



Monotone Relations in Hadamard Spaces

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Abstract. In this paper, the notion of \mathcal{W} -property for subsets of $X \times X^\diamond$ is introduced and investigated, where X is an Hadamard space and X^\diamond is its linear dual space. It is shown that an Hadamard space X is flat if and only if $X \times X^\diamond$ has \mathcal{W} -property. Moreover, the notion of monotone relation from an Hadamard space to its linear dual space is introduced. A characterization result for monotone relations with \mathcal{W} -property (and hence in flat Hadamard spaces) is given. Finally, a type of Debrunner-Flor Lemma concerning extension of monotone relations in Hadamard spaces is proved.

1. Introduction and Preliminaries

Let (X, d) be a metric space. We say that a mapping $c : [0, 1] \rightarrow X$ is a *geodesic path* from $x \in X$ to $y \in X$ if $c(0) = x$, $c(1) = y$ and $d(c(t), c(s)) = |t - s|d(x, y)$, for each $t, s \in [0, 1]$. The image of c is said to be a *geodesic segment* joining x and y . A metric space (X, d) is called a *geodesic space* if there is a geodesic path between every two points of X . Also, a geodesic space X is called *uniquely geodesic space* if for each $x, y \in X$ there exists a unique geodesic path from x to y . From now on, in a uniquely geodesic space, we denote the set $c([0, 1])$ by $[x, y]$ and for each $z \in [x, y]$, we write $z = (1 - t)x \oplus ty$, where $t \in [0, 1]$. In this case, we say that z is a *convex combination* of x and y . Hence, $[x, y] = \{(1 - t)x \oplus ty : t \in [0, 1]\}$. More details can be found in [3, 5].

Definition 1.1. [9, Definition 2.2] Let (X, d) be a geodesic space, $v_1, v_2, v_3, \dots, v_n$ be n points in X and $\{\lambda_1, \lambda_2, \lambda_3, \dots, \lambda_n\} \subseteq (0, 1)$ be such that $\sum_{i=1}^n \lambda_i = 1$. We define *convex combination* of $\{v_1, v_2, v_3, \dots, v_n\}$ inductively as following:

$$\bigoplus_{i=1}^n \lambda_i v_i := (1 - \lambda_n) \left(\frac{\lambda_1}{1 - \lambda_n} v_1 \oplus \frac{\lambda_2}{1 - \lambda_n} v_2 \oplus \dots \oplus \frac{\lambda_{n-1}}{1 - \lambda_n} v_{n-1} \right) \oplus \lambda_n v_n. \quad (1)$$

Note that for every $x \in X$, we have $d(x, \bigoplus_{i=1}^n \lambda_i v_i) \leq \sum_{i=1}^n \lambda_i d(x, v_i)$.

According to [3, Definition 1.2.1], a geodesic space (X, d) is a *CAT(0) space*, if the following condition, so-called *CN-inequality*, holds:

$$d(z, (1 - \lambda)x \oplus \lambda y)^2 \leq (1 - \lambda)d(z, x)^2 + \lambda d(z, y)^2 - \lambda(1 - \lambda)d(x, y)^2 \text{ for all } x, y, z \in X, \lambda \in [0, 1]. \quad (2)$$

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One can show that (for instance see [3, Theorem 1.3.3]) CAT(0) spaces are uniquely geodesic spaces. An Hadamard space is a complete CAT(0) space.

Let X be an Hadamard space. For each $x, y \in X$, the ordered pair (x, y) is called a *bound vector* and is denoted by \vec{xy} . Indeed, $X^2 = \{\vec{xy} : x, y \in X\}$. For each $x \in X$, we apply $\vec{0}_x := \vec{xx}$ as *zero bound vector* at x and $-\vec{xy}$ as the bound vector \vec{yx} . The bound vectors \vec{xy} and \vec{uz} are called *admissible* if $y = u$. Therefore the sum of two admissible bound vectors \vec{xy} and \vec{yz} is defined by $\vec{xy} + \vec{yz} = \vec{xz}$. Ahmadi Kakavandi and Amini in [2] have introduced the *dual space* of an Hadamard space, by using the concept of quasilinearization of abstract metric spaces presented by Berg and Nikolaev in [4]. The *quasilinearization map* is defined as following:

$$\begin{aligned} \langle \cdot, \cdot \rangle : X^2 \times X^2 &\rightarrow \mathbb{R} \\ \langle \vec{ab}, \vec{cd} \rangle &:= \frac{1}{2} \{d(a, d)^2 + d(b, c)^2 - d(a, c)^2 - d(b, d)^2\}; \quad a, b, c, d \in X. \end{aligned} \tag{3}$$

Let $x, y \in X$, we define the mapping $\varphi_{\vec{xy}} : X \rightarrow \mathbb{R}$ by $\varphi_{\vec{xy}}(z) = \frac{1}{2}(d(x, z)^2 - d(y, z)^2)$; for each $z \in X$. We will see that $\varphi_{\vec{xy}}$ possess attractive properties that simplify some calculations. We observe that (3) can be rewritten as following:

$$\langle \vec{ab}, \vec{cd} \rangle = \varphi_{\vec{cd}}(b) - \varphi_{\vec{cd}}(a) = \varphi_{\vec{ab}}(d) - \varphi_{\vec{ab}}(c).$$

The metric space (X, d) satisfies the *Cauchy-Schwarz inequality* if

$$\langle \vec{ab}, \vec{cd} \rangle \leq d(a, b)d(c, d) \quad \text{for all } a, b, c, d \in X.$$

This inequality characterizes CAT(0) spaces. Indeed, it follows from [4, Corollary 3] that a geodesic space (X, d) is a CAT(0) space if and only if it satisfies in the Cauchy-Schwarz inequality. For an Hadamard space (X, d) , consider the mapping

$$\begin{aligned} \Psi : \mathbb{R} \times X^2 &\rightarrow C(X, \mathbb{R}) \\ (t, a, b) &\mapsto \Psi(t, a, b)x = t \langle \vec{ab}, \vec{ax} \rangle; \quad a, b, x \in X, t \in \mathbb{R}, \end{aligned}$$

where $C(X, \mathbb{R})$ denotes the space of all continuous real-valued functions on X . It follows from Cauchy-Schwarz inequality that $\Psi(t, a, b)$ is a Lipschitz function with Lipschitz semi-norm

$$L(\Psi(t, a, b)) = |t|d(a, b), \quad \text{for all } a, b \in X, \text{ and all } t \in \mathbb{R}, \tag{4}$$

where the *Lipschitz semi-norm* for any function $\varphi : (X, d) \rightarrow \mathbb{R}$ is defined by

$$L(\varphi) = \sup \left\{ \frac{\varphi(x) - \varphi(y)}{d(x, y)} : x, y \in X, x \neq y \right\}.$$

A *pseudometric* D on $\mathbb{R} \times X^2$ induced by the Lipschitz semi-norm (4), is defined by

$$D((t, a, b), (s, c, d)) = L(\Psi(t, a, b) - \Psi(s, c, d)); \quad a, b, c, d \in X, t, s \in \mathbb{R}.$$

