| + ||x_{n+1} - p||) + \alpha_n ||\gamma f(x_n) - Ap||^2.$$

Thanks to the condition (C1) and (26), we conclude that

$$\lim_{n \to \infty} ||u_n^{(i)} - x_n|| = 0, \tag{28}$$

also

$$\lim_{n \to \infty} ||\omega_n - x_n|| = 0. \tag{29}$$

(iv) : Let $z_n^* = P_C(p - t_n Gp)$ it follows from (9) that

$$||z_{n} - z_{n}^{*}||^{2} = ||P_{C}(\omega_{n} - t_{n}G\omega_{n}) - P_{C}(p - t_{n}Gp)||^{2}$$

$$\leq ||(\omega_{n} - t_{n}G\omega_{n}) - (p - t_{n}Gp)||^{2}$$

$$= ||(\omega_{n} - p) - t_{n}(G\omega_{n} - Gp)||^{2}$$

$$\leq ||x_{n} - p||^{2} + t_{n}(t_{n} - 2\rho)||G\omega_{n} - Gp||^{2}.$$

Observe that

$$\begin{aligned} \|x_{n+1} - p\|^2 & \leq & \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta) \|\Lambda_n - p\|^2 \\ & \leq & \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta) \|y_n - p\|^2 \\ & = & \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta) \|\{\lambda_n (\omega_n - p) + (1 - \lambda_n)(z_n - z_n^*)\|^2\} \\ & \leq & \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta)\lambda_n \|\omega_n - p\|^2 \\ & + (1 - \beta_n - \alpha_n \eta)(1 - \lambda_n) \|z_n - z_n^*\|^2 \\ & = & \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta)\lambda_n \|\omega_n - p\|^2 \\ & + (1 - \beta_n - \alpha_n \eta)(1 - \lambda_n) \|(\omega_n - p) - t_n (G\omega_n - Gp))\|^2 \\ & \leq & \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta)\lambda_n \|\omega_n - p\|^2 \\ & + (1 - \beta_n - \alpha_n \eta)(1 - \lambda_n)\{\|x_n - p\|^2 + t_n (t_n - 2\rho)\|G\omega_n - Gp\|^2\} \\ & \leq & \alpha_n \|\gamma f(x_n) - Ap\|^2 + (1 - \alpha_n \eta)\|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta)(1 - \lambda_n)t_n (t_n - 2\rho)\|G\omega_n - Gp\|^2 \\ & \leq & \alpha_n \|\gamma f(x_n) - Ap\|^2 + \|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta)(1 - \lambda_n)a(b - 2\rho)\|G\omega_n - Gp\|^2. \end{aligned}$$

It follows that

$$0 \le (1 - \beta_n - \alpha_n \eta)(1 - \lambda_n)a(2\rho - b)||G\omega_n - Gp||^2$$

$$\le \alpha_n ||\gamma f(x_n) - Ap||^2 + ||x_n - p||^2 - ||x_{n+1} - p||^2$$

$$\le \alpha_n ||\gamma f(x_n) - Ap||^2 + ||x_{n+1} - x_n||(||x_n - p|| + ||x_{n+1} - p||).$$

The condition (C1) and (26) imply

$$\lim_{n \to \infty} ||G\omega_n - Gp|| = 0. \tag{30}$$

(v): Notice that

$$\begin{split} \|z_{n}-p\|^{2} &= \|z_{n}-z_{n}^{*}\|^{2} \\ &\leq \langle(\omega_{n}-t_{n}G\omega_{n})-(p-t_{n}Gp),z_{n}-p\rangle \\ &= \frac{1}{2}\{\|(\omega_{n}-t_{n}G\omega_{n})-(p-t_{n}Gp)\|^{2}+\|z_{n}-p\|^{2}\}-\frac{1}{2}\{\|(\omega_{n}-t_{n}G\omega_{n})-(p-t_{n}Gp)-(z_{n}-p)\|^{2}\} \\ &= \frac{1}{2}\{\|\omega_{n}-p\|^{2}+\|z_{n}-p\|^{2}-\|(\omega_{n}-z_{n})-t_{n}(G\omega_{n}-Gp)\|^{2}\} \\ &= \frac{1}{2}\{\|\omega_{n}-p\|^{2}+\|z_{n}-p\|^{2}-(\|\omega_{n}-z_{n}\|^{2}+t_{n}^{2}\|G\omega_{n}-Gp\|^{2}-2t_{n}\langle\omega_{n}-z_{n},G\omega_{n}-Gp\rangle)\} \\ &\leq \frac{1}{2}\{\|\omega_{n}-p\|^{2}+\|z_{n}-p\|^{2}-\|\omega_{n}-z_{n}\|^{2}-t_{n}^{2}\|G\omega_{n}-Gp\|^{2}+2t_{n}\langle\omega_{n}-z_{n},G\omega_{n}-Gp\rangle)\}. \end{split}$$

From which follows that

$$||z_n - p||^2 \le ||\omega_n - p||^2 - ||\omega_n - z_n||^2 - t_n^2 ||G\omega_n - Gp||^2 + 2t_n \langle \omega_n - z_n, G\omega_n - Gp \rangle.$$