For an Hadamard space (X, d) , the pseudometric space $(\mathbb{R} \times X^2, D)$ can be considered as a subspace of the pseudometric space of all real-valued Lipschitz functions $\text{Lip}(X, \mathbb{R})$. Note that, in view of [2, Lemma 2.1], $D((t, a, b), (s, c, d)) = 0$ if and only if $t \langle \vec{ab}, \vec{xy} \rangle = s \langle \vec{cd}, \vec{xy} \rangle$ for all $x, y \in X$. Thus, D induces an equivalence relation on $\mathbb{R} \times X^2$, where the equivalence class of $(t, a, b) \in \mathbb{R} \times X^2$ is

$$[\vec{tab}] = \{ \vec{scd} : s \in \mathbb{R}, c, d \in X, D((t, a, b), (s, c, d)) = 0 \}.$$

The *dual space* of an Hadamard space (X, d) , denoted by X^* , is the set of all equivalence classes $[\vec{tab}]$ where $(t, a, b) \in \mathbb{R} \times X^2$, with the metric $D([\vec{tab}], [\vec{scd}]) := D((t, a, b), (s, c, d))$. Clearly, the definition of equivalence

classes implies that $[\vec{aa}] = [\vec{bb}]$ for all $a, b \in X$. The zero element of X^* is $\mathbf{0} := [\vec{taa}]$, where $a \in X$ and $t \in \mathbb{R}$ are arbitrary. It is easy to see that the evaluation $\langle \mathbf{0}, \cdot \rangle$ vanishes for any bound vectors in X^2 . Note that in general X^* acts on X^2 by

$$\langle x^*, \vec{xy} \rangle = t \langle \vec{ab}, \vec{xy} \rangle, \text{ where } x^* = [\vec{tab}] \in X^* \text{ and } \vec{xy} \in X^2.$$

The following notation will be used throughout this paper.

$$\left\langle \sum_{i=1}^n \alpha_i x_i^*, \vec{xy} \right\rangle := \sum_{i=1}^n \alpha_i \langle x_i^*, \vec{xy} \rangle, \alpha_i \in \mathbb{R}, x_i^* \in X^*, n \in \mathbb{N}, x, y \in X.$$

For an Hadamard space (X, d) , Chaipunya and Kumam in [7], defined the linear dual space of X by

$$X^\circ = \left\{ \sum_{i=1}^n \alpha_i x_i^* : \alpha_i \in \mathbb{R}, x_i^* \in X^*, n \in \mathbb{N} \right\}.$$

Therefore, $X^\circ = \text{span } X^*$. It is easy to see that X° is a normed space with the norm $\|x^\circ\|_0 = L(x^\circ)$ for all $x^\circ \in X^\circ$. Indeed:

Lemma 1.2. [14, Proposition 3.5] *Let X be an Hadamard space with linear dual space X° . Then*

$$\|x^\circ\|_0 := \sup \left\{ \frac{|\langle x^\circ, \vec{ab} \rangle - \langle x^\circ, \vec{cd} \rangle|}{d(a, b) + d(c, d)} : a, b, c, d \in X, (a, c) \neq (b, d) \right\},$$

is a norm on X° . In particular, $\|[\vec{tab}]\|_0 = |t|d(a, b)$.

2. Flat Hadamard Spaces and \mathcal{W} -property

Let M be a relation from X to X° ; i.e., $M \subseteq X \times X^\circ$. The domain and range of M are defined, respectively, by

$$\text{Dom}(M) := \{x \in X : \exists x^\circ \in X^\circ \text{ such that } (x, x^\circ) \in M\},$$

and

$$\text{Range}(M) := \{x^\circ \in X^\circ : \exists x \in X \text{ such that } (x, x^\circ) \in M\}.$$

Definition 2.1. Let X be an Hadamard space with linear dual space X° . We say that $M \subseteq X \times X^\circ$ satisfies \mathcal{W} -property if there exists $p \in X$ such that the following holds:

$$\langle x^\circ, \overline{p((1-\lambda)x_1 \oplus \lambda x_2)} \rangle \leq (1-\lambda)\langle x^\circ, \overline{px_1} \rangle + \lambda\langle x^\circ, \overline{px_2} \rangle, \forall \lambda \in [0, 1], \forall x^\circ \in \text{Range}(M), \forall x_1, x_2 \in \text{Dom}(M).$$

Proposition 2.2. Let X be an Hadamard space with linear dual space X° and let $M \subseteq X \times X^\circ$. Then the following statements are equivalent:

- (i) $M \subseteq X \times X^\circ$ satisfies the \mathcal{W} -property for some $p \in X$.
- (ii) $M \subseteq X \times X^\circ$ satisfies the \mathcal{W} -property for any $q \in X$.
- (iii) For any $q \in X$,

$$\langle x^\circ, \overline{q(\oplus_{i=1}^n \lambda_i x_i)} \rangle \leq \sum_{i=1}^n \lambda_i \langle x^\circ, \overline{qx_i} \rangle, \text{ for all } x^\circ \in \text{Range}(M), \{x_i\}_{i=1}^n \subseteq \text{Dom}(M), \{\lambda_i\}_{i=1}^n \subseteq [0, 1]. \quad (\mathcal{W}_n(q))$$

(iv) For some $p \in X$, $(\mathcal{W}_n(p))$ holds.

Proof.

(i) \Rightarrow (ii): Let $q \in X$ be any arbitrary element of X , $\lambda \in [0, 1]$, $x^\circ \in \text{Range}(M)$, and $x_1, x_2 \in \text{Dom}(M)$. Then

$$\begin{aligned} \langle x^\circ, \overrightarrow{q((1-\lambda)x_1 \oplus \lambda x_2)} \rangle &= \langle x^\circ, \overrightarrow{q\vec{p} + p((1-\lambda)x_1 \oplus \lambda x_2)} \rangle \\ &= \langle x^\circ, \overrightarrow{q\vec{p}} \rangle + \langle x^\circ, \overrightarrow{p((1-\lambda)x_1 \oplus \lambda x_2)} \rangle \\ &\leq (1-\lambda)(\langle x^\circ, \overrightarrow{q\vec{p}} \rangle + \langle x^\circ, \overrightarrow{px_1} \rangle) + \lambda(\langle x^\circ, \overrightarrow{q\vec{p}} \rangle + \langle x^\circ, \overrightarrow{px_2} \rangle) \\ &= (1-\lambda)\langle x^\circ, \overrightarrow{q\vec{p} + px_1} \rangle + \lambda\langle x^\circ, \overrightarrow{q\vec{p} + px_2} \rangle \\ &= (1-\lambda)\langle x^\circ, \overrightarrow{qx_1} \rangle + \lambda\langle x^\circ, \overrightarrow{qx_2} \rangle, \end{aligned}$$

as required.

(ii) \Rightarrow (iii): We proceed by induction on n . By Definition 2.1 the claim is true for $n = 2$. Now assume that $(\mathcal{W}_{n-1}(q))$ is true. In view of equation (1),

$$\begin{aligned} \langle x^\circ, \overrightarrow{q(\oplus_{i=1}^n \lambda_i x_i)} \rangle &= \overrightarrow{\langle x^\circ, q((1-\lambda_n)(\frac{\lambda_1}{1-\lambda_n}x_1 \oplus \frac{\lambda_2}{1-\lambda_n}x_2 \oplus \dots \oplus \frac{\lambda_{n-1}}{1-\lambda_n}x_{n-1}) \oplus \lambda_n x_n) \rangle} \\ &\leq (1-\lambda_n)\langle x^\circ, \overrightarrow{q(\frac{\lambda_1}{1-\lambda_n}x_1 \oplus \frac{\lambda_2}{1-\lambda_n}x_2 \oplus \dots \oplus \frac{\lambda_{n-1}}{1-\lambda_n}x_{n-1})} \rangle + \lambda_n\langle x^\circ, \overrightarrow{qx_n} \rangle \\ &\leq (1-\lambda_n) \sum_{i=1}^{n-1} \frac{\lambda_i}{1-\lambda_n} \langle x^\circ, \overrightarrow{qx_i} \rangle + \lambda_n\langle x^\circ, \overrightarrow{qx_n} \rangle \\ &= \sum_{i=1}^{n-1} \lambda_i \langle x^\circ, \overrightarrow{qx_i} \rangle + \lambda_n\langle x^\circ, \overrightarrow{qx_n} \rangle \\ &= \sum_{i=1}^n \lambda_i \langle x^\circ, \overrightarrow{qx_i} \rangle. \end{aligned}$$

(iii) \Rightarrow (iv): Clear.

(iv) \Rightarrow (i): Take $n = 2$ in $(\mathcal{W}_n(p))$.

We are done. \square

Remark 2.3. It should be noticed that Proposition 2.2 implies that \mathcal{W} -property is independent of the choice of the element $p \in X$.

Definition 2.4. [11, Definition 3.1] An Hadamard space (X, d) is said to be flat if equality holds in the CN-inequality, i.e., for each $x, y \in X$ and $\lambda \in [0, 1]$, the following holds:

$$d(z, (1-\lambda)x \oplus \lambda y)^2 = (1-\lambda)d(z, x)^2 + \lambda d(z, y)^2 - \lambda(1-\lambda)d(x, y)^2, \text{ for all } z \in X.$$

Proposition 2.5. Let X be an Hadamard space. The following statements are equivalent:

(i) X is a flat Hadamard space.

(ii) $\langle x((1-\lambda)x \oplus \lambda y), \overrightarrow{ab} \rangle = \lambda \langle \overrightarrow{xy}, \overrightarrow{ab} \rangle$, for all $a, b, x, y \in X$ and all $\lambda \in [0, 1]$.

(iii) $X \times X^\circ$ has \mathcal{W} -property.

(iv) Any subset of $X \times X^\circ$ has \mathcal{W} -property.

(v) For each $p, z \in X$, the mapping $\varphi_{\vec{p}\vec{z}}$ is convex.

(vi) For each $p, z \in X$, the mapping $\varphi_{\vec{p}\vec{z}}$ is affine, in the sense that:

$$\varphi_{\vec{p}\vec{z}}((1 - \lambda)x \oplus \lambda y) = (1 - \lambda)\varphi_{\vec{p}\vec{z}}(x) + \lambda\varphi_{\vec{p}\vec{z}}(y), \quad \forall x, y \in X, \forall \lambda \in [0, 1].$$

Proof.

(i) \Leftrightarrow (ii): [11, Theorem 3.2].

(ii) \Rightarrow (iii): Let $x, y \in X, \lambda \in [0, 1]$ and $(x, x^\circ) \in X \times X^\circ$. Then $x^\circ = \sum_{i=1}^n \alpha_i [t_i \vec{a}_i \vec{b}_i] \in X^\circ$, and hence by using (ii) we get:

$$\begin{aligned} \langle x^\circ, \overrightarrow{p((1 - \lambda)x \oplus \lambda y)} \rangle &= \sum_{i=1}^n \alpha_i t_i \langle \vec{a}_i \vec{b}_i, \vec{p}\vec{x} + \overrightarrow{x((1 - \lambda)x \oplus \lambda y)} \rangle \\ &= \sum_{i=1}^n \alpha_i t_i (\langle \vec{a}_i \vec{b}_i, \vec{p}\vec{x} \rangle + \langle \vec{a}_i \vec{b}_i, \overrightarrow{x((1 - \lambda)x \oplus \lambda y)} \rangle) \\ &= \sum_{i=1}^n \alpha_i t_i (\langle \vec{a}_i \vec{b}_i, \vec{p}\vec{x} \rangle + \lambda \langle \vec{a}_i \vec{b}_i, \vec{x}\vec{y} \rangle) \\ &= \sum_{i=1}^n \alpha_i t_i (\langle \vec{a}_i \vec{b}_i, \vec{p}\vec{x} \rangle + \lambda \langle \vec{a}_i \vec{b}_i, \vec{p}\vec{y} - \vec{p}\vec{x} \rangle) \\ &= \sum_{i=1}^n \alpha_i t_i ((1 - \lambda) \langle \vec{a}_i \vec{b}_i, \vec{p}\vec{x} \rangle + \lambda \langle \vec{a}_i \vec{b}_i, \vec{p}\vec{y} \rangle) \\ &= (1 - \lambda) \sum_{i=1}^n \alpha_i t_i \langle \vec{a}_i \vec{b}_i, \vec{p}\vec{x} \rangle + \lambda \sum_{i=1}^n \alpha_i t_i \langle \vec{a}_i \vec{b}_i, \vec{p}\vec{y} \rangle \\ &= (1 - \lambda) \langle \sum_{i=1}^n \alpha_i [t_i \vec{a}_i \vec{b}_i], \vec{p}\vec{x} \rangle + \lambda \langle \sum_{i=1}^n \alpha_i [t_i \vec{a}_i \vec{b}_i], \vec{p}\vec{y} \rangle \\ &= (1 - \lambda) \langle x^\circ, \vec{p}\vec{x} \rangle + \lambda \langle x^\circ, \vec{p}\vec{y} \rangle. \end{aligned}$$

Therefore $X \times X^\circ$ has \mathcal{W} -property.

(iii) \Leftrightarrow (iv): Straightforward.