On the other hand, by some manipulation,

$$\begin{aligned} \|x_{n+1} - p\|^2 & \leq & \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta) \|y_n - p\|^2 \\ & = & \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + (1 - \beta_n - \alpha_n \eta) \|\lambda_n \omega_n + (1 - \lambda_n) z_n - p\|^2 \\ & \leq & \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + \lambda_n (1 - \beta_n - \alpha_n \eta) \|\omega_n - p\|^2 \\ & + (1 - \lambda_n) (1 - \beta_n - \alpha_n \eta) \|z_n - p\|^2 \\ & \leq & \alpha_n \|\gamma f(x_n) - Ap\|^2 + \beta_n \|x_n - p\|^2 + \lambda_n (1 - \beta_n - \alpha_n \eta) \|\omega_n - p\|^2 \\ & + (1 - \beta_n - \alpha_n \eta) \{\|\omega_n - p\|^2 - \|z_n - \omega_n\|^2 - t_n^2 \|G\omega_n - Gp\|^2 + 2t_n \langle \omega_n - z_n, G\omega_n \rangle \} \end{aligned}$$

$$\leq \alpha_{n} \| \gamma f(x_{n}) - Ap \|^{2} + \beta_{n} \| x_{n} - p \|^{2} + \lambda_{n} (1 - \beta_{n} - \alpha_{n} \eta) \| \omega_{n} - p \|^{2} + (1 - \beta_{n} - \alpha_{n} \eta) \| x_{n} - p \|^{2} - (1 - \beta_{n} - \alpha_{n} \eta) \| \omega_{n} - z_{n} \|^{2} - t_{n}^{2} (1 - \beta_{n} - \alpha_{n} \eta) \| G\omega_{n} - Gp \|^{2} + 2t_{n} (1 - \beta_{n} - \alpha_{n} \eta) \langle \omega_{n} - z_{n}, G\omega_{n} - Gp \rangle$$

$$\leq \alpha_{n} \| \gamma f(x_{n}) - Ap \|^{2} + \| x_{n} - p \|^{2} + \lambda_{n} (1 - \beta_{n} - \alpha_{n} \eta) \| \omega_{n} - p \|^{2}$$

$$- (1 - \beta_{n} - \alpha_{n} \eta) \| \omega_{n} - z_{n} \|^{2} - t_{n}^{2} (1 - \beta_{n} - \alpha_{n} \eta) \| G\omega_{n} - Gp \|^{2} + 2t_{n} (1 - \beta_{n} - \alpha_{n} \eta) \| \omega_{n} - z_{n} \| \| G\omega_{n} - Gp \|,$$

then

$$(1 - \beta_n - \alpha_n \eta) ||\omega_n - z_n||^2 \leq \alpha_n ||\gamma f(x_n) - Ap||^2 + ||x_n - p||^2 - ||x_{n+1} - p||^2 + \lambda_n (1 - \beta_n - \alpha_n \eta) ||\omega_n - p||^2 - t_n^2 (1 - \beta_n - \alpha_n \eta) ||G\omega_n - Gp||^2 + 2t_n (1 - \beta_n - \alpha_n \eta) ||\omega_n - z_n|||G\omega_n - Gp||.$$

By vitrue of (26) and (30) with conditions (C1) - (C2), we arrive at

$$\lim_{n \to \infty} ||\omega_n - z_n|| = 0. \tag{31}$$

Since $||y_n - z_n|| = \lambda_n ||\omega_n - z_n||$ then $\lim_{n \to \infty} ||y_n - z_n|| = 0$. We observe that

$$||y_n - \Lambda_n|| \le ||\Lambda_n - x_n|| + ||x_n - \omega_n|| + ||\omega_n - z_n|| + ||z_n - y_n||.$$

From which it follows that $\lim_{n\to\infty} ||y_n - \Lambda_n|| = 0$ or

$$\lim_{n \to \infty} ||y_n - \frac{1}{s_n} \int_0^{s_n} T(s) y_n ds|| = 0.$$
 (32)

On the other hand, it follows from definition of $\{x_n\}$ that

$$\begin{aligned} \|\Lambda_{n} - x_{n}\| & \leq \|x_{n+1} - x_{n}\| + \|x_{n+1} - \Lambda_{n}\| \\ & \leq \|x_{n+1} - x_{n}\| + \|\alpha_{n}\gamma f(x_{n}) + \beta_{n}x_{n} + ((1 - \beta_{n})I - \alpha_{n}A)\Lambda_{n} - \Lambda_{n}\| \\ & \leq \|x_{n+1} - x_{n}\| + \alpha_{n}\|\gamma f(x_{n}) - A\Lambda_{n}\| + \beta_{n}\|x_{n} - \Lambda_{n}\|, \end{aligned}$$

That is,

$$||\Lambda_n - x_n|| \leq \frac{1}{1 - \beta_n} ||x_{n+1} - x_n|| + \frac{\alpha_n}{1 - \beta_n} \gamma f(x_n) - A\Lambda_n||.$$