(iv) \Rightarrow (v): Let $x, y \in X$ and $\lambda \in [0, 1]$, then

$$\begin{aligned} (1 - \lambda)\varphi_{\vec{p}\vec{z}}(x) + \lambda\varphi_{\vec{p}\vec{z}}(y) - \varphi_{\vec{p}\vec{z}}((1 - \lambda)x \oplus \lambda y) &= \lambda(\varphi_{\vec{p}\vec{z}}(y) - \varphi_{\vec{p}\vec{z}}(x)) + \varphi_{\vec{p}\vec{z}}(x) - \varphi_{\vec{p}\vec{z}}((1 - \lambda)x \oplus \lambda y) \\ &= \lambda \langle \vec{p}\vec{z}, \vec{x}\vec{y} \rangle + \langle \vec{p}\vec{z}, \overrightarrow{((1 - \lambda)x \oplus \lambda y)x} \rangle \\ &= \lambda \langle \vec{p}\vec{z}, \vec{p}\vec{y} - \vec{p}\vec{x} \rangle + \langle \vec{p}\vec{z}, \vec{p}\vec{x} - \overrightarrow{p((1 - \lambda)x \oplus \lambda y)} \rangle \\ &= \lambda \langle \vec{p}\vec{z}, \vec{p}\vec{y} \rangle + (1 - \lambda) \langle \vec{p}\vec{z}, \vec{p}\vec{x} \rangle - \langle \vec{p}\vec{z}, \overrightarrow{p((1 - \lambda)x \oplus \lambda y)} \rangle \\ &\geq 0. \end{aligned}$$

Therefore, $\varphi_{\vec{p}\vec{z}}$ is convex.

(v) \Rightarrow (vi): It is easy.

(vi) \Rightarrow (iii): Let $x, y, p \in X$, $\lambda \in [0, 1]$ and $x^\circ = \sum_{i=1}^n \alpha_i [t_i \overrightarrow{p_i z_i}] \in X^\circ$ be given. Then

$$\begin{aligned} \langle \overrightarrow{x^\circ, p((1-\lambda)x \oplus \lambda y)} \rangle &= \left\langle \sum_{i=1}^n \alpha_i x_i^*, \overrightarrow{p((1-\lambda)x \oplus \lambda y)} \right\rangle \\ &= \sum_{i=1}^n \alpha_i t_i \langle \overrightarrow{p_i z_i}, \overrightarrow{p((1-\lambda)x \oplus \lambda y)} \rangle \\ &= \sum_{i=1}^n \alpha_i t_i (\varphi_{\overrightarrow{p_i z_i}}((1-\lambda)x \oplus \lambda y) - \varphi_{\overrightarrow{p_i z_i}}(p)) \\ &= \sum_{i=1}^n \alpha_i t_i ((1-\lambda)\varphi_{\overrightarrow{p_i z_i}}(x) + \lambda\varphi_{\overrightarrow{p_i z_i}}(y) - \varphi_{\overrightarrow{p_i z_i}}(p)) \\ &= \sum_{i=1}^n \alpha_i t_i ((1-\lambda)(\varphi_{\overrightarrow{p_i z_i}}(x) - \varphi_{\overrightarrow{p_i z_i}}(p)) + \lambda(\varphi_{\overrightarrow{p_i z_i}}(y) - \varphi_{\overrightarrow{p_i z_i}}(p))) \\ &= \sum_{i=1}^n \alpha_i t_i ((1-\lambda)\langle \overrightarrow{p_i z_i}, \overrightarrow{p x} \rangle + \lambda\langle \overrightarrow{p_i z_i}, \overrightarrow{p y} \rangle) \\ &= (1-\lambda) \sum_{i=1}^n \alpha_i t_i \langle \overrightarrow{p_i z_i}, \overrightarrow{p x} \rangle + \lambda \sum_{i=1}^n \alpha_i t_i \langle \overrightarrow{p_i z_i}, \overrightarrow{p y} \rangle \\ &= (1-\lambda) \left\langle \sum_{i=1}^n \alpha_i [t_i \overrightarrow{p_i z_i}], \overrightarrow{p x} \right\rangle + \lambda \left\langle \sum_{i=1}^n \alpha_i [t_i \overrightarrow{p_i z_i}], \overrightarrow{p y} \right\rangle \\ &= (1-\lambda)\langle x^\circ, \overrightarrow{p x} \rangle + \lambda\langle x^\circ, \overrightarrow{p y} \rangle; \end{aligned}$$

i.e., $X \times X^\circ$ has \mathcal{W} -property.

(iii) \Rightarrow (ii): For $a, b, x, y \in X$ and $\lambda \in [0, 1]$, we have:

$$\begin{aligned} \lambda \langle \overrightarrow{ab}, \overrightarrow{xy} \rangle - \langle \overrightarrow{ab}, \overrightarrow{x((1-\lambda)x \oplus \lambda y)} \rangle &= \lambda (\langle \overrightarrow{ab}, \overrightarrow{p y} - \overrightarrow{p x} \rangle) - \langle \overrightarrow{ab}, \overrightarrow{p((1-\lambda)x \oplus \lambda y)} - \overrightarrow{p x} \rangle \\ &= \lambda (\langle \overrightarrow{ab}, \overrightarrow{p y} \rangle - \langle \overrightarrow{ab}, \overrightarrow{p x} \rangle) - \langle \overrightarrow{ab}, \overrightarrow{p((1-\lambda)x \oplus \lambda y)} \rangle + \langle \overrightarrow{ab}, \overrightarrow{p x} \rangle \\ &= (1-\lambda)\langle \overrightarrow{ab}, \overrightarrow{p x} \rangle + \lambda\langle \overrightarrow{ab}, \overrightarrow{p y} \rangle - \langle \overrightarrow{ab}, \overrightarrow{p((1-\lambda)x \oplus \lambda y)} \rangle \\ &= (1-\lambda)\langle x^\circ, \overrightarrow{p x} \rangle + \lambda\langle x^\circ, \overrightarrow{p y} \rangle - \langle x^\circ, \overrightarrow{p((1-\lambda)x \oplus \lambda y)} \rangle, \end{aligned}$$

where $x^\circ = [\overrightarrow{ab}] \in X^\circ$. Since $X \times X^\circ$ has \mathcal{W} -property, one can deduce that:

$$\lambda \langle \overrightarrow{ab}, \overrightarrow{xy} \rangle \geq \langle \overrightarrow{ab}, \overrightarrow{x((1-\lambda)x \oplus \lambda y)} \rangle. \tag{5}$$

Hence, by interchanging the role of a and b in (5), we obtain:

$$\langle \overrightarrow{ab}, \overrightarrow{x((1-\lambda)x \oplus \lambda y)} \rangle \geq \lambda \langle \overrightarrow{ab}, \overrightarrow{xy} \rangle. \tag{6}$$

Finally, (5) and (6) yield:

$$\langle \overrightarrow{ab}, \overrightarrow{p((1-\lambda)x \oplus \lambda y)} \rangle = \lambda \langle \overrightarrow{ab}, \overrightarrow{xy} \rangle.$$

We are done. \square

The next example shows that there exists a relation $M \subseteq X \times X^\circ$ in the non-flat Hadamard spaces which doesn't have the \mathcal{W} -property.

Example 2.6. Consider the following equivalence relation on $\mathbb{N} \times [0, 1]$:

$$(n, t) \sim (m, s) \Leftrightarrow t = s = 0 \text{ or } (n, t) = (m, s).$$

Set $X := \frac{\mathbb{N} \times [0, 1]}{\sim}$ and let $d : X \times X \rightarrow \mathbb{R}$ be defined by

$$d([(n, t)], [(m, s)]) = \begin{cases} |t - s| & n = m, \\ t + s & n \neq m. \end{cases}$$

The geodesic joining $x = [(n, t)]$ to $y = [(m, s)]$ is defined as follows:

$$(1 - \lambda)x \oplus \lambda y := \begin{cases} [(n, (1 - \lambda)t - \lambda s)] & 0 \leq \lambda \leq \frac{t}{t+s}, \\ [(m, (\lambda - 1)t + \lambda s)] & \frac{t}{t+s} \leq \lambda \leq 1, \end{cases}$$

whenever $x \neq y$ and vacuously $(1 - \lambda)x \oplus \lambda x := x$. It is known that (see [1, Example 4.7]) (X, d) is an \mathbb{R} -tree space. It follows from [3, Example 1.2.10], that any \mathbb{R} -tree space is an Hadamard space. Let $x = [(2, \frac{1}{2})]$, $y = [(1, \frac{1}{2})]$, $a = [(3, \frac{1}{3})]$, $b = [(2, \frac{1}{2})]$ and $\lambda = \frac{1}{5}$. Then $\frac{4}{5}x \oplus \frac{1}{5}y = [(2, \frac{3}{10})]$ and

$$\left\langle \overrightarrow{x(\frac{4}{5}x \oplus \frac{1}{5}y), \overrightarrow{ab}} \right\rangle = \frac{-1}{6} \neq \frac{-1}{10} = \frac{1}{5} \left\langle \overrightarrow{xy}, \overrightarrow{ab} \right\rangle.$$

Now, Proposition 2.5(ii) implies that (X, d) is not a flat Hadamard space. For each $n \in \mathbb{N}$, set $x_n := [(n, \frac{1}{2})]$ and $y_n := [(n, \frac{1}{n})]$. Now, we define

$$M := \{(x_n, \overrightarrow{y_{n+1}y_n}) : n \in \mathbb{N}\} \subseteq X \times X^\circ.$$

Take $p = [(1, 1)] \in X$, $\overrightarrow{y_5y_4} \in \text{Range}(M)$ and $\lambda = \frac{1}{3}$. Clearly, $\tilde{x} := (1 - \lambda)x_1 \oplus \lambda x_3 = [(1, \frac{1}{6})]$ and $\langle \overrightarrow{[y_5y_4]}, \overrightarrow{p\tilde{x}} \rangle = \frac{1}{24}$, while,

$$\frac{2}{3} \langle \overrightarrow{[y_5y_4]}, \overrightarrow{px_1} \rangle + \frac{1}{3} \langle \overrightarrow{[y_5y_4]}, \overrightarrow{px_3} \rangle = \frac{1}{40}.$$

Therefore, M doesn't have the \mathcal{W} -property.

3. Monotone Relations

Ahmadi Kakavandi and Amini [2] introduced the notion of monotone operators in Hadamard spaces. In [10], Khatibzadeh and Ranjbar, investigated some properties of monotone operators and their resolvents and also proximal point algorithm in Hadamard spaces. Chaipunya and Kumam [7] studied the general proximal point method for finding a zero point of a maximal monotone set-valued vector field defined on Hadamard spaces. They proved the relation between the maximality and Minty's surjectivity condition. Zamani Eskandani and Raeisi [14], by using products of finitely many resolvents of monotone operators, proposed an iterative algorithm for finding a common zero of a finite family of monotone operators and a common fixed point of an infinitely countable family of non-expansive mappings in Hadamard spaces. In this section, we will characterize the notation of monotone relations in Hadamard spaces based on characterization of monotone sets in Banach spaces [8, 12, 13].

Definition 3.1. Let X be an Hadamard space with linear dual space X° . The set $M \subseteq X \times X^\circ$ is called *monotone* if $\langle x^\circ - y^\circ, \overrightarrow{yx} \rangle \geq 0$, for all $(x, x^\circ), (y, y^\circ)$ in M .

Example 3.2. Let x_n, y_n and M be the same as in Example 2.6. Let $(u, u^\circ), (v, v^\circ) \in M$. There exists $m, n \in \mathbb{N}$ such that $u = x_n, u^\circ := [\overrightarrow{y_{n+1}y_n}], v = x_m$ and $v^\circ := [\overrightarrow{y_{m+1}y_m}]$. Then

$$\begin{aligned} \langle u^\circ - v^\circ, \overrightarrow{vu} \rangle &= \langle u^\circ, \overrightarrow{vu} \rangle - \langle v^\circ, \overrightarrow{vu} \rangle = \overrightarrow{\langle [\overrightarrow{[(n+1, \frac{1}{n+1})][\overrightarrow{(n, \frac{1}{n})}]]}, [\overrightarrow{(m, \frac{1}{2})}][\overrightarrow{(n, \frac{1}{2})}] \rangle} \\ &\quad - \overrightarrow{\langle [\overrightarrow{[(m+1, \frac{1}{m+1})][\overrightarrow{(m, \frac{1}{m})}]]}, [\overrightarrow{(m, \frac{1}{2})}][\overrightarrow{(n, \frac{1}{2})}] \rangle} \\ &= \begin{cases} 0, & n = m, \\ \frac{1}{m+1} + \frac{1}{n} + \frac{1}{m}, & n = m + 1, \\ \frac{1}{n+1} + \frac{1}{n} + \frac{1}{m}, & n = m - 1, \\ \frac{1}{n} + \frac{1}{m}, & n \notin \{m - 1, m, m + 1\}. \end{cases} \end{aligned}$$

Therefore, $\langle u^\circ - v^\circ, \overrightarrow{vu} \rangle \geq 0$ which shows that, M is a monotone relation.