In view of (C1) and (26), we see that

$$\lim_{n \to \infty} ||\Lambda_n - x_n|| = 0. \tag{33}$$

Theorem 3.2. Suppose that all assumptions of Theorem 3.1 are hold. Then the sequence $\{x_n\}$ strongly converges to a point \bar{x} , where $\bar{x} \in F(S) \cap_{i=1}^k MEP(F_i, \psi_i) \cap VI(C, G)$ solves the variational inequality

$$\langle (A - \gamma f)\bar{x}, x - \bar{x} \rangle \ge 0.$$

Proof. Let $\Gamma = \bigcap_{i=1}^k F(S) \cap MEP(F_i, \psi_i) \cap VI(C, G)$. Thus $P_{\Gamma}(I - A + \gamma f)$ is a contraction of H into itself . Since H is complete , then there exists a unique element $\bar{x} \in H$ such that

$$\bar{x} = P_{\Gamma}(I - A + \gamma f)(\bar{x}).$$

Next, we show

$$\limsup_{n\to\infty} \langle (A-\gamma f)\bar{x}, \bar{x}-\frac{1}{s_n}\int_0^{s_n} T(s)y_n ds\rangle \leq 0.$$

Let $\tilde{x} = P_{\Gamma}x_1$. Set

$$\Pi = \{\bar{y} \in H: ||\bar{y} - \tilde{x}|| \leq ||x_1 - \tilde{x}|| + \frac{||\gamma f(\tilde{x}) - A\tilde{x}||}{\eta - \gamma \lambda}\}.$$

It is clear, Π is nonempty closed bounded convex subset of H which is T(s)-invariant for each $s \in [0, \infty)$ and $\{x_n\} \subset \Pi$. We may assume $S = \{T(s) : s \in [0, \infty)\}$ is a nonexpansive semigroup on Π . It follows from Lemma 2.1 that

$$\lim \sup_{n \to \infty} \left\| \frac{1}{s_n} \int_0^{s_n} T(s) y_n ds - T(h) \frac{1}{s_n} \int_0^{s_n} T(s) y_n ds \right\| = 0.$$
 (34)

Let $\Lambda_n = \frac{1}{s_n} \int_0^{s_n} T(s) y_n ds$, since $\{\Lambda_n\} \subset \Pi$ is bounded, there is a subsequence $\{\Lambda_{n_j}\}$ of $\{\Lambda_n\}$ such that

$$\lim \sup_{n \to \infty} \langle (A - \gamma f)\bar{x}, \bar{x} - \Lambda_n \rangle = \lim_{j \to \infty} \langle (A - \gamma f)\bar{x}, \bar{x} - \Lambda_{n_j} \rangle. \tag{35}$$

As $\{\Lambda_{n_j}\}$ is also bounded , there exists a subsequence $\{\Lambda_{n_{j_i}}\}$ of $\{\Lambda_{n_j}\}$ such that $\Lambda_{n_{j_i}} \to \xi$. Without loss of generality, let $\Lambda_{n_j} \to \xi$. Now, we prove the following items :

(i) $\xi \in F(S) = \bigcap_{s>1} F(T(s))$:

Assume $\xi \neq T(h)\xi$ for some $h \in [0, \infty)$. In view of (32) and Opial's condition, we obtain

$$\lim_{j \to \infty} \inf \|\Lambda_{n_{j}} - \xi\| < \lim_{j \to \infty} \inf \|\Lambda_{n_{j}} - T(h)\xi\|
\leq \lim_{j \to \infty} \inf (\|\Lambda_{n_{j}} - T(h)\Lambda_{n_{j}}\| + \|T(h)\Lambda_{n_{j}} - T(h)\xi\|)
\leq \lim_{j \to \infty} \inf \|\Lambda_{n_{j}} - \xi\|.$$

That is a contradiction . Hence $\xi = T(h)\xi$, i.e., $\xi \in F(S) = \bigcap_{s \ge 1} F(T(s))$

(ii) $\xi \in \bigcap_{i=1}^{k} MEP(F_i, \psi_i)$. For all $1 \le i \le k$, we see that

$$F_i(u_n^{(i)}, y) + \psi_i(y) - \psi_i(u_n^{(i)}) + \frac{1}{r_n} \langle y - u_n^{(i)}, u_n^{(i)} - x_n \rangle \ge 0$$
, for all $y \in C$.

It follows from (A2) that

$$\psi_i(y) - \psi_i(u_n^{(i)}) + \langle y - u_n^{(i)}, \frac{u_{n_j}^{(i)} - x_{n_j}}{r_{n_j}} \rangle \ge F_i(u_{n_j}^{(i)}, y), \text{ for all } y \in C.$$

Thanks to the condition (C4) and (28), we conclude that

$$\liminf_{n \to \infty} \|\frac{x_n - u_n^i}{r_n}\| = \liminf_{n \to \infty} \frac{1}{r_n} \|x_n - u_n^i\| = 0.$$
(36)

In view of (30) and (28), we obtain $u_{n_i}^{(i)} \rightarrow \xi$.

Since ψ_i , $1 \le i \le k$ are weakly lower semicontinus, it follows from (*A*4) and (36) that

$$F_i(y, \xi) + \psi_i(\xi) - \psi_i(y) \le 0$$
, for all $y \in C$.

Let $x_r = rx + (1 - r)\xi$ such that $0 < r \le 1$ and $x \in C$. It is clear that $x_r \in C$, thus

$$F_i(x_r, \xi) + \psi_i(\xi) - \psi_i(x_r) \le 0.$$

In view of (A1)-(A4) and convexity of ψ_i , we obtain

$$0 = F_{i}(x_{r}, x_{r}) + \psi_{i}(x_{r}) - \psi_{i}(x_{r})$$

$$\leq rF_{i}(x_{r}, x) + (1 - r)F_{i}(x_{r}, \xi) + r\psi_{i}(x) + (1 - r)\psi_{i}(x_{r})$$

$$= r(F_{i}(x_{r}, x) + \psi_{i}(x) - \psi_{i}(x_{r})) + (1 - r)(F_{i}(x_{r}, \xi) + \psi_{i}(\xi) - \psi_{i}(x_{r}))$$

$$\leq r(F_{i}(x_{r}, x) + \psi_{i}(x) - \psi_{i}(x_{r})).$$

From which it follows

$$F_i(x_r, x) + \psi_i(x) - \psi_i(x_r) \ge 0.$$

By virtue of weakly lower semi-continuity of ψ_i and (A3), we get

$$F_i(\xi, y) + \psi_i(y) - \psi_i(\xi) \ge 0$$
, for all $y \in C$.