In the sequel, we need the following notations. Let X be an Hadamard space and $Y \subseteq X$. Put

$$\zeta_Y := \left\{ \eta : Y \rightarrow [0, +\infty[\mid \text{supp } \eta \text{ is finite and } \sum_{x \in Y} \eta(x) = 1 \right\}$$

where $\text{supp } \eta = \{y \in Y : \eta(y) \neq 0\}$. Clearly, for each $\emptyset \neq A \subseteq Y, \zeta_A = \{\eta \in \zeta_Y : \text{supp } \eta \subseteq A\}$. It is obvious that ζ_A is a convex subset of \mathbb{R}^Y . Moreover, if $\emptyset \neq A \subseteq B$, then $\zeta_A \subseteq \zeta_B$. Suppose $u \in Y$ be fixed. Define $\delta_u \in \zeta_Y$ by

$$\delta_u(x) = \begin{cases} 1 & x = u, \\ 0 & x \neq u. \end{cases}$$

Let $M \subseteq X \times X^\circ$ and $\eta \in \zeta_A$. Then $\text{supp } \eta = \{\lambda_1, \dots, \lambda_n\}$ where $\lambda_i = \eta(x_i, x_i^\circ)$, for each $1 \leq i \leq n$. Let $p \in X$ be fixed. Define $\alpha : \zeta_{X \times X^\circ} \rightarrow X$ (resp. $\beta : \zeta_{X \times X^\circ} \rightarrow X^\circ$ and $\theta_p : \zeta_{X \times X^\circ} \rightarrow \mathbb{R}$) by

$$\alpha(\eta) = \bigoplus_{i=1}^n \lambda_i x_i, \quad (\text{resp. } \beta(\eta) = \sum_{i=1}^n \lambda_i x_i^\circ \text{ and } \theta_p(\eta) = \sum_{i=1}^n \lambda_i \langle x_i^\circ, \overrightarrow{px_i} \rangle).$$

Proposition 3.3. Let X be an Hadamard space, $M \subseteq X \times X^\circ$ and $p \in X$. Set

$$\Theta_{p,M} := \left\{ \eta \in \zeta_M : \theta_p(\eta) \geq \langle \beta(\eta), \overrightarrow{p\alpha(\eta)} \rangle \right\}. \tag{7}$$

Then $\Theta_{p,M} = \Theta_{q,M}$ for any $q \in X$.

Proof. It is enough to show that $\Theta_{p,M} \subseteq \Theta_{q,M}$. Let $\eta \in \Theta_{p,M}$ be such that $\text{supp } \eta = \{\lambda_1, \dots, \lambda_n\}$ where $\lambda_i = \eta(x_i, x_i^\circ)$, for each $1 \leq i \leq n$. Then

$$\begin{aligned} \theta_q(\eta) &= \sum_{i=1}^n \lambda_i \langle x_i^\circ, \overrightarrow{qx_i} \rangle = \sum_{i=1}^n \lambda_i \langle x_i^\circ, \overrightarrow{qp} \rangle + \sum_{i=1}^n \lambda_i \langle x_i^\circ, \overrightarrow{px_i} \rangle \\ &= \langle \sum_{i=1}^n \lambda_i x_i^\circ, \overrightarrow{qp} \rangle + \theta_p(\eta) = \langle \beta(\eta), \overrightarrow{qp} \rangle + \theta_p(\eta) \\ &\geq \langle \beta(\eta), \overrightarrow{qp} \rangle + \langle \beta(\eta), \overrightarrow{p\alpha(\eta)} \rangle \\ &= \langle \beta(\eta), \overrightarrow{q\alpha(\eta)} \rangle. \end{aligned}$$

Therefore, $\eta \in \Theta_{q,M}$, i.e., $\Theta_{p,M} \subseteq \Theta_{q,M}$. \square

According to Proposition 3.3, for each $M \subseteq X \times X^\circ$, the set $\Theta_{p,M}$ is independent of the choice of the element $p \in X$ and hence we denote the set $\Theta_{p,M}$ by Θ_M .

Theorem 3.4. *Let X be an Hadamard space and $M \subseteq X \times X^\circ$ satisfies the \mathcal{W} -property. Then M is a monotone set if and only if $\Theta_M = \varsigma_M$.*

Proof. Let M be a monotone set. In view of (7), it is enough to show that $\varsigma_M \subseteq \Theta_M$. Let $\eta \in \varsigma_M$ be such that $\text{supp}\eta = \{\lambda_1, \dots, \lambda_n\}$ where $\lambda_i = \eta(x_i, x_i^\circ)$, for each $1 \leq i \leq n$. By using Proposition 2.2, we obtain:

$$\begin{aligned} \theta_p(\eta) - \langle \beta(\eta), \overrightarrow{p\alpha(\eta)} \rangle &= \sum_{i=1}^n \lambda_i \langle x_i^\circ, \overrightarrow{px_i} \rangle - \left\langle \sum_{j=1}^n \lambda_j x_j^\circ, \overrightarrow{p\left(\bigoplus_{i=1}^n \lambda_i x_i\right)} \right\rangle \\ &= \sum_{i=1}^n \lambda_i \langle x_i^\circ, \overrightarrow{px_i} \rangle - \sum_{j=1}^n \lambda_j \langle x_j^\circ, \overrightarrow{p\left(\bigoplus_{i=1}^n \lambda_i x_i\right)} \rangle \\ &\geq \sum_{i=1}^n \lambda_i \langle x_i^\circ, \overrightarrow{px_i} \rangle - \sum_{j=1}^n \sum_{i=1}^n \lambda_i \lambda_j \langle x_j^\circ, \overrightarrow{px_i} \rangle \\ &= \sum_{j=1}^n \sum_{i=1}^n \lambda_i \lambda_j \langle x_i^\circ, \overrightarrow{px_i} \rangle - \sum_{j=1}^n \sum_{i=1}^n \lambda_i \lambda_j \langle x_j^\circ, \overrightarrow{px_i} \rangle \\ &= \sum_{j=1}^n \sum_{i=1}^n \lambda_i \lambda_j \langle x_i^\circ - x_j^\circ, \overrightarrow{px_i} \rangle \\ &= \sum_{j=1}^n \sum_{i=1}^n \lambda_i \lambda_j \langle x_i^\circ - x_j^\circ, \overrightarrow{px_j} \rangle \\ &= \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \lambda_i \lambda_j \langle x_i^\circ - x_j^\circ, \overrightarrow{px_i - px_j} \rangle \\ &= \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \lambda_i \lambda_j \langle x_i^\circ - x_j^\circ, \overrightarrow{x_j x_i} \rangle \geq 0. \end{aligned}$$

Then $\varsigma_M \subseteq \Theta_M$ and hence $\varsigma_M = \Theta_M$. For the converse, let $(x, x^\circ), (y, y^\circ) \in M$ and set $\eta := \frac{1}{2}\delta_{(x,x^\circ)} + \frac{1}{2}\delta_{(y,y^\circ)} \in \varsigma_M$. By using \mathcal{W} -property, we get:

$$\begin{aligned} \frac{1}{4} \langle x^\circ - y^\circ, \overrightarrow{yx} \rangle &= \frac{1}{4} \langle x^\circ - y^\circ, \overrightarrow{px} - \overrightarrow{py} \rangle \\ &= \frac{1}{4} (\langle x^\circ - y^\circ, \overrightarrow{px} \rangle - \langle x^\circ - y^\circ, \overrightarrow{py} \rangle) \\ &= \frac{1}{4} \langle x^\circ, \overrightarrow{px} \rangle + \frac{1}{4} \langle y^\circ, \overrightarrow{py} \rangle - \frac{1}{4} \langle y^\circ, \overrightarrow{px} \rangle - \frac{1}{4} \langle x^\circ, \overrightarrow{py} \rangle \\ &= \frac{1}{2} \langle x^\circ, \overrightarrow{px} \rangle + \frac{1}{2} \langle y^\circ, \overrightarrow{py} \rangle - \frac{1}{4} \langle x^\circ, \overrightarrow{px} \rangle - \frac{1}{4} \langle x^\circ, \overrightarrow{py} \rangle - \frac{1}{4} \langle y^\circ, \overrightarrow{px} \rangle - \frac{1}{4} \langle y^\circ, \overrightarrow{py} \rangle \\ &\geq \frac{1}{2} \langle x^\circ, \overrightarrow{px} \rangle + \frac{1}{2} \langle y^\circ, \overrightarrow{py} \rangle - \left\langle \frac{1}{2}x^\circ + \frac{1}{2}y^\circ, \overrightarrow{p\left(\frac{1}{2}x \oplus \frac{1}{2}y\right)} \right\rangle \\ &= \frac{1}{2} \langle x^\circ, \overrightarrow{px} \rangle + \frac{1}{2} \langle y^\circ, \overrightarrow{py} \rangle - \frac{1}{2} \left\langle x^\circ, \overrightarrow{p\left(\frac{1}{2}x \oplus \frac{1}{2}y\right)} \right\rangle - \frac{1}{2} \left\langle y^\circ, \overrightarrow{p\left(\frac{1}{2}x \oplus \frac{1}{2}y\right)} \right\rangle \\ &= \theta_p(\eta) - \langle \beta(\eta), \overrightarrow{p\alpha(\eta)} \rangle \geq 0. \end{aligned}$$

Therefore, M is monotone. \square

Corollary 3.5. *Let X be a flat Hadamard space and $M \subseteq X \times X^\circ$. Then M is a monotone set if and only if $\Theta_M = \subset M$.*

Proof. Since X is flat, Proposition 2.5 implies that $M \subseteq X \times X^\circ$ satisfies the \mathcal{W} -property. Then the conclusion follows immediately from Theorem 3.4. \square

A fundamental result concerning monotone operators is the extension theorem of Debrunner-Flor (for a proof see [6, Theorem 4.3.1] or [15, Proposition 2.17]). In the sequel, we prove a type of this result for monotone relations from an Hadamard space to its linear dual space. First, we recall some notions and results.

Definition 3.6. [2, Definition 2.4] Let $\{x_n\}$ be a sequence in an Hadamard space X . The sequence $\{x_n\}$ is said to be *weakly convergent* to $x \in X$, denoted by $x_n \xrightarrow{w} x$, if $\lim_{n \rightarrow \infty} \langle \overrightarrow{xx_n}, \overrightarrow{xy} \rangle = 0$, for all $y \in X$.

One can easily see that convergence in the metric implies weak convergence.

Lemma 3.7. [14, Proposition 3.6] *Let $\{x_n\}$ be a bounded sequence in an Hadamard space (X, d) with linear dual space X° and let $\{x_n^\circ\}$ be a sequence in X° . If $\{x_n\}$ is weakly convergent to x and $x_n^\circ \xrightarrow{\|\cdot\|_0} x^\circ$, then $\langle x_n^\circ, \overrightarrow{x_n z} \rangle \rightarrow \langle x^\circ, \overrightarrow{xz} \rangle$, for all $z \in X$.*

Theorem 3.8. *Let X be an Hadamard space and $M \subseteq X \times X^\circ$ be a monotone relation satisfies the \mathcal{W} -property. Let $C \subseteq X^\circ$ be a compact and convex set, and $\varphi : C \rightarrow X$ be a continuous function. Then there exists $z^\circ \in C$ such that $\{(\varphi(z^\circ), z^\circ)\} \cup M$ is monotone.*

Proof. Let $x \in X, u^\circ, v^\circ \in X^\circ$ be arbitrary and fixed element. Consider the function $\tau : C \rightarrow \mathbb{R}$ defined by

$$\tau(x^\circ) = \langle x^\circ - v^\circ, \overrightarrow{x\varphi(u^\circ)} \rangle, \quad x^\circ \in C.$$

Let $\{x_n^\circ\} \subseteq C$ be such that $x_n^\circ \xrightarrow{\|\cdot\|_0} x^\circ$, for some $x^\circ \in C$. By Lemma 3.7,

$$\langle x_n^\circ - v^\circ, \overrightarrow{x\varphi(u^\circ)} \rangle \rightarrow \langle x^\circ - v^\circ, \overrightarrow{x\varphi(u^\circ)} \rangle.$$

Thus $\tau(x_n^\circ) \rightarrow \tau(x^\circ)$. Hence τ is continuous. For every $(y, y^\circ) \in M$, set

$$U(y, y^\circ) := \{u^\circ \in C : \langle u^\circ - y^\circ, \overrightarrow{y\varphi(u^\circ)} \rangle < 0\}.$$

Continuity of τ implies that $U(y, y^\circ)$ is an open subset of C . Suppose that the conclusion fails. Then for each $u^\circ \in C$ there exists $(y, y^\circ) \in M$ such that $u^\circ \in U(y, y^\circ)$. This means that the family of open sets $\{U(y, y^\circ)\}_{(y, y^\circ) \in M}$ is an open cover of C . Using the compactness of C , we obtain that $C = \bigcup_{i=1}^n U(y_i, y_i^\circ)$. In addition, [15, Page 756] implies that there exists a partition of unity associated with this finite subcover. Hence, there are continuous functions $\psi_i : X^\circ \rightarrow \mathbb{R}$ ($1 \leq i \leq n$) satisfying

- (i) $\sum_{i=1}^n \psi_i(x^\circ) = 1$, for all $x^\circ \in C$.
- (ii) $\psi_i(x^\circ) \geq 0$, for all $x^\circ \in C$ and all $i \in \{1, \dots, n\}$.
- (iii) $\{x^\circ \in C : \psi_i(x^\circ) > 0\} \subseteq U_i := U(y_i, y_i^\circ)$ for all $i \in \{1, \dots, n\}$.

Set $K := \text{co}(\{y_1^\circ, \dots, y_n^\circ\}) \subseteq C$ and define

$$\begin{aligned} \iota : K &\rightarrow K \\ u^\circ &\mapsto \sum_{i=1}^n \psi_i(u^\circ) y_i^\circ. \end{aligned}$$

Let $\{u_m^\circ\} \subseteq K$ be such that $u_m^\circ \rightarrow u^\circ$,

$$\|\iota(u_m^\circ) - \iota(u^\circ)\|_0 = \left\| \sum_{i=1}^n \psi_i(u_m^\circ) y_i^\circ - \sum_{i=1}^n \psi_i(u^\circ) y_i^\circ \right\|_0.$$

$$\begin{aligned}
 &= \left\| \sum_{i=1}^n (\psi_i(u_m^\circ) - \psi_i(u^\circ))y_i^\circ \right\|_0 \\
 &\leq \sum_{i=1}^n \|(\psi_i(u_m^\circ) - \psi_i(u^\circ))y_i^\circ\|_0 \\
 &\leq \sum_{i=1}^n |\psi_i(u_m^\circ) - \psi_i(u^\circ)| \|y_i^\circ\|_0.
 \end{aligned}$$