This shows that $\xi \in \bigcap_{i=1}^k MEP(F_i, \psi_i)$.

(iii) $\xi \in VI(C,G)$:

Let N_C be the normal cone of C at $v \in C$. We define a set-valued $\Phi: H \to 2^H$ as follows:

$$\Phi v = \begin{cases} Gv + N_C v, & \text{if } v \in C, \\ \emptyset & \text{if } v \notin C \end{cases}$$

We knowe Φ is maximal monotone and $0 \in \Phi_v$ if and only if $v \in VI(C,G)$. Let $(v,w) \in Graph(\Phi)$. Since $w - Gv \in N_Cv$ and $z_n \in C$, we have

$$\langle v-z_n, w-Gv\rangle$$
.

Hence

$$\langle v - z_n, z_n - (\omega_n - t_n G \omega_n) \rangle \ge 0$$

that is

$$\langle v-z_n, \frac{z_n-\omega_n}{t_n}+G\omega_n\rangle \geq 0.$$

Moreover,

$$\langle v - z_{n_{j}}, w \rangle \geq \langle v - z_{n_{j}}, Gv \rangle$$

$$\geq \langle v - z_{n_{j}}, Gv \rangle - \langle v - z_{n_{j}}, \frac{z_{n_{j}} - \omega_{n_{j}}}{t_{n_{j}}} + G\omega_{n_{j}} \rangle$$

$$= \langle v - z_{n_{j}}, Gv - \frac{z_{n_{j}} - \omega_{n_{j}}}{t_{n_{j}}} - G\omega_{n_{j}} \rangle$$

$$= \langle v - z_{n_{j}}, Gv - Gz_{n_{j}} \rangle + \langle v - z_{n_{j}}, Gz_{n_{j}} - G\omega_{n_{j}} \rangle - \langle v - z_{n_{j}}, \frac{z_{n_{j}} - \omega_{n_{j}}}{t_{n_{j}}} \rangle$$

$$\geq \langle v - z_{n_{j}}, Gz_{n_{j}} - G\omega_{n_{j}} \rangle - \langle v - z_{n_{j}}, \frac{z_{n_{j}} - \omega_{n_{j}}}{t_{n_{j}}} \rangle$$

$$\geq ||v - z_{n_{j}}|| ||Gz_{n_{j}} - G\omega_{n_{j}}|| - ||v - z_{n_{j}}||||\frac{z_{n_{j}} - \omega_{n_{j}}}{t_{n_{j}}} ||.$$

Since G is ρ -inverse strongly monotone and $\lim_{n\to\infty} ||z_{n_j}-\omega_{n_j}||=0$, then $\langle v-\xi,w\rangle\geq 0$. Also Φ is maximal monotone, then $\xi\in\Phi^{-1}0$. Thus $\xi\in VI(C,G)$.

From which it follows that $\xi \in F(S) \cap_{i=1}^{k} MEP(F_i, \Psi_i) \cap VI(C, G)$.

Since $\xi = P_{\Gamma}(I - A + \gamma f)(\xi)$, we have

$$\limsup_{n \to \infty} \langle (A - \gamma f)\bar{x}, \bar{x} - \frac{1}{s_n} \int_0^{s_n} T(s) y_n ds \rangle
= \lim_{n \to \infty} \sup_{n \to \infty} \langle (A - \gamma f)\bar{x}, \bar{x} - \Lambda_{n_j} \rangle
= \langle (A - \gamma f)\bar{x}, \bar{x} - \xi \rangle \leq 0.$$
(37)

Finally, we prove that the sequence $\{x_n\}$ strongly converges to \bar{x} . We have

$$\begin{aligned} \|x_{n+1} - \bar{x}\|^2 &= \|\alpha_n \gamma f(x_n) + \beta_n x_n + ((1 - \beta_n)I - \alpha_n A) \Delta_n - \bar{x}\|^2 \\ &= \|\alpha_n (\gamma f(x_n) - A\bar{x}) + \beta_n (x_n - \bar{x}) + ((1 - \beta_n)I - \alpha_n A) (\Delta_n - \bar{x})\|^2 \\ &= \alpha_n^2 \|\gamma f(x_n) - A\bar{x}\|^2 + \|\beta_n (x_n - \bar{x}) + ((1 - \beta_n)I - \alpha_n A) (\Delta_n - \bar{x})\|^2 \\ &+ 2 \langle \beta_n (x_n - \bar{x}) + ((1 - \beta_n)I - \alpha_n A) (\Delta_n - \bar{x}), \alpha_n (\gamma f(x_n) - A\bar{x}) \rangle \\ &\leq \alpha_n^2 \|\gamma f(x_n) - A\bar{x}\|^2 + \|\beta_n \|x_n - \bar{x}\| + (1 - \beta_n - \alpha_n \eta) \|y_n - \bar{x}\|\|^2 \\ &+ 2\alpha_n \beta_n \langle x_n - \bar{x}, \gamma f(x_n) - A\bar{x} \rangle + 2\alpha_n (1 - \beta_n - \alpha_n \eta) \langle \Delta_n - \bar{x}, \gamma f(x_n) - A\bar{x} \rangle \\ &\leq \alpha_n^2 \|\gamma f(x_n) - A\bar{x}\|^2 + \{\beta_n \|x_n - \bar{x}\| + (1 - \beta_n - \alpha_n \eta) \|x_n - \bar{x}\|\|^2 \\ &+ 2\alpha_n (1 - \beta_n - \alpha_n \eta) \langle \Delta_n - \bar{x}, \gamma f(x_n) - \gamma f(\bar{x}) \rangle + 2\alpha_n (1 - \beta_n - \alpha_n \eta) \langle \Delta_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle \\ &\leq \alpha_n^2 \|\gamma f(x_n) - A\bar{x}\|^2 + (1 - \alpha_n \eta)^2 \|x_n - \bar{x}\|^2 \\ &+ 2\alpha_n \beta_n \langle x_n - \bar{x}, \gamma f(x_n) - \gamma f(\bar{x}) \| + 2\alpha_n \beta_n \langle x_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle \\ &\leq \alpha_n^2 \|\gamma f(x_n) - A\bar{x}\|^2 + (1 - \alpha_n \eta)^2 \|x_n - \bar{x}\|^2 + 2\alpha_n (1 - \beta_n - \alpha_n \eta) \langle \Delta_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle \\ &\leq \alpha_n^2 \|\gamma f(x_n) - A\bar{x}\|^2 + (1 - \alpha_n \eta)^2 \|x_n - \bar{x}\|^2 + 2\alpha_n \beta_n \gamma \lambda \|x_n - \bar{x}\|^2 \\ &+ 2\alpha_n \beta_n \langle x_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle + 2\alpha_n (1 - \beta_n - \alpha_n \eta) \langle \Delta_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle \\ &\leq \alpha_n^2 \|\gamma f(x_n) - A\bar{x}\|^2 + (1 - 2\alpha_n \eta + \alpha_n^2 \eta^2 + 2\alpha_n \gamma \lambda - 2\alpha_n^2 \eta \gamma \lambda) \|x_n - \bar{x}\|^2 \\ &+ 2\alpha_n \beta_n \langle x_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle + 2\alpha_n (1 - \beta_n - \alpha_n \eta) \langle \Delta_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle \\ &\leq \{1 - \alpha_n (2\eta - \alpha_n \eta^2 - 2\gamma \lambda + 2\alpha_n \eta \gamma \lambda) \|x_n - \bar{x}\|^2 \\ &+ \alpha_n^2 \|\gamma f(x_n) - A\bar{x}\|^2 + 2\alpha_n \beta_n \langle x_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle \\ &\leq \{1 - \alpha_n (2\eta - \alpha_n \eta^2 - 2\gamma \lambda + 2\alpha_n \eta \gamma \lambda) \|x_n - \bar{x}\|^2 \\ &+ \alpha_n (1 - \beta_n - \alpha_n \eta) \langle \Delta_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle \\ &\leq \{1 - \alpha_n (2\eta - \alpha_n \eta^2 - 2\gamma \lambda + 2\alpha_n \eta \gamma \lambda) \|x_n - \bar{x}\|^2 \\ &+ \alpha_n (1 - \beta_n - \alpha_n \eta) \langle \Delta_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle \\ &\leq \{1 - \alpha_n (2\eta - \alpha_n \eta^2 - 2\gamma \lambda + 2\alpha_n \eta \gamma \lambda) \|x_n - \bar{x}\|^2 \\ &+ \alpha_n (1 - \beta_n - \alpha_n \eta) \langle \Delta_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle \\ &\leq \alpha_n (1 - \beta_n - \alpha_n \eta) \langle \Delta_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle \\ &\leq \alpha_n (1 - \beta_n - \alpha_n$$

Suppose that

$$\varepsilon_n = \alpha_n ||\gamma f(x_n) - A\bar{x}||^2 + 2\beta_n \langle x_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle + 2(1 - \beta_n - \alpha_n \eta) \langle \Lambda_n - \bar{x}, \gamma f(\bar{x}) - A\bar{x} \rangle,$$

thus

$$||x_{n+1} - \bar{x}||^2 \le \{1 - \alpha_n (2\eta - \alpha_n \eta^2 - 2\gamma\lambda + 2\alpha_n \eta \gamma\lambda)\} ||x_n - \bar{x}||^2 + \alpha_n \varepsilon_n$$
(38)

It follows from (37) and Lemma 2.3 that

$$\limsup_{n\to\infty} \varepsilon_n \leq 0$$

which implies that the sequence $\{x_n\}$ strongly converges to \bar{x} . \square

4. An Application in Optimal Problem Systems

In this section, we consider the following optimization problem:

$$\min_{x \in F(T)} \frac{1}{2} \langle Ax, x \rangle - g(x), \tag{39}$$

where F(T) is the set of fixed points of $T: C \to C$ and g is a potential function for γ (i.e, $g(x) = \gamma f(x)$ for $x \in H$).