By continuity of ψ_i ($1 \leq i \leq n$), letting $m \rightarrow +\infty$, then $\psi_i(u_m^\circ) \rightarrow \psi_i(u^\circ)$ and this implies that $u(u_m^\circ) \rightarrow u(u^\circ)$ and so ι is continuous. One can identify K with a finite-dimensional convex and compact set. By using Brouwer fixed point theorem [15, Proposition 2.6], there exists $w^\circ \in K$ such that $\iota(w^\circ) = w^\circ$. Moreover, by using Proposition 2.2 we get:

$$\begin{aligned}
 0 &= \left\langle \iota(w^\circ) - w^\circ, \overrightarrow{\varphi(w^\circ)(\oplus_j \psi_j(w^\circ)y_j)} \right\rangle \\
 &= \left\langle \sum_i \psi_i(w^\circ)(y_i^\circ - w^\circ), \overrightarrow{\varphi(w^\circ)(\oplus_j \psi_j(w^\circ)y_j)} \right\rangle \\
 &= \left\langle \sum_i \psi_i(w^\circ)(y_i^\circ - w^\circ), \overrightarrow{p(\oplus_j \psi_j(w^\circ)y_j)} \right\rangle - \left\langle \sum_i \psi_i(w^\circ)(y_i^\circ - w^\circ), \overrightarrow{p\varphi(w^\circ)} \right\rangle \quad (p \in X) \\
 &\leq \sum_j \psi_j(w^\circ) \left\langle \sum_i \psi_i(w^\circ)(y_i^\circ - w^\circ), \overrightarrow{p y_j^\circ} \right\rangle - \left\langle \sum_i \psi_i(w^\circ)(y_i^\circ - w^\circ), \overrightarrow{p\varphi(w^\circ)} \right\rangle \\
 &= \sum_j \psi_j(w^\circ) \left\langle \sum_i \psi_i(w^\circ)(y_i^\circ - w^\circ), \overrightarrow{p y_j^\circ} \right\rangle - \sum_j \psi_j(w^\circ) \left\langle \sum_i \psi_i(w^\circ)(y_i^\circ - w^\circ), \overrightarrow{p\varphi(w^\circ)} \right\rangle \\
 &= \sum_j \psi_j(w^\circ) \left\langle \sum_i \psi_i(w^\circ)(y_i^\circ - w^\circ), \overrightarrow{p y_j^\circ - p\varphi(w^\circ)} \right\rangle \\
 &= \sum_j \psi_j(w^\circ) \left\langle \sum_i \psi_i(w^\circ)(y_i^\circ - w^\circ), \overrightarrow{\varphi(w^\circ)y_j^\circ} \right\rangle \\
 &= \sum_j \psi_j(w^\circ) \sum_i \psi_i(w^\circ) \left\langle y_i^\circ - w^\circ, \overrightarrow{\varphi(w^\circ)y_j^\circ} \right\rangle \\
 &= \sum_j \sum_i \psi_j(w^\circ)\psi_i(w^\circ) \left\langle y_i^\circ - w^\circ, \overrightarrow{\varphi(w^\circ)y_j^\circ} \right\rangle \\
 &= \sum_{i,j} \psi_i(w^\circ)\psi_j(w^\circ) \left\langle y_i^\circ - w^\circ, \overrightarrow{\varphi(w^\circ)y_j^\circ} \right\rangle. \tag{8}
 \end{aligned}$$

Set $a_{ij} = \langle y_i^\circ - w^\circ, \overrightarrow{\varphi(w^\circ)y_j^\circ} \rangle$. It follows from monotonicity of M that

$$\begin{aligned}
 a_{ii} + a_{jj} - a_{ij} - a_{ji} &= \langle y_i^\circ - w^\circ, \overrightarrow{\varphi(w^\circ)y_i^\circ} \rangle + \langle y_j^\circ - w^\circ, \overrightarrow{\varphi(w^\circ)y_j^\circ} \rangle \\
 &\quad - \langle y_i^\circ - w^\circ, \overrightarrow{\varphi(w^\circ)y_j^\circ} \rangle - \langle y_j^\circ - w^\circ, \overrightarrow{\varphi(w^\circ)y_i^\circ} \rangle \\
 &= \langle y_i^\circ - y_j^\circ, \overrightarrow{\varphi(w^\circ)y_i^\circ - \varphi(w^\circ)y_j^\circ} \rangle \\
 &= \langle y_i^\circ - y_j^\circ, \overrightarrow{y_j^\circ y_i^\circ} \rangle \geq 0;
 \end{aligned}$$

i.e.,

$$a_{ii} + a_{jj} \geq a_{ij} + a_{ji}. \tag{9}$$

Applying (8) and (9), we obtain:

$$\begin{aligned} 0 &\leq \sum_{i,j}^n \psi_i(w^\circ)\psi_j(w^\circ)a_{ij} \\ &= \sum_{i<j}^n \psi_i(w^\circ)\psi_j(w^\circ)a_{ij} + \sum_{i=1}^n \psi_i(w^\circ)^2a_{ii} + \sum_{i>j}^n \psi_i(w^\circ)\psi_j(w^\circ)a_{ij} \\ &= \sum_{i=1}^n \psi_i(w^\circ)^2a_{ii} + \sum_{i<j}^n \psi_i(w^\circ)\psi_j(w^\circ)(a_{ij} + a_{ji}) \end{aligned} \quad (10)$$

$$\leq \sum_{i=1}^n \psi_i(w^\circ)^2a_{ii} + \sum_{i<j}^n \psi_i(w^\circ)\psi_j(w^\circ)(a_{ii} + a_{jj}). \quad (11)$$

Set $I(w^\circ) := \{i \in \{1, \dots, n\} : w^\circ \in U_i\}$. Applying property (iii) of the partition of unity in (11) we get:

$$0 \leq \sum_{i \in I(w^\circ)} \psi_i(w^\circ)^2a_{ii} + \sum_{\substack{i<j \\ i,j \in I(w^\circ)}} \psi_i(w^\circ)\psi_j(w^\circ)(a_{ii} + a_{jj}). \quad (12)$$

By using property (iii) of the partition of unity and the definition of U_i , one deduce that all terms in the right-hand side of (12) are nonpositive. So all of $\psi_i(w^\circ)$'s must be vanish, which contradicts with (i). \square

Corollary 3.9. *Let X be a flat Hadamard space and $M \subseteq X \times X^\circ$ be a monotone set. Let $C \subseteq X^\circ$ be a compact and convex set, and $\varphi : C \rightarrow X$ be a continuous function. Then there exists $z^\circ \in C$ such that $\{(\varphi(z^\circ), z^\circ)\} \cup M$ is monotone.*

Proof. Since X is flat, it follows from Proposition 2.5 that $M \subseteq X \times X^\circ$ has \mathcal{W} -property. The inclusion follows from Theorem 3.8. \square

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