Theorem 4.1. Let H be a real Hilbert space, C be a nonempty closed convex subset of H, and $f: C \to C$ be a λ -contraction. Let A be a strongly positive linear bounded operator on H with coefficient $\eta > 0$ and $0 < \gamma < \frac{\eta}{\lambda}$ and $T: C \to C$ be a nonexpansive mapping such that $F(T) \neq \emptyset$. Suppose $\{x_n\}$ be a sequence generated by $x_1 \in C$ and:

$$x_{n+1} = \alpha_n \gamma f(x_n) + \beta_n x_n + ((1 - \beta_n)I - \alpha_n A)Tx_n, \tag{40}$$

where $\{\alpha_n\}$, $\{\beta_n\}$ and $\{\lambda_n\}$ are sequences in Theorem 3.1. Also, the conditions (C1) and (C3), in Theorem 3.1, are hold. If F(T) is a compact subset of C, then the sequence $\{x_n\}$ strongly converges to a point \bar{x} , where $\bar{x} \in F(T)$ which solves the optimization problem (39).

Proof. For $\{T(s)\}_{s\geq 0}=T$, A=I, $\lambda_n=0$, $\psi_i=0$, $F_i=0$, $\forall i\in\{1,2,\ldots,k\}$, and $G\equiv 0$, $P_C=I$, $y_n=x_n$ in Theorem 3.1, the sequence $\{x_n\}$ strongly converge to a point \bar{x} , where $\bar{x}\in F(T)$ which is the unique solution of the following variational inequality

$$\langle (A - \gamma f)\bar{x}, x - \bar{x} \rangle \ge 0, \forall x \in F(T). \tag{41}$$

Note that F(T) is a compact and convex subset of C and

$$\frac{1}{2}\langle Ax, x \rangle - g(x) : C \to R \tag{42}$$

is a continuous mapping. By Weierstrass theorem , there exists $\varepsilon \in F(T)$ which is a minimal point of optimization problem (39). On the other hand , (41) is the optimality necessary condition for the optimization problem (39) [26]. This implies

$$\langle (A - \gamma f)\varepsilon, x - \varepsilon \rangle \ge 0, \forall x \in F(T). \tag{43}$$

It is clear $\bar{x} = \varepsilon$, since \bar{x} is the unique solution of (41). \square

5. Numerical Examples

First, we present an example for Theorem 3.2.

Example 5.1. Suppose $H = \mathbb{R}$, C = [-1, 1] and

$$F_1(x, y) = -3x^2 + xy + 2y^2$$
 and $F_2(x, y) = -5x^2 + xy + 4y^2$,
 $F_3(x, y) = -7x^2 + xy + 6y^2$ and $F_4(x, y) = -9x^2 + xy + 8y^2$.

Also , we consider $\psi_1(x)=\psi_2(x)=\psi_3(x)=\psi_4(x)=3x^2$, $G(x)=\frac{x}{10}$, $A=I, f(x)=\frac{x}{5}$ with coefficient $\eta=\frac{1}{2}$, $\gamma=1$ and $T(s)=e^{-s}$ as a nonexpansive semigroup on C. It is easy to check that $\psi_1,\psi_2,\psi_3,\psi_4,A,f$ and T(s) satisfy all conditions in Theorem 3.1 . For each r>0 and $x\in C$, there exists $z\in C$ such that, for any $y\in C$,

$$F(z,y) + \psi(y) - \psi(z) + \frac{1}{r} \langle y - z, z - x \rangle \ge 0 \quad \Leftrightarrow \quad -3z^2 + zy + 5y^2 - 3z^2 + \frac{1}{r} (y - z)(z - x) \ge 0$$
$$\Leftrightarrow \quad 5ry^2 + ((r+1)z - x)y - 6rz^2 - z^2 + zx \ge 0$$

Set $B(y) = 5ry^2 + ((r+1)z - x)y - 6rz^2 - z^2 + zx$. Then B(y) is a quadratic function of y with coefficients a = 5r, b = (r+1)z - x and $c = -6rz^2 - z^2 + zx$. So

$$\Delta = [(r+1)z - x]^2 - 20r(zx - z^2 - 6rz^2)$$

$$= (r+1)^2 z^2 - 2(r+1)xz + x^2 + 120r^2 z^2 + 20rz^2 - 20rzx$$

$$= x^2 - 2(11rz + z)x + (121r2z^2 + 22rz^2 + z^2)$$

$$= [(x - (11rz + z))]^2.$$

 $B(y) \ge 0$ for all $y \in C$, if and only if $\Delta = [(x - (11rz + z))]^2 \le 0$. Therefore, $z = \frac{x}{11r+1}$, which yields $T_{r_n^{(1)}}=u_n^{(1)}=\frac{x_n}{11r_n+1}.$ By the same argument , for F_2 , one can conclude

$$\begin{split} T_{r_n^{(2)}} &= u_n^{(2)} = \frac{x_n}{15r_n + 1}, \\ T_{r_n^{(3)} = u_n^{(2)}} &= \frac{x_n}{19r_n + 1}, \\ T_{r_n^{(4)} = u_n^{(4)}} &= \frac{x_n}{23r_n + 1}. \end{split}$$

Hence

$$\omega_n = \frac{u_n^{(1)} + u_n^{(2)} + u_n^{(3)} + u_n^{(4)}}{4}.$$

Let $t_n = \frac{n}{n+2}$, $s_n = n$, $r_n = \frac{n}{n+1}$ and $\lambda_n = \frac{1}{10n}$, $\alpha_n = \frac{1}{20n}$ and $\beta_n = \frac{2n-1}{10n-9}$, we have the following algorithm for the sequence $\{x_n\}$

$$\begin{cases} z_n = \frac{19n+20}{10n+20} \omega_n, \\ y_n = \frac{1}{10n} \omega_n + \frac{10n-1}{10n} z_n, \\ x_{n+1} = \frac{200n^2 - 190n+9}{1000n^2 - 900n} x_n + \frac{160n^2 - 170n+9}{200n^3 - 180n^2} (1 - e^{-n}) \omega_n. \end{cases}$$

By using MATLAB software, we obtain the following table and figure of the result, with initial point $x_1 = 1$.

| n | x_n | n | x_n | n | x_n |
|----|------------------|----|-------------------------------|----|-------------------------------|
| 1 | 1 | 11 | $2.287053908 \times 10^{-6}$ | 21 | $3.762255275 \times 10^{-13}$ |
| 2 | 1.006470149 | 12 | $4.88149991 \times 10^{-7}$ | 22 | $7.780342962 \times 10^{-14}$ |
| 3 | 0.3059037033 | 13 | $1.036076343 \times 10^{-7}$ | 23 | $1.606482782 \times 10^{-14}$ |
| 4 | 0.07945190726 | 14 | $2.188663486 \times 10^{-8}$ | 24 | $3.312377978 \times 10^{-15}$ |
| 5 | 0.01922449408 | 15 | 4.604863982×10^{-9} | 25 | $6.820908513\times10^{-16}$ |
| 6 | 0.004465484024 | 16 | $9.654838368 \times 10^{-10}$ | 26 | $1.402906653 \times 10^{-16}$ |
| 7 | 0.001010074517 | 17 | $2.018167853 \times 10^{-10}$ | 27 | $2.882304587 \times 10^{-17}$ |
| 8 | 0.0002242641019 | 18 | $4.207385568 \times 10^{-11}$ | 28 | $5.915770281 \times 10^{-18}$ |
| 9 | 0.00004911325747 | 19 | $8.750678216 \times 10^{-12}$ | 29 | $1.213039518 \times 10^{-18}$ |
| 10 | 0.00001064273173 | 20 | $1.816167376 \times 10^{-12}$ | 30 | $2.48518864 \times 10^{-19}$ |

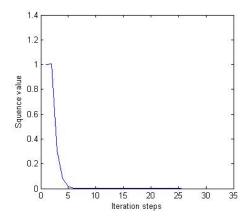


Figure 1: The graph of $\{x_n\}$ with initial value $x_1 = 1$.

Example 5.2. Let $H = \mathbb{R}$ and C = [1,2]. For each $x \in C$, we know $f(x) = \frac{x^2}{4}$ is a contractive mapping, $T(x) = \frac{1}{x}$ is a nonexpansive mapping on C and $F(T) = \{1\}$, A(x) = 2x is a strongly positive linear bounded operator on H. Let $\alpha_n = \frac{n}{2n-1}$ and $\gamma = 1$. Substituting all of the given conditions to the scheme (40), we have

$$x_{n+1} = \frac{n}{2n-1}x_n + \frac{1}{4n}x_n^2 + \frac{n^2 - 5n + 2}{2n^2 - n}\frac{1}{x_n}$$

Following the proof of Theorem 4.1, we easily obtain the sequence $\{x_n\}$ strongly converge to $1 \in F(T)$, which is the solution of the optimization problem

$$min_{x \in F(T)} \frac{1}{2} \langle Ax, x \rangle - g(x).$$

We obtain the following table and figure of the result, with the initial point $x_1 = 2$.

| n | x_n | n | x_n | n | x_n |
|----|--------------|----|--------------|----|--------------|
| 1 | 2 | 11 | 0.7992975259 | 21 | 0.9068849985 |
| 2 | 1.5 | 12 | 0.8201697889 | 22 | 0.9116063592 |
| 3 | 0.9097222222 | 13 | 0.8370906671 | 23 | 0.9158706523 |
| 4 | 0.4930490245 | 14 | 0.8510851663 | 24 | 0.9197413424 |
| 5 | 0.3762130308 | 15 | 0.8628533176 | 25 | 0.9232706421 |
| 6 | 0.5332945703 | 16 | 0.8728886137 | 26 | 0.9265019037 |
| 7 | 0.6270101604 | 17 | 0.8815486756 | 27 | 0.9294714244 |
| 8 | 0.6922463705 | 18 | 0.8890989313 | 28 | 0.9322098276 |
| 9 | 0.7385773109 | 19 | 0.8957405173 | 29 | 0.9347431316 |
| 10 | 0.7729182527 | 20 | 0.901628642 | 30 | 0.9370935844 |

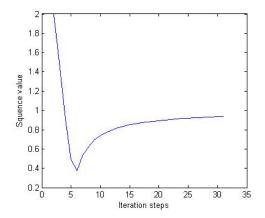


Figure 2: The graph of $\{x_n\}$ with initial value $x_1 = 2$.

References

- [1] E. Blum and W. Oettli, From optimization and variational inequalities to equilibrium problems, Journal of Mathematical Study 63 (1994) 123–145.
- [2] T. Chamnarnapan and P. Kummam, Iterative algorithms for solving the system of mixed equilibrium problems, fixed point problems, and variational inclusions with application to minimization problem, Journal of Applied Mathematics (2012) Article ID. 538912, 29 pages.
- [3] M. G. Crandall and P. L. Lions, Viscosity solution of Hamilton-Jacobi equations, Transactions of the American Mathematical Society 277 (1983) 1–42.

- [4] F. Cianciaruso, G. Marini and L. Muglia, Iterative methods for equilibrium and fixed point problems for nonexpansive semigroups in Hilbert spaces, Journal of Optimization Theory and Applications 146 (2010) 491–509.
- [5] A. L. Dontchev and T. Zolezzi, Well-posed optimization problems, Lecture Notes in Mathematics 1543 (1993) Springer-Verlag.
- [6] C. Jaiboon and P. Kumam, Viscosity approximation method forsystem of variational inclusions problems and fixed point problems of a countablefamily of nonexpansive mappings, Journal of Applied Mathematics 2012 (2012) Article ID 816529, 26 pages...
- [7] T. Jitpeera, P. Kachang and P. Kumam, A viscosity of Ceasaro mean approximation methods for a mixed equilibrium, varational inequalities, and fixed point problems, Fixed Point Theory and Applications (2011) Article ID. 945051, 24 pages.
- [8] J. Kang, Y. Su and X. Zhang, Genaral iterative algorithm for nonexpansive semigroups and variational inequalitis in Hilbert space, Journal of Inequalities and Applications (2010) Article ID.264052, 10 pages.
- [9] P. Katchang, Y. Khamlae and P. Kumam, A viscosity iterative scheme for inverse-strongly accretive operators in Banach spaces, Journal of Computational Analysis and Applications 12 (2010) No.3, 678–686.
- [10] R. V. Kohn and P. Sternberg, Local minimizers and singular perturbations, Proc. Royal Soc. Edinburgh, Sect A 111 (1989) 64–84.
- [11] P. Kumam and S. Plubtieng, Viscosity approximation methods for monotone mappings and a countable family of nonexpansive mappings, Mathematica Slovaca 61 (2) (2011) 257–274.
- [12] O. A. Ladyzenskaya and N. N. Uralceva, Local estimates for gradients of solutions of uniformly elliptic and parabolic equations, Communications on Pure and Applied Mathematics 18 (1970) 677–703.
- [13] S. Li , L. Li and Y. Su, General iterative methods for a one-parameter nonexpansive semigoup in Hibert space, Journal of Mathematical Analysis and Applications 70 (2009) 3065–3071.
- [14] J. L. Lions, Quelques methodes de resolution des probl'emes aux limites nonlineaires, Dunod et Gauthiers-Villars, Paris, 1969.
- [15] G. Marino and H. K. Xu, A general iterative methods for nonexpansive mappings in Hilbert spaces, Journal of Mathematical Analysis and Applications 318 (2006) 43–52.
- [16] M. O. Oslike and D. I. Igbokwe, Weak and strong convergence theorems for fixed points of pseudocontractions and solutions of monotone type operators equations, Computers & Mathematics with Applications 40 (2000) No.4-5, 559–567.
- [17] J. W. Peng and J. C. Yao, Strong convergence theorems of itareative scheme based on the extragardient method for mixed equilibrium problems and fixed point problems, Mathematical and Computer Modelling 49 (2009) No.9-10, 1816-1828.
- [18] S. Plubtieng and R. Punpaeng, A general iterative for equilibrium problems and fixed point problems in Hilbert spaces, Journal of Mathematical Analysis and Applications 336 (2007) 455–469.
- [19] R. T. Rockafellar, On the maximality of sums of nonlinear monotoe operators, Transactions of the American Mathematical Society 149 (1970) 75–88.
- [20] K. Sitthithakerngkiet, J. Deepho and P. Kumam, A hybrid viscosity algorithm via modify the hybrid steepest descent method for sloving the split variational inclusion and fixed point problems, Applied Mathematics and Computation 250 (2015) 986–1001.
- [21] P. Sunthrayuth and P. Kumam, Viscosity approximation methods base on generalized contraction mappings for a countable family of strict pseudo-contractions, a general system of variational inequalities and a generalized mixed equilibrium problem in Banach spaces, Mathematical and Computer Modelling 58 (2013) No. 11-12, 1814–1828.
- [22] T. Suzuki. Strong convergence of Krasnoselkii and Mann's type sequences for one-parameter nonexpansive semigroups without Bochner integrals. Journal of Mathematical Analysis and Applications 305 (2005) 227–239.
- [23] A. Tychonov, Solution of incorrectly formulated problems and the regularization method, Soviet Mathematics Dokady 4 (1963) 1035–1038.
- [24] U. Witthayarat, T. Jitpeera and P. Kumam, A new modified hybrid steepest-descent by using a viscosity approximation method with a weakly contractive mapping for A system of equilibrium problems and fixed point problems with minimization problems, Abstract and Applied Analysis 2012 (2012) Article ID 206345, 29 pages.
- [25] U. Witthayarat, J. K. Kim and P. Kumam, A viscosity hybrid steepest-descent methods for a system of equilibrium problems and fixed point for an infinitefamily of strictly pseudo-contractive mappings, Journal of Inequalities and Applications 2012 (2012), 2012:224.
- [26] H. K. Xu, An iterative approach to quadratic optimization, Journal of Optimization Theory and Applications 116 (2003) 659–678.